

HS_FCU FLIGHT MODEL

REPORT OF FUNCTIONAL TESTS AT RAL

Reference: SAP-SPIRE-HT-xxx-06

Issue: 1.0

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2 Test Configuration

We use the LTU in its latest software configuration, the fully assembled DCU and FCU, the FPU and the PSU Flight Model (PSU FM).

Before to connect any harness, we place savers on all connectors

Connect all harnesses as described below :

- Between SCU and LTU
- Between DCU and PSU FM
- Between SCU and PSU FM

Place savers on all connectors

Connect all harnesses as described below

FPU simulator

FCU



FCU FLIGHT MODEL TEST CONFIGURATION

3 POWER ON : SCU CONSUMPTION TESTS

3.1 Main side

- Set 28 V ON at LTU level (main position)
- Measure the voltages and currents (primary)

Channel	Source	Primary Voltage (V)	Expected values (V)	Primary current (mA)	Expected values (mA)
28 V Prime		28 V	28 V	400 mA	400 mA

(the FPU simulator is not ON)

3.2 Redundant side

- Set 28 V ON at LTU level (redundant position)
- Measure the voltages and currents (primary)

Channel	Source	Primary Voltage (V)	Expected values (V)	Primary current (mA)	Expected values (mA)
28 V Prime		28 V	28 V	400 mA	400 mA

(the FPU simulator is not ON)

If these measurements are correct, we can perform the functional tests.



HS_FCU FLIGHT MODEL (FM)



Report of functional tests at RAL

SAP-SPIRE- HT-0xxx-06 V1.0

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Consumption TEST	OK	NON OK
Test responsible Henri TRIOU	Comments :	
Technical specialist		
Quality		
	TEST OK	

4 Tests des frames

⇒ FPU simulator switched ON but not used

Main Side

⇒ Batch executed by LTU : *CCHK-IF test.txt*

⇒ 4 TM files generated by LTU (DPU) (Main and Redundant)

⇒ Rename the files with the following extensions :

Renamed TM file	DCUTm(yyyy.mm.dd_hh.mm.ss)_Frame_Main.tm
Renamed TM file	DCUTm(yyyy.mm.dd_hh.mm.ss)_segment_length.tm
Renamed TM file	DCUTm(yyyy.mm.dd_hh.mm.ss)_frequency_Main.tm
Renamed TM file	DCUTm(yyyy.mm.dd_hh.mm.ss)_reset_Main.tm

Redundant side

⇒ Batch executed by LTU : *CCHK-IF test.txt*

⇒ 4 TM files generated by LTU (DPU) (Main and Redundant)

⇒ Rename the files with the following extensions :

Renamed TM file	DCUTm(yyyy.mm.dd_hh.mm.ss)_Frame_Redundant.tm
Renamed TM file	DCUTm(yyyy.mm.dd_hh.mm.ss)_segment_length_Redundant.tm
Renamed TM file	DCUTm(yyyy.mm.dd_hh.mm.ss)_frequency_Main.tm
Renamed TM file	DCUTm(yyyy.mm.dd_hh.mm.ss)_reset_Redundant.tm

Frames :

Check consistency of frames in terms of length, frame ID and number of blocks

Length of segments :

1 sec at 80 Hz => at least 80 frames observed

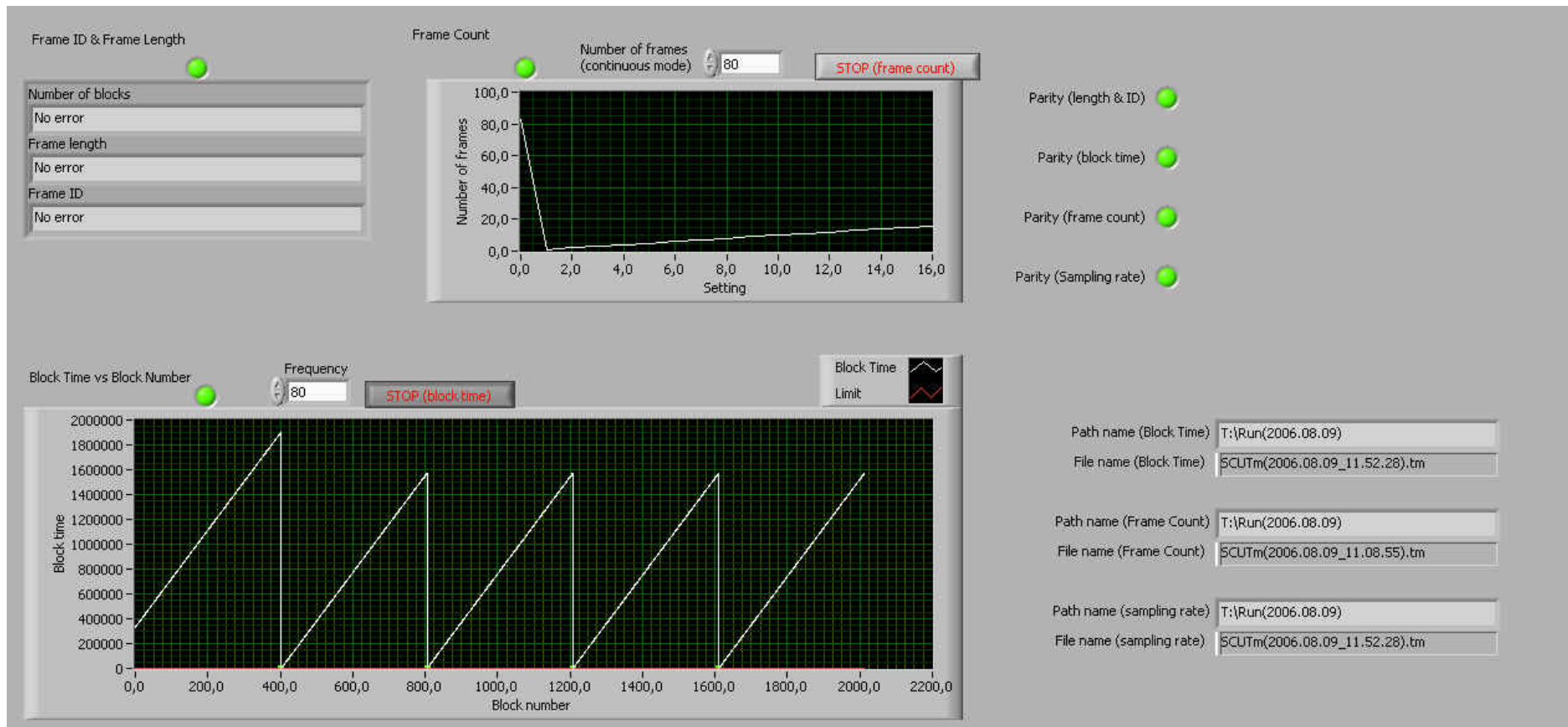
Sampling frequency

⇒ Check consistency with specification : Labview Software

⇒ delta t max = 0,0005 s (Criterion)

Reset of Time Stamp reset

We obtain the following screen copy



SCU Frames, redundant side

Frame ID & Frame Length

Number of blocks

No error

Frame length

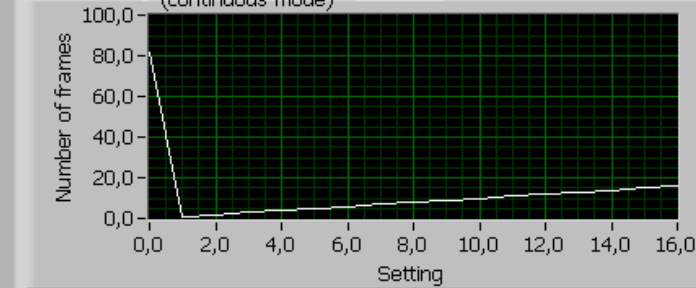
No error

Frame ID

No error

Frame Count Number of frames (continuous mode)

STOP (frame count)



Parity (length & ID)

Parity (block time)

Parity (frame count)

Parity (Sampling rate)

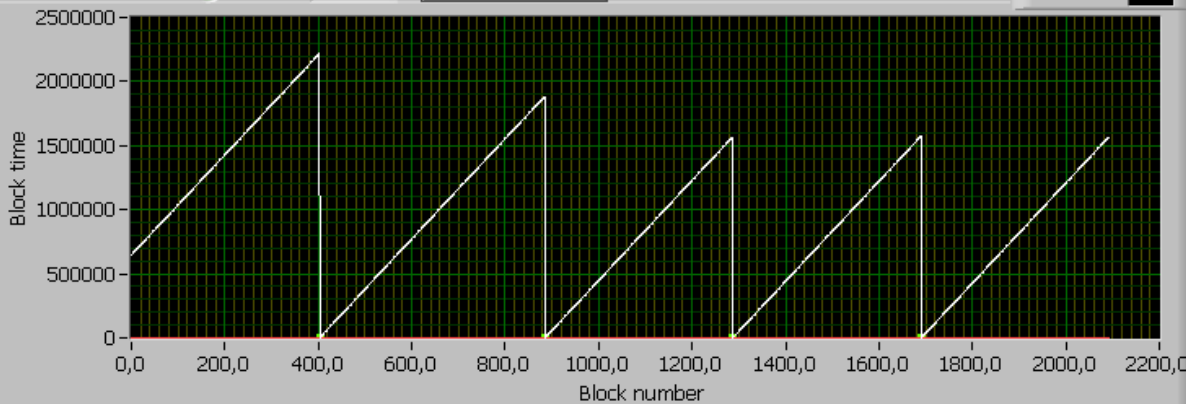
Block Time vs Block Number

Frequency

STOP (block time)

Block Time

Limit



Path name (Block Time) C:\QM2 RAL\Tests SCU du 29 06

File name (Block Time) SCUTm(2005.06.29_13.22.54)_re

Path name (Frame Count) C:\QM2 RAL\Tests SCU du 29 06

File name (Frame Count) SCUTm(2005.06.29_11.48.35)_Se

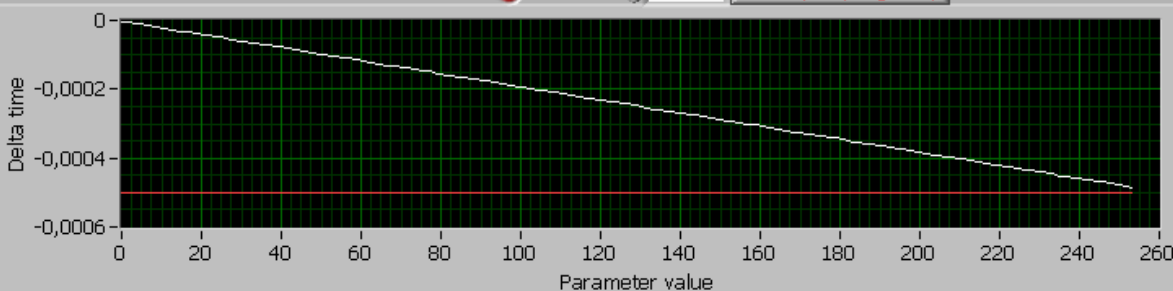
Path name (sampling rate) C:\QM2 RAL\Tests SCU du 29 06

File name (sampling rate) SCUTm(2005.06.29_11.52.29)_fr

Delta time = Sampling time (measured) - Sampling time from ICD

Limit (s)

STOP (sampling rate)



5 SCU Montoring (HK)

We monitored the SCU in main and Redundant sides

Main side

SCU					
Status					
Nom Parametre	Description	Valeur Lue H...	Valeur Nomin...		
ScuStatus	SCU Status	0000			

Temperatures					
Nom Parametre	Description	Valeur Conver...	Unite		
Csu Temp	CCHK_IF Booard temperature	20.00	°C		
Tsu Temp	Temp Board temperature	19.00	°C		
Psu Temp1	PSU temperature 1	23.00	°C		
Psu Temp2	PSU temperature 2	23.00	°C		

Reference/Voltage					
Nom Parametre	Description	Valeur Conver...	Valeur Lue H...	Min	Max
ScuCHTp05	+5V DC powe...	5.25	6980	4.77	5.28
ScuCHTp09	+9V DC powe...	9.09	6885	8.89	9.07
ScuCHTn09	-9V DC power...	-9.08	975C	-9.07	-8.88
ScuCHT25	+2.5V DC inte...	2.52	4096	2.47	2.55
ScuCHTref	Internal voltag...	1.23	3F16	1.21	1.25
ScuCHTgnd	Internal Groun...	0.00	0009	-0.04	0.04
ScuTHTref	Internal voltag...	1.23	3F36	1.21	1.25
ScuTHTgnd	Internal Groun...	-0.00	FFFD	-0.04	0.04

Redundant side

SCU
Status

Nom Parametre	Description	Valeur Lue H...	Valeur Nomin...
ScuStatus	SCU Status	0000	

Temperatures

Nom Parametre	Description	Valeur Conver...	Unite
Csu Temp	CCHK_IF Booard temperature	19.00	°C
Tsu Temp	Temp Board temperature	19.00	°C
Psu Temp1	PSU temperature 1	22.00	°C
Psu Temp2	PSU temperature 2	23.00	°C

Reference/Voltage

Nom Parametre	Description	Valeur Conver...	Valeur Lue H...	Min	Max
ScuCHTp05	+5V DC powe...	5.24	6941	4.77	5.28
ScuCHTp09	+9V DC powe...	9.09	6887	8.89	9.07
ScuCHTn09	-9V DC power...	-9.11	9718	-9.07	-8.88
ScuCHT25	+2.5V DC inte...	2.52	4090	2.47	2.55
ScuCHTref	Internal voltag...	1.23	3F17	1.21	1.25
ScuCHTgnd	Internal Groun...	0.00	000A	-0.04	0.04
ScuTHTref	Internal voltag...	1.24	3F4A	1.21	1.25
ScuTHTgnd	Internal Groun...	0.00	0001	-0.04	0.04

6 Temp / SubK Channels

⇒ FPU simulator switched ON in slave mode

⇒ Run the Script Script_Spire_R1R2R3R4.spt : the four set of TEMP resistances are switched on successively

⇒ Batch executed by LTU : SCUSubK_and_TEMP.txt : the LTU sets the four set of TEMP resistances successively and performs TM acquisitions.

⇒ 1 TM files generated by LTU (DPU)

⇒ Rename the files with the extension :

Main side :

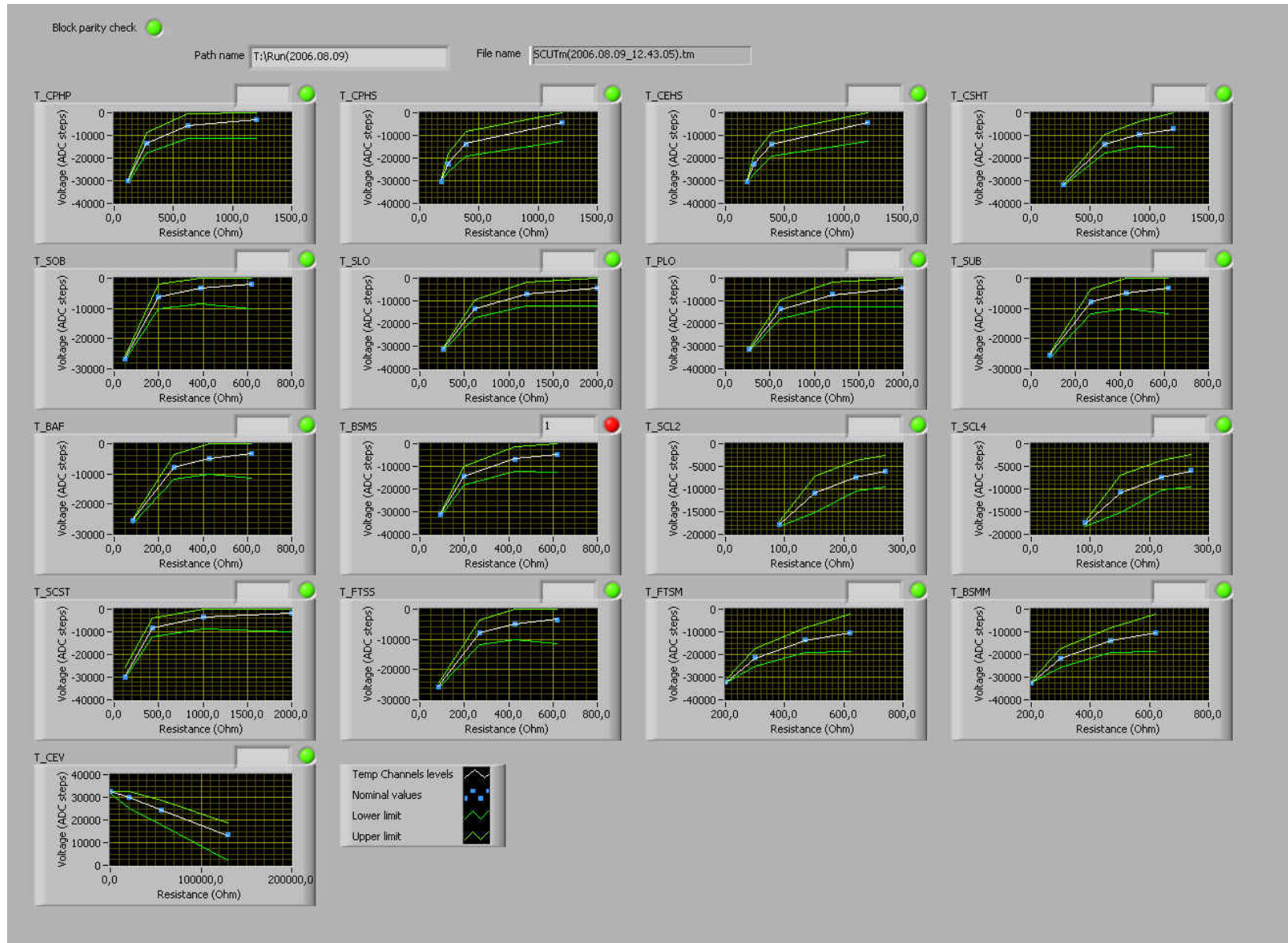
	As run (SCU TEMP/SubK)
Renamed TM file	SCUTm(yyyy.mm.dd_hh.mm.ss)_Temp_SubK_main.tm

Redundant side :

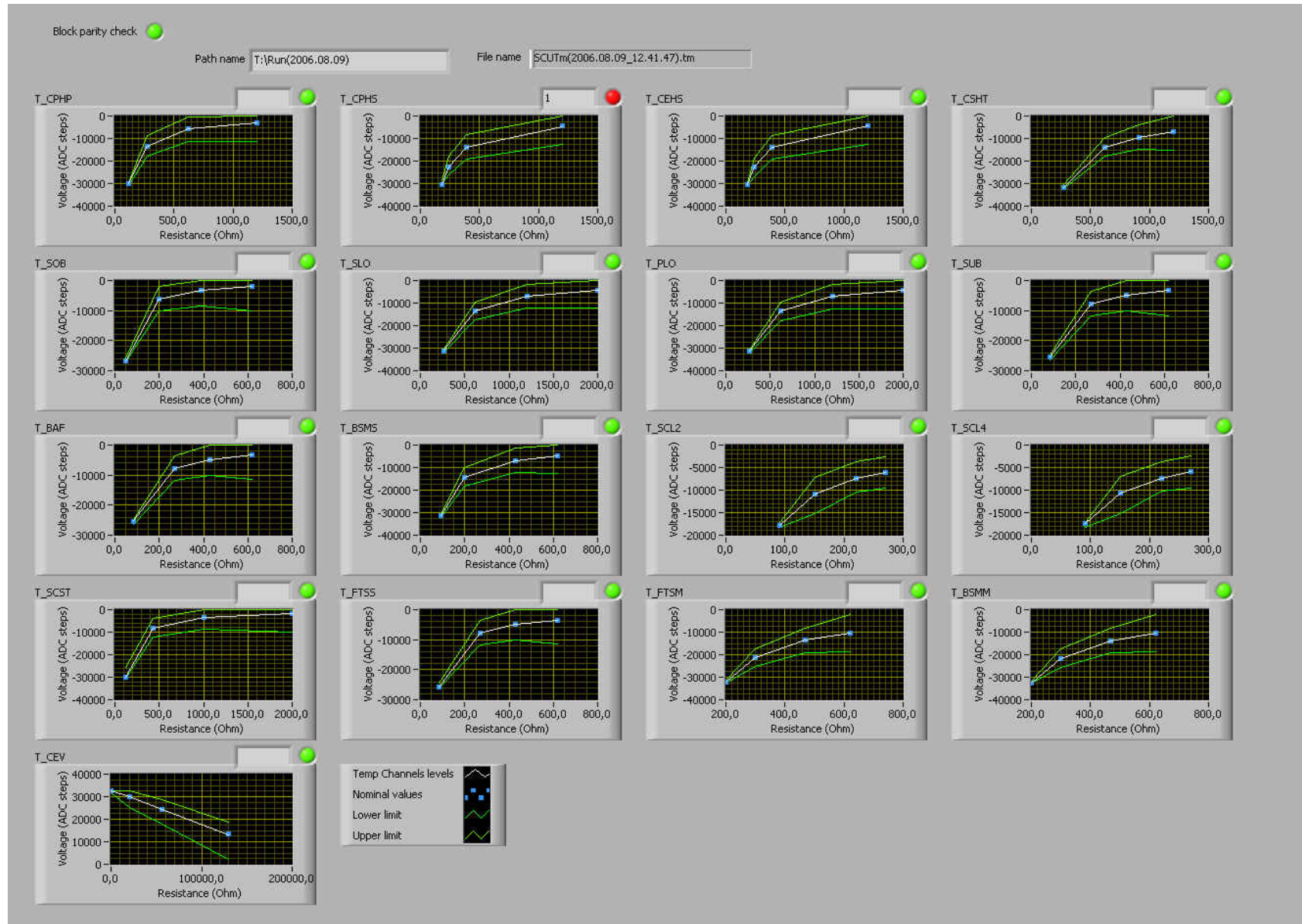
	As run (SCU TEMP/SubK)
Renamed TM file	SCUTm(yyyy.mm.dd_hh.mm.ss)_Temp_SubK_redundant.tm

The results are given on the screen copies here after :

Main side



Redundant side



7 Heaters Calibrators tests

⇒ FPU simulator switched ON in stand alone mode
⇒ Run any Script

⇒ Batch executed by LTU : SCU_Heater_and_Calib.txt : the LTU sets different current levels on Heater/calibrator channels.

- ⇒ 1 TM files generated by LTU (DPU)
- ⇒ 1 H/K files generated by LTU (DPU)
- ⇒ Rename the files with the extension :

Main side :

	As run (SCU Heater/Calib)
Renamed TM file	SCUTm(yyyy.mm.dd_hh.mm.ss)_Heater_Calib_main.tm
Renamed H/K file	SCUAck(yyyy.mm.dd_hh.mm.ss)_Heater_Calib_main.tm

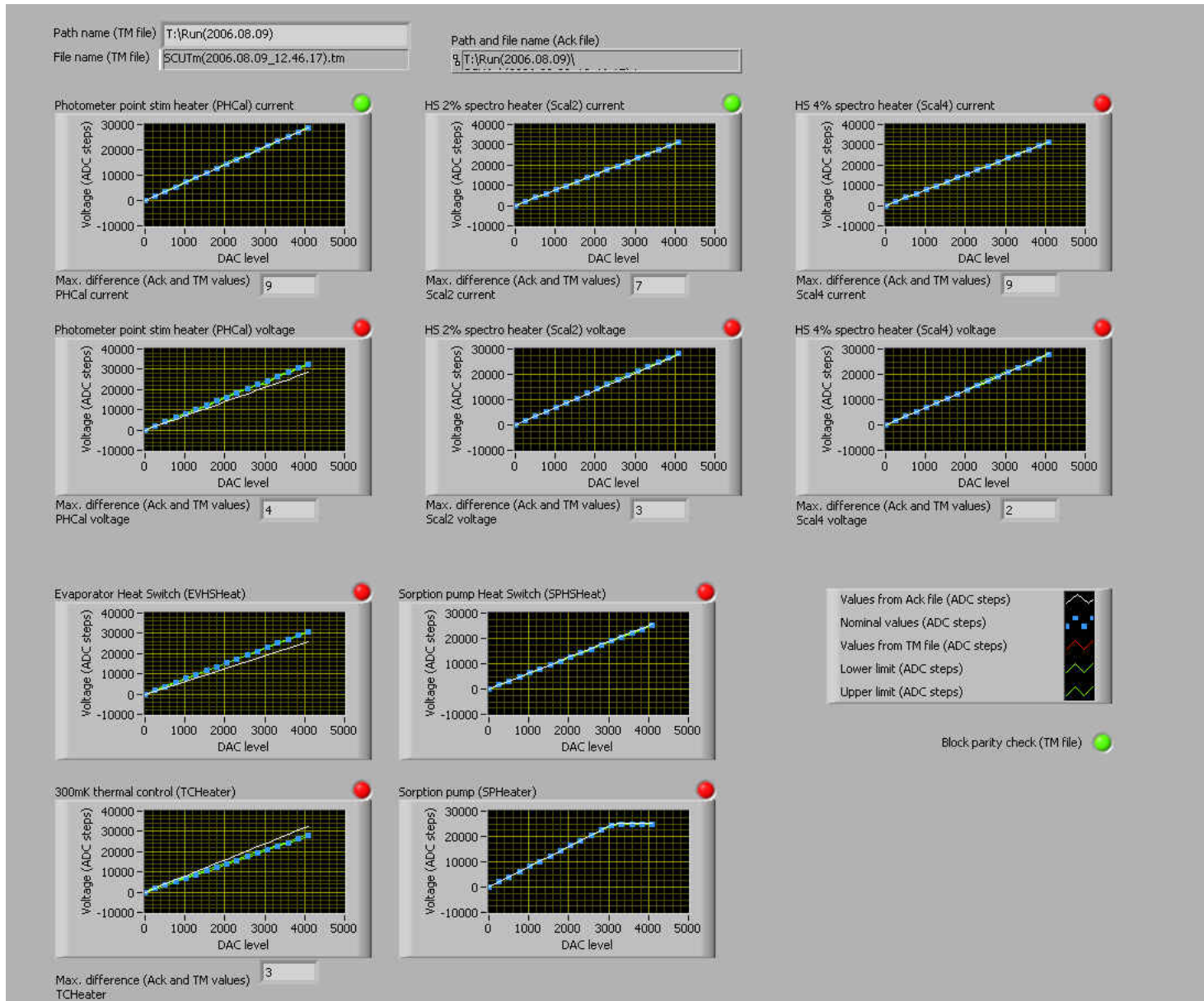
Redundant side :

	As run (SCU Heater/Calib)
Renamed TM file	SCUTm(yyyy.mm.dd_hh.mm.ss)_Heater_Calib_main.tm
Renamed H/K file	SCUAck(yyyy.mm.dd_hh.mm.ss)_Heater_Calib_main.tm

The results are given on the screen copies here after :

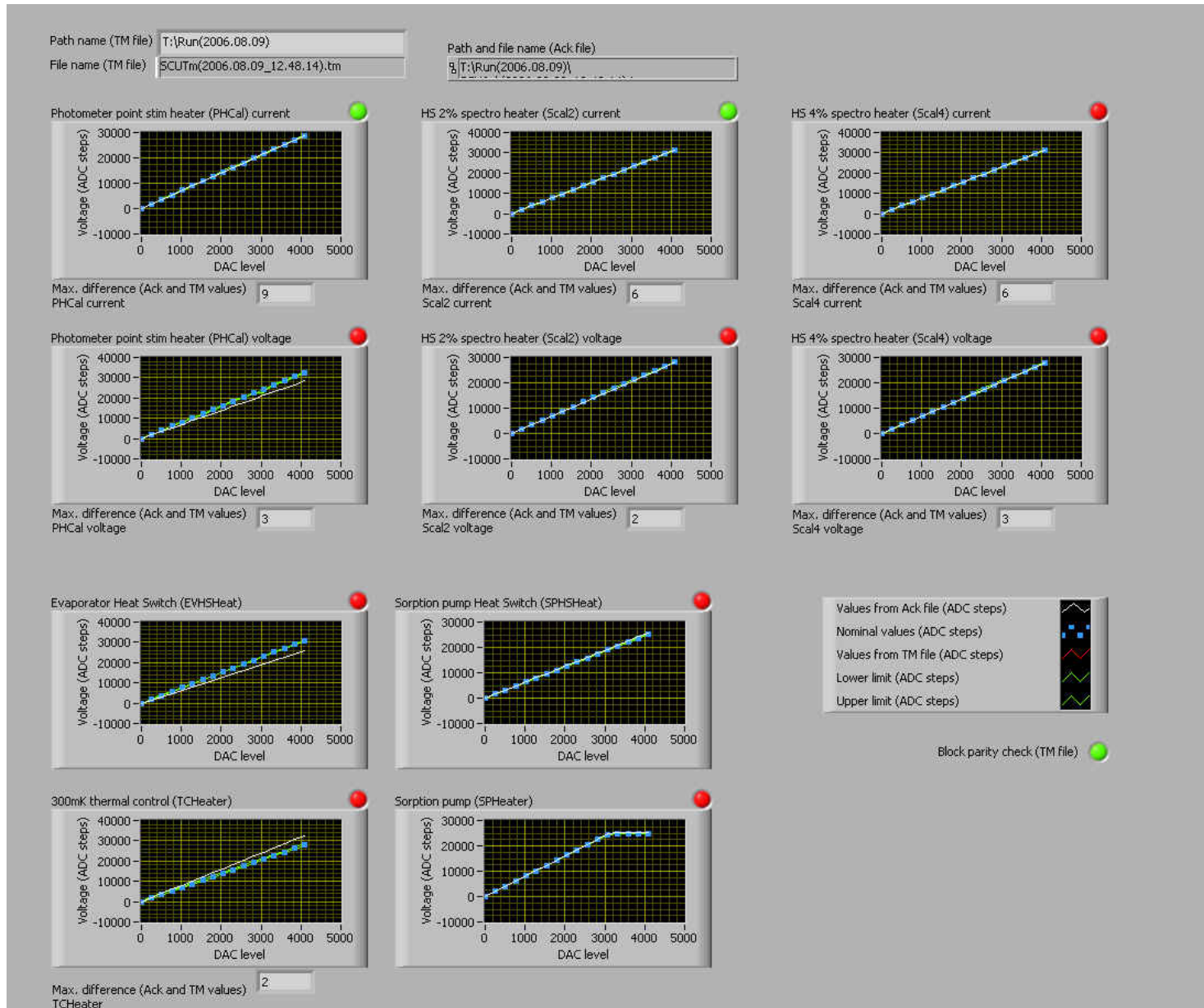
Report of functional tests at RAL

Main side



Report of functional tests at RAL

Redundant side



8 Currents generated by SCU as measured by FPU simulator

⇒ FPU simulator switched ON in slave mode (the harnesses, on FPU simulator side, will be plugged on Main part so that the generated measurement files can be analysed by the labview software (it analyzes the main part)

⇒ We run any the script SPIRE_test_LGS_1.spt

⇒ Batch executed by LTU : Heater_and_Calib_mes.txt

The LTU sends commands to that the SCU generates currents over the DAC range on all Heater/calibrator channels.

This test is performed successively in main and redundant sides so that we get 2 measurement files generated by the FPU simulator.

The measurement file obtained are :

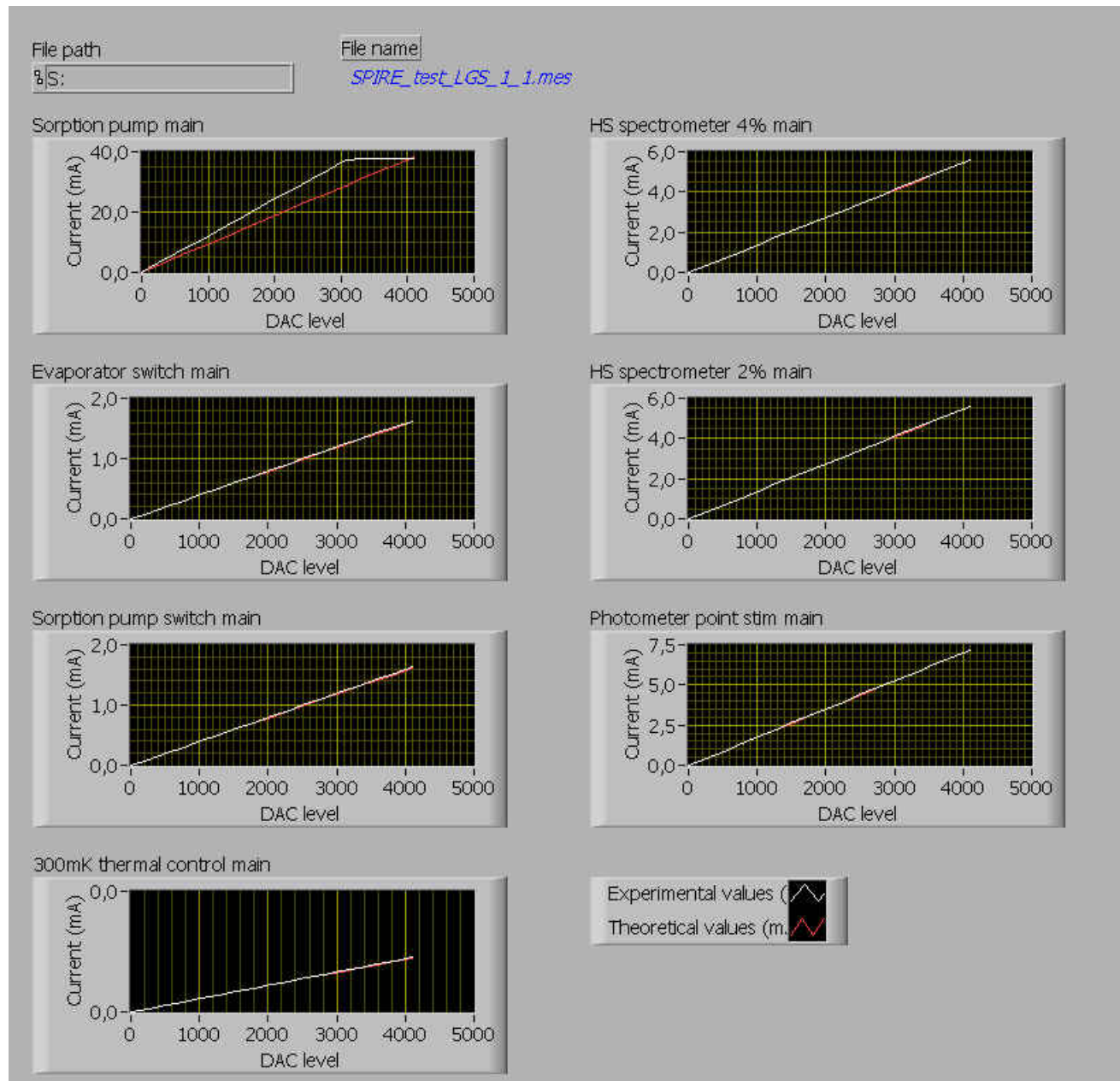
Script_Spire_01\Script_Spire_01_090806_122652\SPIRE_test_LGS_1_1.mes for main side

Script_Spire_01\Script_Spire_01_090806_122544\SPIRE_test_LGS_1_1.mes for redundant side

The thereafter graphics represent the currents sent by SCU on Heaters calibrators channels, as measured by the FPU simulator.

We get the same results on main and redundant sides.

These results correspond to the expected nominal values.



9 Currents generation test in stand alone mode : Monitoring of currents

When in stand alone mode, we can check all the BIAS on a given working point. We use the test sequence BIAS-TEST(stand alone).txt

Check the measurement file on the FPU simulator : Values of all the heaters and Calibrators currents at a given level (refer to the batch)

The measurement file obtained is : SPIRE_test_LGS_1_1.mes to be renamed as Currents.mes.

We set the DAC to their maximum (test sequence : Heater_and_Calib_DAC_MAXI_mes.txt) and measure the currents at simulator level. The results are the following :

Refer to file : Currents.mes

	<i>Expected⁽¹⁾</i>	<i>Main side</i>	<i>Redundant side</i>
Sorption pump main :	38.157E-3 A	38.210E-3 A	38.265E-3 A
Evaporator Switch main :	1.625E-3 A	1.627-3 A	1.625-3 A
Sorption pump Switch main :	1.626E-3 A	1.627-3 A	1.627-3 A
300mK thermal control main :	4.533E-6 A	4.537-6 A	4.535-6 A
HS spect 4% main :	5.597E-3 A	5.606-3 A	5.607-3 A
HS spect 2% main :	5.598E-3 A	5.606-3 A	5.606-3 A
Photometer point stim main :	7.183E-3 A	7.193-3 A	7.188-3 A

⁽¹⁾ from previous tests

We check that these values are consistent with the specifications.

10 MCU Functional Tests

10.1 Test principle

The MCU functional parameters, coming from the telemetry messages, have been tested on main and redundant sides and under the following functional configurations :

- Configuration 1 : MCU ON, all currents applied to the mechanisms set at 0 level
- Configuration 2 : MCU ON, all currents applied to the mechanisms set at 0 level; latch engaged
- Configuration 3 :MCU ON, all currents applied to the mechanisms set at 10% level;
- Configuration 4 :MCU ON, all currents applied to the mechanisms set at 50% level;
- Configuration 3 :MCU ON, all currents applied to the mechanisms set at 100% level;

Under each of these configurations, the values of the thereafter parameters are read from telemetry packets. We reprogrammed the telemetry packets so as to get all these required parameters within different kind of telemetry packets. We then test the capability of receiving simultaneously all kind of telemetry packets.

- Encoder Sinus 0°,
- Encoder Sinus 120°,
- Encoder sinus 240°,
- LVDT AC
- LVDT DC
- SMEC Motor Current,
- SMEC Motor Voltage
- Chopper Sensor
- Chopper current
- Chopper Voltage
- Jiggle sensor
- Jiggle current
- Jiggle voltage

The test setup is the following :

Simulator Configuration

The MCU FPU simulator is switched ON.

The following procedure is applied to launch the simulation :

- ⇒ dSPACE control desk (on computer screen)
- ⇒ File : Recent Experiment -> c:\dSPACE\Work\testenv
- ⇒ Icon “Load application model” -> c:\MATLAB6p1\work\testenvatsteelqm2.sdf
- ⇒ Icon “Animation Mode”

To stop, Icone “Edit Mode”, then File Exit

Note : in case of problem : View-> Active Navigator -> mainlayout.lay

Test of the functional parameters of the MCU

⇒ Batch executed by LTU : MCU TESTS Main Redundant FM.txt

5 different test configurations are commanded by the LTU, these are separated by stops in the test sequence. These configurations are executed in Main and Redundant configurations.

⇒ Note : When switching from MAIN to REDUNDANT, change the harnesses.

The analysis consists in checking the values from the telemetry packets . We check consistency of these parameters with data given in the files indicating their nominal values (with associated margins). These files are provided by LAM.

⇒ Window HK/MCU at LTU

⇒ Check the displayed values depending on the configuration by comparison to expected values

10.2 Tests results

The values of the engineering parameters under each configuration have been saved in EXCEL files (“MCU_FM_main.xls” and “MCU_FM_redundant.xls”) so as to be compared to the expected values. The values of these parameters remained nominal in main and redundant sides.

The tests performed are :

Tests in Main configuration

Refer to file “MCU_FM_main.xls”

Test in configuration 1

All motors (SMEC, BSM) at zero level

Test in configuration 2

All motors (SMEC, BSM) at zero level

Tout à zero level, latch engaged

Test in configuration 3

All motors (SMEC, BSM) at 10% level

Test in configuration 4

All motors (SMEC, BSM) at 50% level

Test in configuration 5

All motors (SMEC, BSM) at 100% level

Tests in Redundant configuration

Refer to file “MCU_FM_redundant.xls”

Test in configuration 1

All motors (SMEC, BSM) at zero level

Test in configuration 2

All motors (SMEC, BSM) at zero level

Tout à zero level, latch engaged

Test in configuration 3

All motors (SMEC, BSM) at 10% level

Test in configuration 4

All motors (SMEC, BSM) at 50% level

Test in configuration 5

All motors (SMEC, BSM) at 100% level

10.3 Report of the primary current consumption (28V)

MCU Status	Main	Redundant	Expected ⁽¹⁾
OFF	400 mA	400 mA	400 mA
MCU ON	810 mA	810 mA	810 mA
MCU after boot	870 mA	870 mA	870 mA
Configuration 1	880 mA	870 mA	870 mA
Configuration 2	880 mA	870 mA	870 mA
Configuration 3	930 mA	940 mA	930 mA
Configuration 4	1060 mA	1060 mA	1060 mA
Configuration 5	1210 mA	1210 mA	1210 mA

⁽¹⁾ from previous tests