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# Herschel SPIRE DPU Electrical Test Procedures

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Issue 1

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#### Acronyms

ASI Agenzia Spaziale Italiana (Italian Space Agency)

AVM AVionic Model

CDMS Central Data Management System
CDMU Central Data Management Unit

CGS Carlo Gavazzi Space

CRT Cathode Ray Tube (Oscilloscope)

EEPROM Electrically Erasable Programmable Read Only Memory

EGSE Electrical Ground Support Equipment

EIDP End Item Data Package

EMC ElectroMagnetic Compatibility

ESD Electro Static Discharge

EQM Electrical Qualification Model

DPU Digital Processing Unit

FIRST Far Infra-Red and Sub-millimetre Telescope

FCU Focal plane Control Unit

FM Flight Model

FP S/S Focal Plane sub-system

FPU Focal Plane Unit FS Flight Spare

HIFI Heterodyne Instrument for First

HK House-Keeping

HRS High Resolution Spectrometer
HRSU High Resolution Spectrometer Unit

HW HardWare

IC Instrument Control

ICD Interface Control Document

ICE In Circuit Emulator
ICU Instrument Control Unit

I/F Interface

ILT Instrument Level Test
LCU Local oscillator Control Unit
LOA Local Oscillator Assembly

LO S/S Local Oscillator sub-system

LOU Local Oscillator Unit



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NCR Non Conformance Report

OBS On Board Software PA Product Assurance

PACS Photoconductor Array Camera and Spectrometer

PFM Proto Flight Model

PROM Programmable Read Only memory

QA Quality Assurance QM Qualification Model

S/C Spacecraft S/S Subsystem

SPIRE Spectral and Photometric Imaging Receiver

SW SoftWare

TBC To Be Confirmed
TBD To Be Defined
TBW To Be Written

TLP Transfer Layer Protocol
TRB Test Review Board

TRRB Test Readiness Review Board

UR User Requirement URD UR Document

VCD Verification Control Document

WBS S/S Wide Band Spectrometer sub-system

WBSU Wide Band Spectrometer Unit



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#### 1 INTRODUCTION

#### 1.1 General

The content of this procedure is based on the DPU model philosophy and the DPU subsystem specification (AD03), the DPU product tree; it is consistent with the interface documents AD01 and AD02. This document specifies how the electrical tests will be carried-out on the DPU, to be sure that the DPU fulfils its electrical performances with the subsystems and with the S/C. The subsystem that is delivered for integration and tests at instrument level consists of an electronic box called DPU and of the On Board Software both appropriate for each of the delivered models. As the DPU boards are designed and manufactured by CGS, the electrical tests related to the boards are CGS responsibility and the relevant test procedures are in REF02-REF04. These procedures cover also the interfaces of the DPU with the subsystems and with the S/C. The S/C interfaces of the integrated DPU subsystem are covered from the physical layer to the SW application layer in REF05.

At integrated instrument level however the secondary power and the command/data interfaces tests should be repeated in order to check also the cabling.

The remaining electrical tests, that are typical of the DPU integrated subsystem, **continuity and bonding measurements**, are also described in this document. This procedure applies to the following deliverable models of the DPU subsystem:

EQM subsystem FM subsystem

The letters EQM and FM identify these models respectively.

#### 1.2 Objectives

Verification by means of testing of the DPU subsystem with respect to the subsystem specification, especially with reference to AD01-AD06.

#### 1.3 Tools

The following electrical instruments will be used to carry out the measurements:



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- for resistance measurements the PROTEK 506 Digital Multimeter;
- for capacitance measurements the Wayne Kerr Automatic LCR Meter 4250;
- for low resistance measurements CROPICO Digital Ohmmeter –D05.
- For command/data timing measurement the Oscilloscope (CRT) Tektronix TDS 380

#### 2 DOCUMENTS

#### 2.1 Applicable Documents

AD	Name		
01	Herschel/Planck Instrument Interface Document, part A		
02	Herschel/Planck Instrument Interface Document, part B-Instrument SPIRE		
03	Herschel SPIRE DPU Subsystem Specification Document		
04	SPIRE DPU ICD		
05	DPU/ICU P.A.Plan		
06	SPIRE DPU AIT Plan		

#### 2.2 Reference Documents

RD	Title		
01	SPIRE DPU User manual		
02	CPU BOARD Test Procedure		
03	I/F BOARD Test Procedure		
04	DC/DC BOARD Test Procedure		
05	DPU/ICU Spacecraft Interface Acceptance Test Plan		



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#### 3 Command/Data Interface Checks

The clock and the command words are generated by the DPU and are the same for all subsystems but with separated line drivers. It is checked that:

- the cabling is without faults;
- the subsystem addresses are correct;
- the command bits change on the clock falling edge;
- rise and fall times are within limits;

**NOTE:** the Oscilloscope COMMON is connected to GND, the 2 CRT channels should show inverted signals (positive signal on pin 2, 3, 4, 8, 10, 11 of J07, J08, J09, J10, J11, J12)

3.1	3.1 Connector JO7		Clock Measured	Clock Nominal	Passed
Pin		Pin			
2		-		312500 Hz	
15		-		312500 Hz	
			Rise Time Measured	Rise Time nominal	
2		-		< 100 ns	
15		-		< 100 ns	
			Fall Time Measured	Fall Time Nominal	
2		-		< 100 ns	
15		-		< 100 ns	
			Command Address	Command Addr. Sent	
3		-		00	



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16		-		11	
			Rise Time Measured	Rise Time nominal	
3		-		< 100 ns	
16		-		< 100 ns	
			Fall Time Measured	Fall Time Nominal	
3		-		< 100 ns	
16		-		< 100 ns	
3.2	Co J1	onnector 10	Clock Measured	Clock Nominal	Passed
Pin		Pin			
2		-		312500 Hz	
15		-		312500 Hz	
			Rise Time Measured	Rise Time nominal	
2		-		< 100 ns	
15		-		< 100 ns	
			Fall Time Measured	Fall Time Nominal	
2		-		< 100 ns	
15		-		< 100 ns	
			Command Address	Command Addr. Sent	
3		-		00	
16		-		11	
			Rise Time Measured	Rise Time nominal	
3		-		< 100 ns	



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16	-		< 100 ns	
		Fall Time Measured	Fall Time Nominal	
3	-		< 100 ns	
16	-		< 100 ns	
3.3	Connector J08	Clock Measured	Clock Nominal	Passed
Pin	Pin			
2	-		312500 Hz	
15	-		312500 Hz	
		Rise Time Measured	Rise Time nominal	
2	-		< 100 ns	
15			< 100 ns	
		Fall Time Measured	Fall Time Nominal	
2			< 100 ns	
15			< 100 ns	
		Command Address	Command Addr. Sent	
3			01	
16			10	
		Rise Time Measured	Rise Time nominal	
3			< 100 ns	
16			< 100 ns	
		Fall Time Measured	Fall Time Nominal	
3	-		< 100 ns	



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16			< 100 ns	
3.4 Connector J11		Clock Measured	Clock Nominal	Passed
Pin	Pin			
2	-		312500 Hz	
15	-		312500 Hz	
		Rise Time Measured	Rise Time nominal	
2	-		< 100 ns	
15	-		< 100 ns	
		Fall Time Measured	Fall Time Nominal	
2	-		< 100 ns	
15	-		< 100 ns	
		Command Address	Command Addr. Sent	
3	_		01	
16	_		10	
		Rise Time Measured	Rise Time nominal	
3	-		< 100 ns	
16	_		< 100 ns	
		Fall Time Measured	Fall Time Nominal	
3	-		< 100 ns	
16	-		< 100 ns	



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3.5	Connect J09	Clock Measured	Clock Nominal	Passed
Pin	Pin			
2	_		312500 Hz	
15			312500 Hz	
		Rise Time Measured	Rise Time nominal	
2			< 100 ns	
15			< 100 ns	
		Fall Time Measured	Fall Time Nominal	
2	_		< 100 ns	
15			< 100 ns	
		Command Address	Command Addr. Sent	
3			10	
16			01	
		Rise Time Measured	Rise Time nominal	
3	_		< 100 ns	
16	_		< 100 ns	
		Fall Time Measured	Fall Time Nominal	
3			< 100 ns	
16	_		< 100 ns	
3.6	Connect J12	tor		Passed
Pin	Pin			



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2	-		312500 Hz
15	-		312500 Hz
		Rise Time Measured	Rise Time nominal
2	_		< 100 ns
15	-		< 100 ns
		Fall Time Measured	Fall Time Nominal
2	-		< 100 ns
15	-		< 100 ns
		Command Address	Command Addr. Sent
3	-		10
16	-		01
		Rise Time Measured	Rise Time nominal
3	-		< 100 ns
16	_		< 100 ns
		Fall Time Measured	Fall Time Nominal
3	-		< 100 ns
16	-		< 100 ns

NOTE: Once tested that the clock and command signals are on the expected connectors, the phasing of clock and commands will be documented with one CRT picture and the waiting time after an HK request will be documented with one CRT picture.



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#### 4 Continuity Checks

In the following table the measurements of the relevant pins with respect to the GND are reported.

**NOTE:** the column 1 pin is connected to the instrument COMMON.

4.1	Connector JO1	Resistance Measured	Resistance Nominal	Passed
Pin	Pin			
2	7		0	
2	GND		> 1 MOHM	
2	GND		< 10 nF	
4	9		0	
4	GND		> 1 MOHM	
4	GND		< 10 nF	
2	4		> 20 kOHM	
4.2	Connector JO2	Resistance Measured	Resistance Nominal	Passed
Pin	Pin			
2	7		0	
2	GND		> 1 MOHM	
2	GND		< 10 nF	
4	9		0	
4	GND		> 1 MOHM	



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4	GND		< 10 nF	
2	4		> 20 kOHM	
	Connector IO3	Resistance Measured	Resistance Nominal	Passed
Pin	Pin			
2	GND		> 1 MOHM	
6	GND		> 1 MOHM	
2	6		> 0 OHM	
	Connector JO4	Resistance Measured	Resistance Nominal	Passed
Pin	Pin			
2	GND		> 1 MOHM	
6	GND		> 1 MOHM	
2	6		> 0 OHM	
	Connector JO5	Resistance Measured	Resistance Nominal	Passed
Pin	Pin			
2	GND		> 1 MOHM	
6	GND		> 1 MOHM	
2	6		> 0 OHM	



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	onnector O6	Resistance Measured	Resistance Nominal	Passed
Pin	Pin			
2	GND		> 1 MOHM	
6	GND		> 1 MOHM	
2	6		> 0 OHM	

4.6.1	Connector JO7	Resistance Measured	Resistance Nominal	Passed
Pin	Pin			
1	GND		0	
2	GND		> 10 KOHM	
3	GND		> 10 KOHM	
4	GND		> 10 KOHM	
8	GND		> 7 kOHM	
10	GND		> 7kOHM	
11	GND		> 7 kOHM	
14	GND		0	
15	GND		> 10 kOHM	
16	GND		> 10 kOHM	
17	GND		> 10 kOHM	



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	<u> </u>	<u> </u>		
21	GND		> 7 kOHM	
22	GND		> 7 kOHM	
24	GND		> 7 kOHM	
2	15		> 20 kOHM	
3	16		> 20 kOHM	
4	17		> 10 kOHM	
8	21		> 10 kOHM	
10	22		> 10 kOHM	
11	24		> 10 kOHM	
	Connector JO8	Resistance Measured	Resistance Nominal	Passed
Pin	Pin			
1	GND		0	
2	GND		> 10 KOHM	
3	GND		> 10 KOHM	
4	GND		> 10 KOHM	
8	GND		> 7 kOHM	
10	GND		> 7kOHM	
11	GND		> 7 kOHM	
14	GND		0	
			10 kOUM	
15	GND		> 10 kOHM	



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I	T	T	
GND		> 10 kOHM	
GND		> 7 kOHM	
GND		> 7 kOHM	
GND		> 7 kOHM	
15		> 20 kOHM	
16		> 20 kOHM	
17		> 10 kOHM	
21		> 10 kOHM	
22		> 10 kOHM	
24		> 10 kOHM	
Connector	Resistance Measured	Resistance Nominal	Passed
JO9			
Pin			
		0	
שמוטן			
GND GND		> 7 kOHM 0	
	GND GND 15 16 17 21 22 24	GND GND 15 16 17 21 22 24  Connector Resistance Measured Pin GND	GND         > 7 kOHM           GND         > 7 kOHM           GND         > 7 kOHM           15         > 20 kOHM           16         > 20 kOHM           17         > 10 kOHM           21         > 10 kOHM           22         > 10 kOHM           24         > 10 kOHM           Pin         Resistance Measured GND           GND         > 10 KOHM           GND         > 7 KOHM



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	T	<u> </u>	T .	
16	GND		> 10 kOHM	
17	GND		> 10 kOHM	
21	GND		> 7 kOHM	
22	GND		> 7 kOHM	
24	GND		> 7 kOHM	
2	15		> 20 kOHM	
3	16		> 20 kOHM	
4	17		> 10 kOHM	
8	21		> 10 kOHM	
10	22		> 10 kOHM	
11	24		> 10 kOHM	
	Connector J10	Resistance Measured	Resistance Nominal	Passed
Pin	Pin			
1	GND		0	
2	GND		> 10 KOHM	
3	GND		> 10 KOHM	
4	GND		> 10 KOHM	
8	GND		> 7 kOHM	
9	GND		> 7kOHM	
10	GND		> 7 kOHM	



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3 4	16		> 10 kOHM > 10 kOHM	
10	22		> 10 kOHM > 10 kOHM	
	24 Connector J11	Resistance Measured	Resistance Nominal	Passed
Pin	Pin			
1	GND		0	
2	GND		> 10 KOHM	
_			> 10 KOHM	
3	GND		> 10 KOHM	



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10	GND		> 7kOHM	
11	GND		> 7 kOHM	
14	GND		0	
15	GND		> 10 kOHM	
16	GND		> 10 kOHM	
17	GND		> 10 kOHM	
21	GND		> 7 kOHM	
22	GND		> 7 kOHM	
24	GND		> 7 kOHM	
2	15		> 20 kOHM	
3	16		> 20 kOHM	
4	17		> 10 kOHM	
8	21		> 10 kOHM	
10	22		> 10 kOHM	
11	24		> 10 kOHM	
	Connector J12	Resistance Measured	Resistance Nominal	Passed
Pin	Pin			
1	GND		0	
2	GND		> 10 KOHM	
3	GND		> 10 KOHM	
4	GND		> 10 KOHM	



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8	GND	> 7 kOHM
10	GND	> 7kOHM
11	GND	> 7 kOHM
14	GND	0
15	GND	> 10 kOHM
16	GND	> 10 kOHM
17	GND	> 10 kOHM
21	GND	> 7 kOHM
22	GND	> 7 kOHM
24	GND	> 7 kOHM
2	15	> 20 kOHM
3	16	> 20 kOHM
4	17	> 10 kOHM
8	21	> 10 kOHM
10	22	> 10 kOHM
11	24	> 10 kOHM

#### 5 Bonding Checks

In the following table the measurements of the resistance between the relevant parts of the box/connectors and the bonding lug are reported.



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#### 5.1 Measurements between adjacent faces of the equipment chassis

BOX PART1	BOX PART2	Measured Value (mOHM)	Maximum Value (mOHM)	PASSED
Base-plate	Front Wall		2.5	
Base-plate	Тор		2.5	
Base-plate	Back Wall		2.5	
Front Wall	Тор		2.5	
Back Wall	Тор		2.5	

#### 5.2 Measurements between bonding lug and underside of the mounting feet

POINT 1	POINT 2	Measured Value (mOHM)	Maximum Value (mOHM)	PASSED
Bonding lug	Ref foot (say 1)		2.5	
Bonding lug	Foot (say 2)		2.5	
Bonding lug	Foot (say 3)		2.5	
Bonding lug	Foot (say 4)		2.5	



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Bonding lug	Foot (say 5)	2.5	
Bonding lug	Foot (say 6)	2.5	

#### 5.3 Measurements between instrument star point and bonding lug

POINT 1	POINT 2	Measured Value (mOHM)	Maximum Value (mOHM)	PASSED
Bonding lug	Box Star Point		5.0	

#### 5.4 Measurements between any shield ground and chassis

POINT 1	CONNECTORS PINS	Measured Value (mOHM)	Maximum Value (mOHM)	PASSED
Screw-lock Ass.	J07 - 1		2.5 mOHM	
Screw-lock Ass.	J07 - 14		2.5 mOHM	
Screw-lock Ass.	J08 - 1		2.5 mOHM	
Screw-lock Ass.	J08 - 14		2.5 mOHM	
Screw-lock Ass.	J09 - 1		2.5 mOHM	
Screw-lock Ass.	J09 - 14		2.5 mOHM	



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Screw-lock Ass.	J10 - 1	2.5 mOHM	
Screw-lock Ass.	J10 - 14	2.5 mOHM	
Screw-lock Ass.	J11 - 1	2.5 mOHM	
Screw-lock Ass.	J11 - 14	2.5 mOHM	
Screw-lock Ass.	J12 - 1	2.5 mOHM	
Screw-lock Ass.	J12 - 14	2.5 mOHM	

#### 5.5 Measurements between bonding lug and connectors screw-lock assembly

POINT 1	CONNECTORS SCREW-LOCK ASSEMBLY	Measured Value (mOHM)	Maximum Value (mOHM)	PASSED
Bonding lug	J01		2.5 mOHM	
Bonding lug	J02		2.5 mOHM	
Bonding lug	J03		2.5 mOHM	
Bonding lug	J04		2.5 mOHM	
Bonding lug	J05		2.5 mOHM	
Bonding lug	J06		2.5 mOHM	
Bonding lug	J07		2.5 mOHM	
Bonding lug	J08		2.5 mOHM	
Bonding lug	J09		2.5 mOHM	
Bonding lug	J10		2.5 mOHM	



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Bonding lug	J11	2.5 mOHM	
Bonding lug	J12	2.5 mOHM	