

SPIRE	Laboratoire d'Astrophysique de Marseille	Ref: LAM.QUA.SPI.ECR.200102
	ENGINEERING CHANGE REQUEST	Date: 12 July 2001

PROJECT: HERSCHEL SPIRE		Engineering Change Request Number: 2	
SYSTEM: SMEC and BSM Harness			
Title of change: Current and resistance for launch latch(es) harness			
Affected Items/Workpackages:		MCU/SMECm interface MCU/BSMm interface SPIRE harness	
Classification:		Urgent	
Documents affected: SPIRE harness definition : ref SPIRE-RAL-PRJ-000608 issue 0.3			
Description of Change:			
<p>The control of the launch latch solenoid shall be based on a DC pulse mode instead of a on a stall current mode.</p> <p>The new specification for the launch latch(es) drive 1 and drive 2 (SMECm and BSMm) is:</p> <ul style="list-style-type: none"> - current of 400mA during 50 ms - harness resistance 5 Ohm (FSPU to CVV 80k feedthrough)+5 Ohm (CVV to 300K) 			
Related factor:		Electrical interface	
Need/Justification:			
<p>The control of the launch latch solenoid is based on a DC pulse mode and not on a stall current mode.</p> <p>This allows to develop a much greater force to unlock the mecanism during only the needed time.</p> <p>Note that due to the pulse very small duration, the impact on the wire diameter should ne null or minimal.</p> <p>Up to now, we have foreseen to re-design an 'off the shelf' latch solenoid and to re-make the winding with a much higher efficiency (ie a great number of ampere-turns). In this configuration, the command of the latch was a limited stall current of 35 mA with a great number of solenoid coil turns to get the request force of 3N to unstick the plunger from the holding magnet.</p> <p>Indeed, the goal is to stick/unstick the plunger on the magnet on short duration. This way of commanding is more adequate but need a higher current level for a short time.</p>			
Distribution:	SPIRE Project Office		
Attachments:	None		
Originator	Name: D.Ferrand	SIGNATURE: D.Ferrand	DATE: 12 July 01
CHANGE APPROVED	Name:	SIGNATURE:	DATE: