

CCU TM TOPE check
 File: H_FCP_CCU_TCHK.xls
 Author: E. Picallo



Procedure Summary

Objectives

This procedure describes the CCUs TM TOPE checks

Summary of Constraints

Specific procedure to check the CCU status during monitoring mode i.e. not during DLCM or valves actuation.

Valves 103, 106, 501 and 503 will be opened at launch (by Ariane dry-loops commands) and they will always remain opened.

On Ground the Valves 504 and 505 status is OPEN and will remain OPEN at launch (no dry loops commands) but they will be closed TBD days after in-flight.

The CCUs valves actuation status is checked in step 5 and 15 based on HK telemetry parameters, assuming they are not actuated. The actual status of the valves is checked in steps 24-27 (dependant on s/c mode).

Spacecraft Configuration

Start of Procedure

CCU A and CCU B switch ON, declared ON and valid on S/C Bus and configured ON in the UIU table
 CCU A and CCU B in monitoring mode

End of Procedure

CCU A and CCU B switch ON, declared ON and valid on S/C Bus and configured ON in the UIU table
 CCU A and CCU B in monitoring mode

Reference File(s)

Input Command Sequences

Output Command Sequences

Referenced Displays

ANDs	GRDs	SLDs
ZAZ9L999		(None)
ZAZ9K999		

Configuration Control Information

DATE	FOP ISSUE	VERSION	MODIFICATION DESCRIPTION	AUTHOR	SPR REF
28/10/08		1	Created	E. Picallo	

Status : Version 6 - Unchanged
 Last Checkin: 09/04/09

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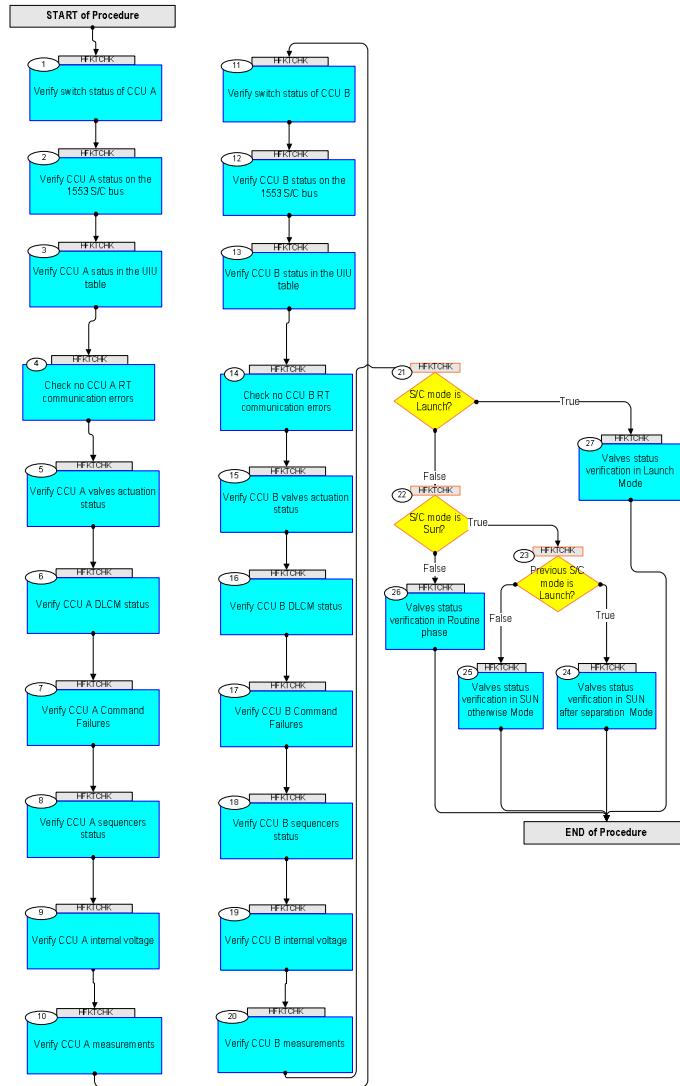


31/10/08		1.01	Validation : MonSeq_Sts TM check corrected	E. Picallo	
02/02/09	2	2	minor expected values correction after HSVT2	E. Picallo	
18/02/09	2.1	3	Include RT error flags check.	E. Picallo	
25/03/09	2.2	4	Valves polarity check removed from SUN after separation	E. Picallo	
30/03/09		5	Launch Mode config updated according to H-P-2-ASP-TS-1780 issue 2	E. Picallo	
09/04/09	2.3	6	Summary constrain updated: <input type="checkbox"/> - Valves 504 and 505 status is OPEN and will remain OPEN at launch (no dry loops commands) <input type="checkbox"/> - clarification CCUs valves check on Step 5 and 15 checks are actuation status related	E. Picallo	

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Procedure Flowchart Overview



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Step No.	Time	Activity/Remarks	TC/TLM	Display/ Branch
Beginning of Procedure				
TC Seq. Name : HFKTCHK (CCU TM TOPE check) CCU subsystem TM TOPE checkout TimeTag Type: Sub Schedule ID: <input type="checkbox"/>				
1		Verify switch status of CCU A		Next Step: 2
		Verify CCU A (LCL37) line status Telemetry Ccu_A_L37_S WM12A565	= ON	AND=ZAZ9L999
		Verify Telemetry Ccu_A_L37_I WM106565	>= 0.10 A <= 0.20 A	AND=ZAZ9L999
2		Verify CCU A status on the 1553 S/C bus		Next Step: 3
		Verify Telemetry CCUA_OnOff DED3G161	= ON	AND=ZAZ9L999
		Verify Telemetry CCUA_DeadAlive DED3H161	= Alive	AND=ZAZ9L999
		Verify Telemetry CCUA_WellsickTC DED3Z161	= Well	AND=ZAZ9L999
		Verify Telemetry CCUA_WellsickTM DED3J161	= Well	AND=ZAZ9L999
		Verify Telemetry CCUA_ValidInval DED3K161	= Valid	AND=ZAZ9L999
		Verify Telemetry CCUA_VitalNonV DED62161	= NonVital	AND=ZAZ9L999
		Verify Telemetry CCUA_NomRed DED63161	= NOMINAL	AND=ZAZ9L999
3		Verify CCU A status in the UIU table		Next Step: 4
		Verify Telemetry CcuAFuncSts DEL97171	= On	AND=ZAZ9L999
4		Check no CCU A RT communication errors		Next Step: 5

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Step No.	Time	Activity/Remarks	TC/TLM	Display/ Branch
		<p>The CCU RT reports the following error flags in the MIL STD-1553B Status Words:</p> <ul style="list-style-type: none"> - RT message error bit: set by the RT upon detection of an error in the message or an illegal message identification. - RT busy bit: indicates that the RT or subsystem is unable to move data to or from the subsystem in compliance with thte BC command. - RT subsystem flag bit: indicates a subsystem fault condition, and alert the BC to potentially invalid data. - RT terminal flag bit: indicates a RT fault condition. <p>These RT error bits are not supported by DLL FDIR mechanisms. Thus, if a permanent error is reported on one of these bits, this could indicate a failure in the RT or the CCU, and a recovery action should be taken by calling the contingency procedure H_CRP_CCU_CCUR (CCU Anomaly).</p>		
		<p>The value of the error bits for the CCU A is kept in the following DIDs (included in the CCU A monitoring packets):</p> <p>DID_CCU_A_SA01_RSP_STS_WORD DID_CCU_A_SA08_RSP_STS_WORD DID_CCU_A_SA11_RSP_STS_WORD DID_CCU_A_SA12_RSP_STS_WORD DID_CCU_A_SA13_RSP_STS_WORD DID_CCU_A_SA16_RSP_STS_WORD DID_CCU_A_SA30_RSP_STS_WORD</p> <p>NOTE: in case of permanent failures (i.e. if DID_CCU_A_SA11_RSP_STS_WORD is indicating a subsystem error flag condition), the same error will be reported in all the other DIDs for response status words. Then, it is enough to check only one of these Status Words. The parameters below correspond to DID_CCU_A_SA11_RSP_STS_WORD.</p>		
		<p>Verify RT message error bit Telemetry</p> <p style="text-align: center;">MsgErr DEYC2161</p>	= 0 <dec>	(None)
		<p>Verify RT message error bit Telemetry</p> <p style="text-align: center;">Busy DEYC6161</p>	= 0 <dec>	(None)
		<p>Verify RT subsystem flag bit Telemetry</p> <p style="text-align: center;">SubSys DEYC7161</p>	= 0 <dec>	(None)
		<p>Verify RT terminal flag bit Telemetry</p> <p style="text-align: center;">Term DEYC9161</p>	= 0 <dec>	(None)
5		<p>Verify CCU A valves actuation status</p>		Next Step: 6

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Step No.	Time	Activity/Remarks	TC/TLM	Display/ Branch
		Verify State of Valve 1 arming relay Telemetry Arm_V103 KM110300	= DISARMED	AND=ZAZ9K999
		Verify Valve 1 actuated i.e. active output detected (direction of actuation is specified V1 polarity) Telemetry Actuated_V103 KM112300	= NOT DETECTED	AND=ZAZ9K999
		Verify Valve 1 open or close command rejected Telemetry OpCl_TCREJ_V103 KM113300	= NOT DETECTED	AND=ZAZ9K999
		Verify Valve 1 arm command rejected Telemetry Arm_TCREJ_V103 KM114300	= NOT DETECTED	AND=ZAZ9K999
		Verify Valve 1 arm deactivated by timer Telemetry dis_TCREJ_V103 KM115300	= NOT DETECTED	AND=ZAZ9K999
		Verify State of Valve 2 arming relay Telemetry Arm_V501 KM120300	= DISARMED	AND=ZAZ9K999
		Verify Valve 2 actuated Telemetry Actuated_V501 KM122300	= NOT DETECTED	AND=ZAZ9K999
		Verify Valve 2 open or close command rejected Telemetry OpCl_TCREJ_V501 KM123300	= NOT DETECTED	AND=ZAZ9K999
		Verify Valve 2 Arm command rejected Telemetry Arm_TCREJ_V501 KM124300	= NOT DETECTED	AND=ZAZ9K999
		Verify Valve 2 Arm deactivated by timer Telemetry dis_TCREJ_V501 KM125300	= NOT DETECTED	AND=ZAZ9K999
		Verify State of Valve 3 arming relay Telemetry Arm_V504 KM130300	= DISARMED	AND=ZAZ9K999
		Verify Valve 3 actuated Telemetry Actuated_V504 KM132300	= NOT DETECTED	AND=ZAZ9K999
		Verify Valve 3 open or close command rejected Telemetry OpCl_TCREJ_V504 KM133300	= NOT DETECTED	AND=ZAZ9K999
		Verify Valve 3 Arm command rejected Telemetry Arm_TCREJ_V504 KM134300	= NOT DETECTED	AND=ZAZ9K999
		Verify Valve 3 Arm deactivated by timer Telemetry dis_TCREJ_V504 KM135300	= NOT DETECTED	AND=ZAZ9K999
6		Verify CCU A DLCM status		Next Step: 7
		Verify State of DLCM heater arming relay DLCMHArm_st A KM037300	= OFF	AND=ZAZ9L999
		Verify State of DLCM heater DLCMheat_stat A KM034300	= OFF	AND=ZAZ9L999
		Verify Synchronization to frame failed in DLCM Telemetry DLCMSync_fail A KM036300	= NOT DETECTED	AND=ZAZ9L999
		Verify Inconsistence in time counters detected Telemetry TimeCntr_Inc A KM035300	= NOT DETECTED	AND=ZAZ9L999

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Step No.	Time	Activity/Remarks	TC/TLM	Display/ Branch
		Verify DLCM On command rejected Telemetry DLCMcmdON_rj A KM033300	= NOT DETECTED	AND=ZAZ9L999
		Verify DLCM Arm command rejected Telemetry DLCMcmdARM_rj A KM032300	= NOT DETECTED	AND=ZAZ9L999
		Verify DLCM heater arm deactivated by timer Telemetry DLCMhtARMdist A KM031300	= NOT DETECTED	AND=ZAZ9L999
		Verify DLCM heater arm deactivated during heating Telemetry DLCMhtARMdish A KM030300	= NOT DETECTED	AND=ZAZ9L999
7		Verify CCU A Command Failures		Next Step: 8
		Verify RTU reported format error in received or transmit message Telemetry RTU_fmt_err A KM027300	= NOT DETECTED	AND=ZAZ9L999
		Verify Undefined data word content detected Telemetry SA1R_failure A KM026300	= NOT DETECTED	AND=ZAZ9L999
		Verify Undefined word count or data word content detected (11 R), or Data wrap-around, Configure RTU or Read RTU configuration command rejected Telemetry SA11_30R_fail A KM025300	= NOT DETECTED	AND=ZAZ9L999
		Verify Execution of Monitoring sequence, Data wrap-around, Read RTU configuration or Configure RTU command aborted Telemetry Exe_Abort A KM024300	= NOT DETECTED	AND=ZAZ9L999
8		Verify CCU A sequencers status		Next Step: 9
		Verify State of DLCM sequencer (execution phase) DLCM_stat A KM022300	= Idle	AND=ZAZ9L999
		Verify Telemetry MonSeq_stat MA KM621300	= ACTIVE	(None)
		Verify State of Monitoring sequencer Telemetry reported in HK is replaced by the TM parameter reported in monitoring packet. The reason is HK TM parameter MonSeq_stat A KM021300 is toggling between ACTIVE and NO ACIVE		
		Verify Pre- and Post-Calibration (used in DLCM) Pre_post_cal A KM028300	= Pre-calib	AND=ZAZ9L999
		Verify State of configuration arm Telemetry ConfArm_stat A KM038300	= OFF	AND=ZAZ9L999
9		Verify CCU A internal voltage		Next Step: 10
		Verify CCU internal -15V status CCU_Vol_stat A KM048300	= OK	AND=ZAZ9L999

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Step No.	Time	Activity/Remarks	TC/TLM	Display/ Branch
10		Verify CCU A measurements		Next Step: 11
		Verify Current state of Meas. Average control bit MeasAavg_st A KM046300	= ENABLED	AND=ZAZ9L999
		Verify Underflow error during measurement detected MeasUnflow_st A KM045300	= NOT DETECTED	AND=ZAZ9L999
		Verify AD-converter latchup during measurement detected ADC_latchup A KM044300	= NOT DETECTED	AND=ZAZ9L999
		Verify Number of AD-converter latchups since CCU power up ADC_latchuCnt A KM040300	= 0 <dec>	AND=ZAZ9L999
11		Verify switch status of CCU B		Next Step: 12
		Verify CCU B (LCL38) line status Telemetry Ccu_B_L38_S WMA2A565	= ON	AND=ZAZ9L999
		Verify Telemetry Ccu_B_L38_I WMA06565	>= 0.10 A <= 0.20 A	AND=ZAZ9L999
12		Verify CCU B status on the 1553 S/C bus		Next Step: 13
		Verify Telemetry CCUB_OnOff DED41161	= ON	AND=ZAZ9L999
		Verify Telemetry CCUB_DeadAlive DED42161	= Alive	AND=ZAZ9L999
		Verify Telemetry CCUB_WellsickTC DED43161	= Well	AND=ZAZ9L999
		Verify Telemetry CCUB_WellsickTM DED44161	= Well	AND=ZAZ9L999
		Verify Telemetry CCUB_ValidInval DED45161	= Valid	AND=ZAZ9L999
		Verify Telemetry CCUB_VitalNonV DED6G161	= NonVital	AND=ZAZ9L999
		Verify Telemetry CCUB_NomRed DED6H161	= NOMINAL	AND=ZAZ9L999
13		Verify CCU B status in the UIU table		Next Step: 14
		Verify Telemetry CcuBFuncSts DEL96171	= On	AND=ZAZ9L999
14		Check no CCU B RT communication errors		Next Step: 15

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		<p>The CCU RT reports the following error flags in the MIL STD-1553B Status Words:</p> <ul style="list-style-type: none"> - RT message error bit: set by the RT upon detection of an error in the message or an illegal message identification. - RT busy bit: indicates that the RT or subsystem is unable to move data to or from the subsystem in compliance with thte BC command. - RT subsystem flag bit: indicates a subsystem fault condition, and alert the BC to potentially invalid data. - RT terminal flag bit: indicates a RT fault condition. <p>These RT error bits are not supported by DLL FDIR mechanisms. Thus, if a permanent error is reported on one of these bits, this could indicate a failure in the RT or the CCU, and a recovery action should be taken by calling the contingency procedure H_CRP_CCU_CCUR (CCU Anomaly).</p>		
		<p>The value of the error bits for the CCU B is kept in the following DIDs (included in the CCU B monitoring packets):</p> <p>DID_CCU_B_SA01_RSP_STS_WORD DID_CCU_B_SA08_RSP_STS_WORD DID_CCU_B_SA11_RSP_STS_WORD DID_CCU_B_SA12_RSP_STS_WORD DID_CCU_B_SA13_RSP_STS_WORD DID_CCU_B_SA16_RSP_STS_WORD DID_CCU_B_SA30_RSP_STS_WORD</p> <p>NOTE: in case of permanent failures (i.e. if DID_CCU_B_SA11_RSP_STS_WORD is indicating a subsystem error flag condition), the same error will be reported in all the other DIDs for response status words. Then, it is enough to check only one of these Status Words. The parameters below correspond to DID_CCU_B_SA11_RSP_STS_WORD.</p>		
		<p>Verify RT message error bit Telemetry</p> <p style="text-align: center;">MsgErr DEYK2161</p>	= 0 <dec>	(None)
		<p>Verify RT busy bit Telemetry</p> <p style="text-align: center;">Busy DEYK6161</p>	= 0 <dec>	(None)
		<p>Verify RT subsystem flag bit Telemetry</p> <p style="text-align: center;">SubSys DEYK7161</p>	= 0 <dec>	(None)
		<p>Verify RT terminal flag bit Telemetry</p> <p style="text-align: center;">Term DEYK9161</p>	= 0 <dec>	(None)
15		<p>Verify CCU B valves actuation status</p>		Next Step: 16

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Step No.	Time	Activity/Remarks	TC/TLM	Display/ Branch
		Verify State of Valve 1 arming relay Telemetry Arm_V106 KM110301	= DISARMED	AND=ZAZ9K999
		Verify Valve 1 actuated i.e. active output detected (direction of actuation is specified by Valve 1 polarity) Telemetry Actuated_V106 KM112301	= NOT DETECTED	AND=ZAZ9K999
		Verify Valve 1 open or close command rejected Telemetry OpCl_TCREJ_V106 KM113301	= NOT DETECTED	AND=ZAZ9K999
		Verify Valve 1 arm command rejected Telemetry Arm_TCREJ_V106 KM114301	= NOT DETECTED	AND=ZAZ9K999
		Verify Valve 1 arm deactivated by timer Telemetry dis_TCREJ_V106 KM115301	= NOT DETECTED	AND=ZAZ9K999
		Verify State of Valve 2 arming relay Telemetry Arm_V503 KM120301	= DISARMED	AND=ZAZ9K999
		Verify Valve 2 actuated Telemetry Actuated_V503 KM122301	= NOT DETECTED	AND=ZAZ9K999
		Verify Valve 2 open or close command rejected Telemetry OpCl_TCREJ_V503 KM123301	= NOT DETECTED	AND=ZAZ9K999
		Verify Valve 2 Arm command rejected Telemetry Arm_TCREJ_V503 KM124301	= NOT DETECTED	AND=ZAZ9K999
		Verify Valve 2 Arm deactivated by timer Telemetry dis_TCREJ_V503 KM125301	= NOT DETECTED	AND=ZAZ9K999
		Verify State of Valve 3 arming relay Telemetry Arm_V505 KM130301	= DISARMED	AND=ZAZ9K999
		Verify Valve 3 actuated Telemetry Actuated_V505 KM132301	= NOT DETECTED	AND=ZAZ9K999
		Verify Valve 3 open or close command rejected Telemetry OpCl_TCREJ_V505 KM133301	= NOT DETECTED	AND=ZAZ9K999
		Verify Valve 3 Arm command rejected Telemetry Arm_TCREJ_V505 KM134301	= NOT DETECTED	AND=ZAZ9K999
		Verify Valve 3 Arm deactivated by timer Telemetry dis_TCREJ_V505 KM135301	= NOT DETECTED	AND=ZAZ9K999
16		Verify CCU B DLCM status		Next Step: 17
		Verify State of DLCM heater arming relay Telemetry DLCMHArm_st B KM037301	= OFF	AND=ZAZ9L999
		Verify State of DLCM heater Telemetry DLCMheat_stat B KM034301	= OFF	AND=ZAZ9L999
		Verify Synchronization to frame failed in DLCM DLCMsync_fail B KM036301	= NOT DETECTED	AND=ZAZ9L999
		Verify Inconsistence in time counters detected TimeCtrntr_Inc B KM035301	= NOT DETECTED	AND=ZAZ9L999

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Step No.	Time	Activity/Remarks	TC/TLM	Display/ Branch
		Verify DLCM On command rejected Telemetry DLCMcmdON_rj B KM033301	= NOT DETECTED	AND=ZAZ9L999
		Verify DLCM Arm command rejected Telemetry DLCMcmdARM_rj B KM032301	= NOT DETECTED	AND=ZAZ9L999
		Verify DLCM heater arm deactivated by timer Telemetry DLCMhtARMdist B KM031301	= NOT DETECTED	AND=ZAZ9L999
		Verify DLCM heater arm deactivated during heating DLCMhtARMdish B KM030301	= NOT DETECTED	AND=ZAZ9L999
17		Verify CCU B Command Failures		Next Step: 18
		Verify RTU reported format error in received or transmit message Telemetry RTU_fmt_err B KM027301	= NOT DETECTED	AND=ZAZ9L999
		Verify Undefined data word content detected Telemetry SA1R_failure B KM026301	= NOT DETECTED	AND=ZAZ9L999
		Verify Undefined word count or data word content detected (11 R), or Data wrap-around, Configure RTU or Read RTU configuration command rejected Telemetry SA11_30R_fail B KM025301	= NOT DETECTED	AND=ZAZ9L999
		Verify Execution of Monitoring sequence, Data wrap-around, Read RTU configuration or Configure RTU command aborted Telemetry Exe_Abort B KM024301	= NOT DETECTED	AND=ZAZ9L999
18		Verify CCU B sequencers status		Next Step: 19
		Verify State of DLCM sequencer Telemetry DLCM_stat B KM022301	= Idle	AND=ZAZ9L999
		Verify Telemetry MonSeq_stat MB KM621301	= ACTIVE	(None)
		Verify State of Monitoring sequencer Telemetry reported in HK is replaced by the TM parameter reported in monitoring packet. The reason is HK TM parameter MonSeq_stat A KM021301 is toggling between ACTIVE and NO ACTIVE		
		Verify Pre- or Post-Calibration (used in DLCM) Pre_post_cal B KM028301	= Pre-calib	AND=ZAZ9L999
		Verify State of configuration arm Telemetry ConfArm_stat B KM038301	= OFF	AND=ZAZ9L999
19		Verify CCU B internal voltage		Next Step: 20
		Verify CCU internal -15V status Telemetry CCU_Vol_stat B KM048301	= OK	AND=ZAZ9L999

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Step No.	Time	Activity/Remarks	TC/TLM	Display/ Branch
20		Verify CCU B measurements		Next Step: 21
		Verify Current state of Meas. Average control bit MeasAavg_st B KM046301	= ENABLED	AND=ZAZ9L999
		Verify Underflow error during measurement detected MeasUnflow_st B KM045301	= NOT DETECTED	AND=ZAZ9L999
		Verify AD-converter latchup during measurement detected ADC_latchup B KM044301	= NOT DETECTED	AND=ZAZ9L999
		Verify Number of AD-converter latchups since CCU power up ADC_latchuCnt B KM040301	= 0 <dec>	AND=ZAZ9L999
21		<i>S/C mode is Launch?</i>		Next Step: False 22 True 27
		Verify Telemetry CurrentMode DEL34170	= LaunchMode	(None)
22		<i>S/C mode is Sun?</i>		Next Step: True 23 False 26
		Verify Telemetry CurrentMode DEL34170	= SunAcquisition	(None)
23		<i>Previous S/C mode is Launch?</i>		Next Step: True 24 False 25
		Verify Telemetry PrevMode DEL35170	= LaunchMode	(None)
24		<i>Valves status verification in SUN after separation Mode</i>		Next Step: END
24.1		<i>Valves CCU A verification</i>		<input type="checkbox"/>
		Verify VS103 Status monitoring ; VS1 (A) Valv_Stat_VS103 KM269302	= OPEN	AND=ZAZ9K999
		Verify VS501 Status monitoring ; VS2 (A) Valv_Stat_VS501 KM270302	= OPEN	AND=ZAZ9K999
		Verify VS504 Status monitoring ; VS3 (A) Valv_Stat_VS504 KM271302	= OPEN	AND=ZAZ9K999
24.2		<i>Valves CCU B verification</i>		<input type="checkbox"/>

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		Verify VS106 Status monitoring ; VS1 (B) Valv_Stat_VS106 KM269303	= OPEN	AND=ZAZ9K999
		Verify VS503 Status monitoring ; VS2 (B) Valv_Stat_VS503 KM270303	= OPEN	AND=ZAZ9K999
		Verify VS505 Status monitoring ; VS3 (B) Valv_Stat_VS505 KM271303	= OPEN	AND=ZAZ9K999
25		Valves status verification in SUN otherwise Mode Valves Status same as during Routine phase		Next Step: END
25.1		Valves CCU A verification		☐
		Verify VS103 Status monitoring ; VS1 (A) Valv_Stat_VS103 KM269302	= OPEN	AND=ZAZ9K999
		Verify VS501 Status monitoring ; VS2 (A) Valv_Stat_VS501 KM270302	= OPEN	AND=ZAZ9K999
		Verify VS504 Status monitoring ; VS3 (A) Valv_Stat_VS504 KM271302	= CLOSED	AND=ZAZ9K999
		Verify State of Valve 1 polarity relays Telemetry Polarity_V103 KM111300	= Open	AND=ZAZ9K999
		Verify State of Valve 2 polarity relays Telemetry Polarity_V501 KM121300	= Open	AND=ZAZ9K999
		Verify State of Valve 3 polarity relays Telemetry Polarity_V504 KM131300	= Closed	AND=ZAZ9K999
25.2		Valves CCU B verification		☐
		Verify VS106 Status monitoring ; VS1 (B) Valv_Stat_VS106 KM269303	= OPEN	AND=ZAZ9K999
		Verify VS503 Status monitoring ; VS2 (B) Valv_Stat_VS503 KM270303	= OPEN	AND=ZAZ9K999
		Verify VS505 Status monitoring ; VS3 (B) Valv_Stat_VS505 KM271303	= CLOSED	AND=ZAZ9K999
		Verify State of Valve 1 polarity relays Telemetry Polarity_V106 KM111301	= Open	AND=ZAZ9K999
		Verify State of Valve 2 polarity relays Telemetry Polarity_V503 KM121301	= Open	AND=ZAZ9K999
		Verify State of Valve 3 polarity relays Telemetry Polarity_V505 KM131301	= Closed	AND=ZAZ9K999

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Step No.	Time	Activity/Remarks	TC/TLM	Display/ Branch
26		Valves status verification in Routine phase		Next Step: END
26.1		Valves CCU A verification		<input type="checkbox"/>
		Verify VS103 Status monitoring ; VS1 (A) Valv_Stat_VS103 KM269302	= OPEN	AND=ZAZ9K999
		Verify VS501 Status monitoring ; VS2 (A) Valv_Stat_VS501 KM270302	= OPEN	AND=ZAZ9K999
		Verify VS504 Status monitoring ; VS3 (A) Valv_Stat_VS504 KM271302	= CLOSED	AND=ZAZ9K999
		Verify State of Valve 1 polarity relays Telemetry Polarity_V103 KM111300	= Open	AND=ZAZ9K999
		Verify State of Valve 2 polarity relays Telemetry Polarity_V501 KM121300	= Open	AND=ZAZ9K999
		Verify State of Valve 3 polarity relays Telemetry Polarity_V504 KM131300	= Closed	AND=ZAZ9K999
26.2		Valves CCU B verification		<input type="checkbox"/>
		Verify VS106 Status monitoring ; VS1 (B) Valv_Stat_VS106 KM269303	= OPEN	AND=ZAZ9K999
		Verify VS503 Status monitoring ; VS2 (B) Valv_Stat_VS503 KM270303	= OPEN	AND=ZAZ9K999
		Verify VS505 Status monitoring ; VS3 (B) Valv_Stat_VS505 KM271303	= CLOSED	AND=ZAZ9K999
		Verify State of Valve 1 polarity relays Telemetry Polarity_V106 KM111301	= Open	AND=ZAZ9K999
		Verify State of Valve 2 polarity relays Telemetry Polarity_V503 KM121301	= Open	AND=ZAZ9K999
		Verify State of Valve 3 polarity relays Telemetry Polarity_V505 KM131301	= Closed	AND=ZAZ9K999
27		Valves status verification in Launch Mode		Next Step: END

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Step No.	Time	Activity/Remarks	TC/TLM	Display/ Branch
		<p>At launch, the cryostat will be with the following state of commandable valves:</p> <ul style="list-style-type: none"> · CLOSED: V103, V106, V501, V503 · OPEN: V504, V505 <p>After the cryostat flushing is stopped in the BAF, the ventline (between valves V501, V503, V502, V506, V105, V701, V103, V106, V104, V102, V702 and the filling port) will be closed, and its pressure will increase due to the cryostat warm up. Therefore the line shall be vented from time to time.</p>		
		<p>The procedure is the following command V501 shall be made upon monitoring of P501 (acquired by the Cryo COTE) when P501 reaches 1.2 bar V501 is OPENED for 8 sec then is CLOSED again.</p> <p>It is expected that at the time of the first launch attempt, the time elapsed from one opening to another is about 2 hours or more.</p> <p>In order to avoid an operation of V501 during the automatic sequence, V501 will be opened and closed as described above at H0 – 20 min.</p>		
27.1		Valves CCU A verification		<input type="checkbox"/>
		Verify VS103 Status monitoring ; VS1 (A) Valv_Stat_VS103 KM269302	= CLOSED	AND=ZAZ9K999
		Verify VS501 Status monitoring ; VS2 (A) Valv_Stat_VS501 KM270302	= CLOSED	AND=ZAZ9K999
		Verify VS504 Status monitoring ; VS3 (A) Valv_Stat_VS504 KM271302	= OPEN	AND=ZAZ9K999
		Verify State of Valve 1 polarity relays Telemetry Polarity_V103 KM111300	= Closed	AND=ZAZ9K999
		Verify State of Valve 2 polarity relays Telemetry Polarity_V501 KM121300	= Closed	AND=ZAZ9K999
		Verify State of Valve 3 polarity relays Telemetry Polarity_V504 KM131300	= Open	AND=ZAZ9K999
27.2		Valves CCU B verification		<input type="checkbox"/>
		Verify VS106 Status monitoring ; VS1 (B) Valv_Stat_VS106 KM269303	= CLOSED	AND=ZAZ9K999
		Verify VS503 Status monitoring ; VS2 (B) Valv_Stat_VS503 KM270303	= CLOSED	AND=ZAZ9K999
		Verify VS505 Status monitoring ; VS3 (B) Valv_Stat_VS505 KM271303	= OPEN	AND=ZAZ9K999

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Step No.	Time	Activity/Remarks	TC/TLM	Display/ Branch
		Verify State of Valve 1 polarity relays Telemetry Polarity_V106 KM111301	= Closed	AND=ZAZ9K999
		Verify State of Valve 2 polarity relays Telemetry Polarity_V503 KM121301	= Closed	AND=ZAZ9K999
		Verify State of Valve 3 polarity relays Telemetry Polarity_V505 KM131301	= Open	AND=ZAZ9K999
End of Procedure				