

	DRCU INTERFACE CONTROL DOCUMENT	 SAp-SPIRE-CCa-25-00 Issue: 0.6 Date :1/03/02
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SPIRE INSTRUMENT

DETECTOR READOUT & CONTROL UNIT INTERFACE CONTROL DOCUMENT

Contributors: **F. PINSARD-DCU Engineer**
 D. FERRAND-MCU
 O. GACHELIN-SCU Engineer

	Name and Function	Date	Signature
Prepared by:	C.CARA - DRCU Responsible	1/03/02	
Verified by:	F.PINSARD D. FERRAND O. GACHELIN		
Approved by:	F. LOUBERT-PA Responsible		
Approved by:	JL. AUGUERES - Project Manager		

Table of Contents

1.	INTRODUCTION	9
1.1.	PURPOSE	9
1.2.	SCOPE	9
1.3.	REFERENCE DOCUMENTS.....	9
1.4.	APPLICABLE DOCUMENTS	9
1.5.	INTERFACES CROSS-MATRIX	10
2.	THERMO-MECHANICAL INTERFACES.....	11
2.1.	MECHANICAL INTERFACES.....	11
2.2.	THERMAL INTERFACES.....	11
3.	ELECTRICAL INTERFACES WITH THE DPU.....	15
3.1.	COMMAND INTERFACE.....	15
3.1.1.	<i>General Information.....</i>	<i>15</i>
3.1.2.	<i>Interface Overall Diagrams</i>	<i>16</i>
3.1.3.	<i>Interface Circuit.....</i>	<i>16</i>
3.1.4.	<i>Protocol definition</i>	<i>18</i>
3.1.4.1.	Command Word	18
3.1.4.2.	Response Word.....	19
3.1.4.3.	Word exchange	20
3.1.5.	<i>Interface Timing.....</i>	<i>21</i>
3.1.5.1.	Low level Timing	21
3.1.5.2.	Command timing	21
3.1.5.3.	Performance.....	21
3.2.	COMMAND LIST	22
3.2.1.1.	Command and parameter mapping.....	22
3.2.2.	<i>DRCU generic command list summary.....</i>	<i>22</i>
3.2.2.1.	Write only commands	22
3.2.2.2.	Read only commands	22
3.2.2.3.	Read/Write Commands	22
3.2.3.	<i>DRCU command description</i>	<i>23</i>
3.2.3.1.	TstampRst.....	23
3.2.3.2.	CmdIfStat.....	23
3.2.3.3.	CmdIfCtrl.....	23
3.2.4.	<i>DRCU parameter description</i>	<i>23</i>
3.2.5.	<i>DCU specific command list summary.....</i>	<i>24</i>
3.2.5.1.	Command and parameter mapping.....	24
3.2.5.2.	Photometer write/read commands	24
3.2.5.3.	Spectrometer write/read commands	25
3.2.5.4.	Photometer / spectrometer common write/read commands.....	25
3.2.5.5.	Read only commands	25
3.2.5.6.	DCU housekeeping identifier list	26
3.2.6.	<i>DCU command description.....</i>	<i>27</i>
3.2.6.1.	Photometer	27
3.2.6.2.	SetPhSWJfetBias	30
3.2.6.3.	SetPhMLWJfetBias	30
3.2.6.4.	Spectrometer	33
3.2.7.	<i>DCU parameters description</i>	<i>38</i>
3.2.7.1.	Photometer	38
3.2.7.2.	Spectrometer	41
3.2.8.	<i>DCU typical commanding scenarios</i>	<i>43</i>
3.2.8.1.	DCU Configuration	43
3.2.8.2.	Photometer Configuration.....	45
3.2.8.3.	Photometer offset setting.....	45

3.2.8.4.	Photometer acquisition.....	46
3.2.8.5.	Spectrometer Configuration.....	46
3.2.8.6.	Spectrometer offset setting.....	46
3.2.8.7.	Spectrometer acquisition.....	47
3.2.9.	<i>MCU specific command list summary</i>	48
3.2.9.1.	SMEC Commands.....	48
3.2.9.2.	CHOP COMMANDS.....	50
3.2.9.3.	JIGGLE COMMANDS.....	51
3.2.9.4.	TELEMETRY AND TRACE CONFIGURATION COMMANDS.....	51
3.2.9.5.	HK and miscellaneous commands.....	51
3.2.10.	<i>MCU typical commanding scenarios</i>	52
3.2.10.1.	SMEC Commanding scenarios.....	52
3.2.10.2.	Commanding the SMEC.....	53
3.2.10.3.	Commanding the Chopper.....	54
3.2.10.4.	Commanding the Jiggle and Chopper.....	55
3.2.11.	<i>SCU specific command list summary</i>	56
3.2.11.1.	Command and parameter mapping.....	56
3.2.11.2.	Write/read commands.....	56
3.2.11.3.	Read only commands.....	56
3.2.12.	<i>SCU command description</i>	57
3.2.12.1.	Write only commands.....	57
3.2.12.2.	Read/Write commands.....	57
3.2.12.3.	Read only commands.....	61
3.2.13.	<i>SCU parameters description</i>	66
3.2.14.	<i>SCU typical commanding scenarios</i>	67
3.3.	DATA INTERFACE.....	68
3.3.1.	<i>General Information</i>	68
3.3.2.	<i>Overall Interface Diagram</i>	68
3.3.3.	<i>Interface Circuit</i>	68
3.3.4.	<i>Word definition</i>	69
3.3.5.	<i>General Frame Definition</i>	70
3.3.5.1.	Length.....	70
3.3.5.2.	Frame ID.....	70
3.3.5.3.	Frame time.....	76
3.3.5.4.	Data structure.....	71
3.3.5.5.	Check word.....	77
3.3.6.	<i>Test pattern</i>	77
3.3.7.	<i>Interface Timing</i>	77
3.3.8.	<i>Timing Performance</i>	77
3.3.9.	<i>Data Rate Estimations</i>	77
4.	INTERFACE WITH S/C.....	78
4.1.	PCDU INTERFACE.....	78
4.1.1.	<i>Electrical characteristics</i>	78
4.1.2.	<i>Power profile</i>	78
5.	INTERFACE WITH FPU.....	79
5.1.	DCU INTERFACE.....	79
5.1.1.	<i>Seeing Bolometer Bias Interface</i>	79
5.1.1.1.	Electrical characteristics.....	79
5.1.1.2.	Interface circuitry.....	79
5.1.2.	<i>T/C Bolometer Bias Interface</i>	80
5.1.2.1.	Electrical characteristics.....	80
5.1.2.2.	Interface circuitry.....	80
5.1.3.	<i>JFET Vss bias interface</i>	81
5.1.3.1.	Electrical characteristics.....	81
5.1.3.2.	Interface circuitry.....	81
5.1.4.	<i>JFET Vdd bias interface</i>	82
5.1.4.1.	Electrical characteristics.....	82

5.1.4.2.	Interface circuitry	82
5.1.5.	<i>Heater bias interface</i>	83
5.1.5.1.	Electrical characteristics.....	83
5.1.5.2.	Interface circuitry	83
5.1.6.	<i>Photometer JFET signal interface</i>	84
5.1.6.1.	Electrical characteristics.....	84
5.1.6.2.	Interface circuitry	84
5.1.7.	<i>Spectrometer JFET signal interface</i>	85
5.1.7.1.	Electrical characteristics.....	85
5.1.7.2.	Interface circuitry	85
5.2.	MCU INTERFACE	86
5.2.1.	<i>SMEC Drive coil</i>	86
5.2.1.1.	Excitation	86
5.2.1.2.	Supply Sense.....	87
5.2.2.	<i>SMEC position sensor LED</i>	88
5.2.2.1.	Electrical characteristics.....	88
5.2.3.	<i>SMEC position sensor photodiode</i>	89
5.2.3.1.	Electrical characteristics.....	89
5.2.4.	<i>SMEC position sensor supply</i>	90
5.2.4.1.	Electrical characteristics.....	90
5.2.4.2.	Interface circuitry	90
5.2.5.	<i>SMEC position sensor photodiode</i>	91
5.2.5.1.	Electrical characteristics.....	91
5.2.5.2.	Interface circuitry	91
5.2.6.	<i>SMEC launch latch supply</i>	92
5.2.6.1.	Electrical characteristics.....	92
5.2.6.2.	Interface circuitry	92
5.2.7.	<i>SMEC launch confirmation</i>	93
5.2.7.1.	Electrical characteristics.....	93
5.2.7.2.	Interface circuitry	93
5.2.8.	<i>SMEC LVDT coil supply</i>	94
5.2.8.1.	Electrical characteristics.....	94
5.2.8.2.	Interface circuitry	94
5.2.9.	<i>Chop sensor</i>	95
5.2.9.1.	Supply	95
5.2.9.2.	Sense	96
5.2.10.	<i>Chop sensor output</i>	97
5.2.10.2.	Interface circuitry	97
5.2.11.	<i>Jiggle sensor</i>	98
5.2.11.1.	Supply	98
5.2.11.2.	Sense	99
5.2.11.3.	Interface circuitry	99
5.2.12.	<i>Launch latch sensor</i>	100
5.2.12.2.	Interface circuitry	100
5.2.13.	<i>Launch latch coil supply</i>	101
5.2.13.2.	Interface circuitry	101
5.2.14.	<i>Chop motor</i>	102
5.2.14.1.	Supply	102
5.2.14.2.	Sense	103
5.2.15.	<i>Jiggle motor</i>	104
5.2.15.1.	Supply	104
5.2.15.2.	Sense	105
5.3.	SCU INTERFACES	106
5.3.1.	<i>Temperature Probes – “300 mK”</i>	106
5.3.1.1.	Probe bias.....	106
5.3.1.2.	Probe sense	107
5.3.2.	<i>Standard Temperature Probes</i>	108
5.3.2.1.	Probe bias.....	108
5.3.2.2.	Probe sense	110
5.3.3.	<i>Heaters</i>	112

5.3.3.1.	Sorption pump	112
5.3.3.2.	Heat switches	113
5.3.3.3.	Thermal strap	114
5.3.4.	<i>Calibrator</i>	115
5.3.4.1.	Flood type	115
5.3.4.2.	Point source type	116
6.	CONNECTORS AND HARNESS DEFINITION	117
6.1.	OVERALL HARNESS CONFIGURATION	117
6.2.	CONNECTOR LAYOUT ON BOX.....	118
6.2.1.	<i>DCU box</i>	118
6.2.1.1.	Top View	118
6.2.1.2.	Lateral Views.....	118
6.2.2.	<i>FCU box</i>	119
6.2.2.1.	Top View	119
6.2.2.2.	Lateral Views.....	119
6.2.3.	<i>DRCU to FPU harness tail configuration</i>	120
6.3.	CONNECTOR LIST.....	121
6.4.	CONNECTORS DESCRIPTION.....	123
6.4.1.	<i>Interfaces with DPU</i>	123
6.4.2.	<i>Interfaces with S/C</i>	129
6.4.3.	<i>Interfaces with FPU</i>	132
6.4.3.1.	DCU Interfaces	132
6.4.3.2.	FCU Interfaces.....	144
6.4.3.3.	SCU Interfaces.....	150
7.	GROUNDING SCHEME	160
8.	APPENDIX – DRCU SUB-SYSTEM INTERCONNECTIONS	161
8.1.	PSU TO DCU INTERFACE	161
8.1.1.	<i>Interface Description</i>	161
8.1.2.	<i>Interface definition</i>	161
8.2.	PSU TO MCU INTERFACE.....	163
8.3.	PSU TO SCU INTERFACE	165

1. Introduction

1.1. Purpose

The purpose of this document is to provide a description of all the DRCU units electrical interfaces. Along with the DRCU Mechanical ICD this document shall allow a complete overview of the DRCU units in terms of interfaces. This document will be useful when performing unit test, integration or qualification by containing all the DRCU electrical interfaces (this avoids the need for multiple documents).

1.2. Scope

The scope of this document includes all the DRCU units external interfaces low level description including electrical and low level protocol and connector pin-out. However in the case of the analog interfaces with FPU the description is limited to pin-out since these interfaces are already described in respective sub-system ICDs.

1.3. Reference Documents

RD1	Note IFSI : <i>DPU/DRCU Interfaces</i>	SP-RCI-18.5.00
RD2	Efficient Shift Registers, and Long Pseudo-Random Sequence Generators	XILINX XAPP 052
RD3	MCU interconnections list	LAM/ELE/FTS/NTT/010314 - issue 2.0

1.4. Applicable Documents

AD1	Herschel/Planck IID part A	SCI-PT-IIDA-04624

1.5. Interfaces cross-matrix

This table lists the interface types against the SPIRE sub-assembly for the HSDCU and HSFCU units.

Unit	Interface Types	Interfaces with:
HSDCU	Electrical – Digital	DPU
	Electrical – Analog	FPU
	Mechanical	S/C
	Thermal	S/C
HSFCU	Electrical – Digital	DPU
	Electrical – Analog	FPU
	Electrical - Power	S/C
	Mechanical	S/C
	Thermal	S/C

2. Thermo-mechanical Interfaces

2.1. Mechanical interfaces

2.1.1. HSDCU unit

The mechanical interface can be summarized by assuming the HSDCU unit occupies a rectangular volume defined by its surface, its height and its mass:

- 494 (xxx) mm x 289 mm
- 305 (352.5) mm
- 15.41 kg

Those values (dimensions) take into account connectors back shields (worst case GLENAIR type-values into brackets).

Mounting on the S/C is done by means of 10 feet and fastening by means of 10 M6 screws.

For a fully detailed mechanical interface description refers to the figure 2.1-a.

2.1.2. HSFCU unit

The mechanical interface can be summarized by assuming the HSFCU unit occupies a rectangular volume defined by its surface, its height and its mass:

- 334 (xxx) mm x 329 mm
- 330.5 (377.9) mm
- 14.28 kg

Those values (dimensions) take into account connectors back shields (worst case GLENAIR type-values into brackets).

Mounting on the S/C is done by means of 10 feet and fastening by means of 10 M6 screws.

For a fully detailed mechanical interface description refers to the figure 2.1-b.

2.2. Thermal interfaces

2.2.1. HSDCU unit

The thermal is defined by the dissipated power by the unit and the parameters, which define the heat exchange (by radiation and conduction) with its environment.

The parameters for heat exchange dimensioning are:

Dissipated Power (W)	Radiation Surfaces	Surfaces Emissivity	Feet Surfaces
40.57 - see §2.3.1 18.49	See §2.1.1	0.8	10 x 4 cm ²

2.2.2. HSFCU unit

The thermal is defined by the dissipated power by the unit and the parameters, which define the heat exchange (by radiation and conduction) with its environment.

The parameters for heat exchange dimensioning are:

Dissipated Power (W)	Radiation Surfaces	Surfaces Emissivity	Feet Surfaces
51.27 - see §2.3.1 40.75	See §2.1.2	0.8	10 x 4 cm ²

3. Electrical interfaces with the DPU

The DRCU has two kinds of interface with the DPU: one is devoted to low level command transmission (to the DRCU) for H/W configuration and housekeeping/status parameters reporting while the second is in turn devoted to data transfer from the DRCU to the DPU for further packing activities. While the command interface is slow (312kps) bi-directional with word-based protocol the data interface is fast (up to 2.5 Mbps) unidirectional with frame-based protocol.

3.1. Command interface

3.1.1. General Information

The command interface goal is manifold:

- Passing of commands from the DPU to the DRCU subsystems.
- Setting of DRCU Subsystems parameters.
- DRCU Subsystems synchronisation.

Physically it consist in 3 sets of bi-directional point to point links between the DPU and the DRCU (one link per DRCU subsystem except PSU: DCU MCU & SCU). The protocol is master-slave based, the DPU being the master.

It allows operating independently the 3 DRCU sub-units.

All commands being sent simultaneously to the 3 DRCU subsystems each subsystem recognising its own commands by means of a address inserted into the command word. In addition a broadcast code allows sending the same (broadcast) command simultaneously to the 3 DRCU sub-units.

The command format is fix and consists in a 32-bit word with 3 fields:

- a DRCU sub-unit address field.
- a command identifier field.
- a parameter field.

DRCU subsystems, if addressed individually reply with a response word with the following format:

- a field echoing the sub-unit address and the command identifier field.
- a data field which contains, either the echo of the command parameter field, or a data requested by the command (housekeeping parameter).

In the case of broadcast command, no acknowledgement is sent back by the DRCU subsystems. If the DPU requires acknowledgement it has to be carried out by sending successive acknowledgement request (specific command) to the DRCU sub-units.

3.1.2. Interface Overall Diagrams

The Command Interface diagram is given in figure 1.2-a. Main and Redundant interfaces are shown.

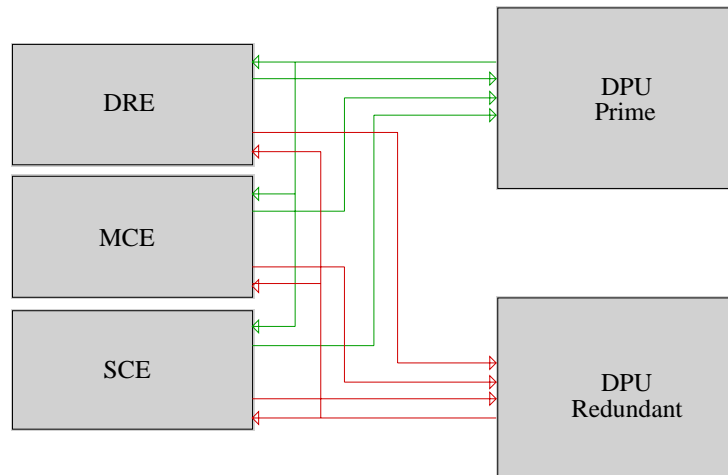


Figure 1.2-a

3.1.3. Interface Circuit

Each interface is defined by the following signals:

- a command (CMD) line - from DPU to DRU, MCU, SCU sub-units
- a response (RES) line - from each sub-unit to DPU
- a clock (CLK) line for bit synchronisation - from the DPU to DRU, MCU, SCU sub-units.

Each sub-unit implements a complete set of the above interface signals: that is the DPU implements 3 electrically independent “Command Interfaces” each having 2 transmitters + 1 receiver. However all these signals are interconnected type by type inside the DPU. In particularly the 3 RES signals are mixed according to the sub-unit address previously sent.

The interface uses the balanced lines RS422 electrical standard based on 26C31 and 26C32 transmitter and receiver type.

Complete interface functional diagram is given figures 2.3-a and 2.3-b.

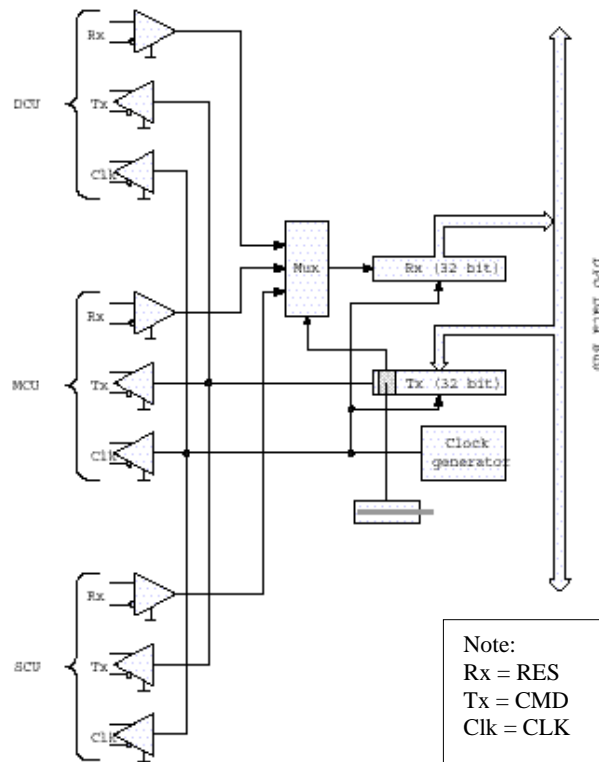


Figure 2.3-a - DPU Low Speed Interface Functional Diagram

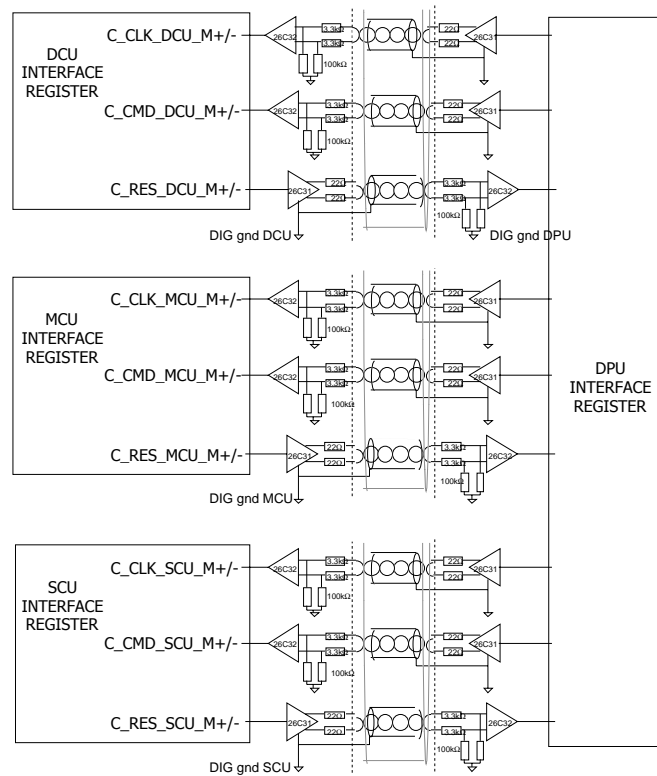


Figure 2.3-b - Electrical configuration

3.1.4. Protocol definition

3.1.4.1. Command Word

At any time after completion of a previous command/response exchange the DPU can send command words to the DRCU subsystems on the CMD line.

The 32-bit command word is divided into 5 fields as defined below:

- a 2-bit sync pattern : see table 2.4.1-a for details
- a 2-bit sub-unit address : see table 2.4.1-b for details
- a 12-bit command or command + parameter address : see table 2.4.1-c for details
- a 16-bit parameter when applicable*

*: filled with zero if the command does not require any parameter.

These 4 fields are concatenated as follow to form the 32-bits word:

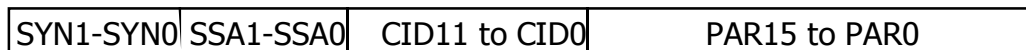


Figure 2.4.1-a - Command Word Field Structure

SYN1 - SYN0 : sync. pattern
 SSA1 - SSA0 : subsystem address
 CID11 to CID0 : command identifier
 PAR15 to PAR0 : command parameter*
 *: filled with zero if no used

Note : • MSB is transmitted first
 • SYN1 = MSB
 • PAR0 = LSB

SYN1	SYN0	Response
1	0	Yes
1	1	No ¹

Table 2.4.1-a - Sync Pattern definition

¹ Not used by DRCU S/S (equivalent to: SYN0 has no signification)

SSA1	SSA0	Subsystem Name
0	0	DCU
0	1	MCU
1	0	SCU
1	1	Broadcast Command

Table 2.4.1-b - Subsystem address allocation

Bit 11 of the Command Identifier determines the type of the command between Read (or Get) and Write (or Set). The following table explicits the R/W definition:

CID11	Command Type
1	Read
0	Write

Table 2.4.1-c - Command Identifier Structure

Note: the subsystems do not include any command buffering. If a subsystem is not able to any reason to execute a command it will reply with a negative acknowledge and the last command is definitively lost.

3.1.4.2. Response Word

The response line (RES) enables command verification and DRCU sub-system housekeeping parameters reading by the DPU.

When a “Set_parameter” command is received the subsystem responds to the DPU by transferring a command acknowledge word (positive or negative) on the response line. The positive acknowledgement is required for further command transfer after specific critical commands.

When a “get_parameter” command is received the subsystem responds to the DPU by transferring the requested housekeeping parameter. (Housekeeping parameter polling is running typically at 1Hz).

The sub-system shall respond (leading bit of the response word) within a maximum delay of tbd clock periods ($\partial T1$ – see §1.6). The DPU S/W shall include a time-out in order to recover from a lack of response and then report the anomaly.

The 32-bit command response is divided into 3 fields, which are:

- a 2-bit sync pattern (SYN0 & SYN1),
- a 2-bit acknowledge word (ACK0 & ACK1),
- a 12-bit command or parameter address echo (CID11 to CID0),
- a 16-bit parameter (PAR15 to PAR0) echo or requested housekeeping.

These 4 fields are concatenated as follow to form the 32-bits word:



If the subsystem address corresponds to the broadcast address the subsystems do not generate any response word to avoid collision at the DPU end.

Along with the “synchro. Pattern”, Command Id field and the Parameter field an acknowledge word is in place of the sub-system address field of the received command. While normally the ACK field will content a null character (00 binary) provision for “negative” acknowledge has been introduced to enable sub-system reporting in case of anomaly.

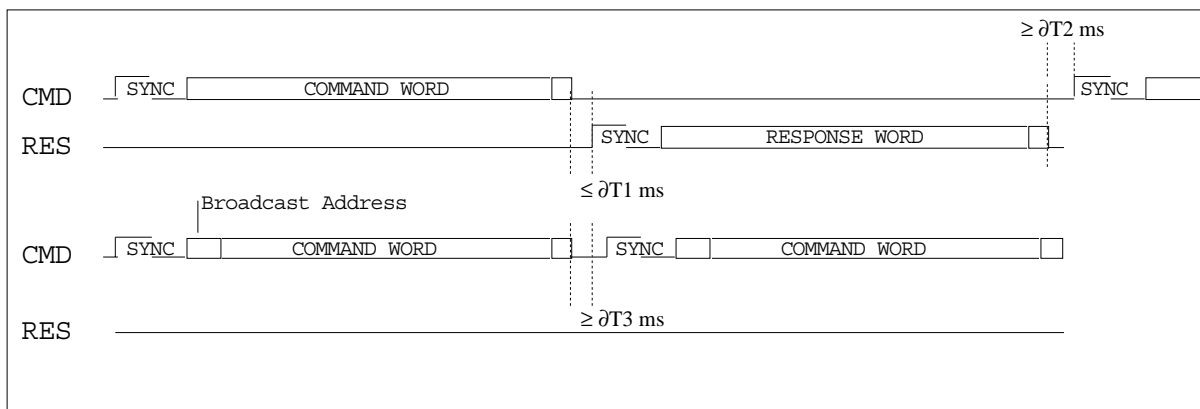
A “negative” acknowledge may result from the following reasons:

- DRCU subsystem is off
- A transmission error occurred: receiver does not recognise command identifier
- A command is not allowed in a specific subsystem status (e.g. modification of FTS scan length when mechanism is scanning): return ACK code = CID forbidden.
- The S/S H/W does not respond to the I/F H/W within a given delay: return ACK code = S/S time-out.

ACK	Command Status
00	OK
01	CID unknown
10	CID forbidden
11	S/S Time-out

3.1.4.3. Word exchange

The following figure illustrates the command interface protocol for the possible modes of operation (a “set_parameter” / “get_parameter” command and a “broadcast command”).



3.1.5. Interface Timing

3.1.5.1. Low level Timing

The CMD signal is switched on the falling edge of the CLK signal. This signal shall be sampled by the DRCU subsystem on the next rising edge of the CLK signal. To validate the command the subsystem shall identify the word sync pattern (“10” or “11”) and then check the subsystem address. If one of these conditions is not fulfilled the subsystem input logic shall stay in the “wait for command” status. In order to achieve cyclic re-synchronisation of the interface the subsystem shall implement a time-out counter, which will reset the input 32-bit register if no command is received (all input register bits contain zero) within 33 CLK periods. The RES signal shall be modified on the rising edge of the CLK signal and being sampled by the DPU on the next falling edge of the CLK signal.

For detailed interface timing see AD01.

3.1.5.2. Command timing

The following table gives interval timing value for the delay shown in §2.6.

Parameters	Symbols	Limits		Units
		Min	Max	
Command to Response Delay	$\partial T1$	6.4	102.4	μs
Response to next Command Delay	$\partial T2$	3.2	500	μs

3.1.5.3. Performance

The NRZ data rate is fixed at 312.5 kbit per second.

The command rate including both command word transmission and command response word transmission is:

$$\text{Max. Command rate} = 1 / ((3.2 \mu s \times 32) \times 2 + \partial T2) \leq 4883 \text{ commands per second.}$$

This value gives the maximum command rate supported by the protocol. Real rate will have to take into account the DPU software performance.

3.2. Command list

3.2.1.1. Command and parameter mapping

The following table shows respectively the bit mapping for CID and PAR field of a low-level command for the DCU.

CID11	CID10 to CID0	PAR15 to PAR0
R/W	Command Code	Parameter(s)

3.2.2. DRCU generic command list summary

These list refer to commands common to the 3 DRCU S/S. The execution of those commands is supported by the DRCU to DPU (CmdIF) interface H/W only.

3.2.2.1. Write only commands

Command Name	Argument(s)	Ranges List	Command verification	Execution Delay
SetTStampRst	NA	NA	Cmd Echo	

3.2.2.2. Read only commands

Command Name	Argument(s)	Ranges List	Command verification	Execution Delay
GetCmdIfStat	TBD		NA	

3.2.2.3. Read/Write Commands

Command Name	Argument(s)	Ranges List	Command verification	Execution Delay
Set/GetCmdIfCtrl	TBD		Get... cmd	

3.2.3. DRCU command description

3.2.3.1. TstampRst

Command	Unit	Code	Description
SetTstampRst	DRCU		Reset the 32-bit counter inserted in the S/S output data format.
Parameters	Location	Length	
No parameter	NA	NA	PAR15 to PAR00 = 00 hexa

3.2.3.2. CmdIfStat

Command	Unit	Code	Description
GetCmdIfStat	DCU		Get the S/S interface status
Returned Parameter(s)	Location	Length	
CmdIfStat	0	8	

3.2.3.3. CmdIfCtrl

Command	Unit	Code	Description
SetCmdIfCtrl	DCU		Set the S/S command IF control word.
Parameters	Location	Length	
CmdIfCtrl	0	8	

Command	Unit	Code	Description
GetCmdIfCtrl	DCU		Get the S/S command IF control word.
Returned Parameter(s)	Location	Length	
CmdIfCtrl	0	8	

3.2.4. DRCU parameter description

Name	Type	Size	Conversion	Limits	Description
CmdIfStat	Digital				
CmdIfCtrl	Digital				

3.2.5. DCU specific command list summary

3.2.5.1. Command and parameter mapping

The following table shows respectively the bit mapping for CID and PAR field of a low-level command for the DCU.

CID11	CID10 to CID0	PAR15 to PAR9	PAR8 to PAR0
R/W	Command Code	Channel id.	Parameter(s)

Note: for the SetPhotoOffset and SetSpectroOffset commands the *parameter* field is in turn divided into two sub-fields has described bellow.

PAR8 to PAR4	PAR3 to PAR0
Channel Number	Offset Value

3.2.5.2. Photometer write/read commands

Command Name	Argument(s)	Ranges List	Command verification	Execution Delay
SetPhotoSampFreq	Channel id Bias freq divider	NA 000 to 255	Get_... cmd	
SetPhotoBiasFreq	Channel id. Frequency divider	NA 064 to 511	Get_... cmd	
SetPhotoDemodPh	Ref. Channel id PSD Phase	00 to 03 000 to 255	Get_... cmd	
SetPhotoBiasMode	Channel id Bias gene mode	NA 000 to 255	Get_... cmd	
SetPhotoBiasAmpl	Bias Channel id. Sine amplitude	00 to 03 000 to 255	Get_... cmd	
SetPhotoJfetVss	Channel id. Vss voltage	00 to 11 000 to 255	Get_... cmd	
SetPhotoHeaterVolt	Channel id. Bias current	NA 000 to 255	Get_... cmd	
SetPhotoJfetBias	Channel id On/Off word	00 to 01 See note x	Get_... cmd	
SetPhotoOffset	Channel id. Channel number Offset value	00 to 08 00 to 32 00 to 15	Get_... cmd	

3.2.5.3. Spectrometer write/read commands

Command Name	Argument(s)	Ranges List	Command verification	Execution Delay
SetSpectroSampFreq	Channel id Bias freq divider	NA 000 to 255	Get_... cmd	
SetSpectroBiasFreq	Channel id. Frequency divider	NA 064 to 511	Get_... cmd	
SetSpectroDemodPh	Channel id PSD Phase	00 to 01 000 to 255	Get_... cmd	
SetSpectroBiasMode	Channel id Bias gene mode	NA 000 to 255	Get_... cmd	
SetSpectroBiasAmpl	Channel id. Sine amplitude	00 to 01 000 to 255	Get_... cmd	
SetSpectroHeaterPwr	Channel id. Bias current	NA 000 to 255	Get_... cmd	
SetSpectroJfetVss	Channel id. Vss voltage	00 to 02 000 to 255	Get_... cmd	
SetSpectroJfetPwr	Channel id On/Off word	00 to 01 See note x	Get_... cmd	
SetSpectroOffset	Channel id. Channel number Offset value	00 to 02 00 to 32 00 to 15	Get_... cmd	

3.2.5.4. Photometer / spectrometer common write/read commands

Command Name	Argument(s)	Ranges List	Command verification	Execution Delay
SetDataMode	Channel id. Mode id.	NA See xx	Get_... cmd TBC	
SetFrameNber	Channel id Nber of frames	NA 000 to 255	Get_... cmd TBC	
StartFrame	Channel id Run/Stop code	NA 000 / 255	Get_... cmd TBC	

3.2.5.5. Read only commands

Command Name	Argument(s)
GetHKChannel	HK Channel id.

3.2.5.6. DCU housekeeping identifier list

The following table explicits the *HK Channel id* to be transmitted as an argument of the *GetHKChannel* command.

Parameter Name	Word size (bits)	Comments	HK Channel id (hex)	Delay To Transmit
T/C 1	20-TBC	16-bit ADC + 4-bit offset	00	
T/C 2	20-TBC	16-bit ADC + 4-bit offset	01	
T/C 3	20-TBC	16-bit ADC + 4-bit offset	02	
LIA_B1_TEMP	8	LIA board 1 temperature	03	
LIA_B2_TEMP	8	LIA board 2 temperature	04	
LIA_B3_TEMP	8	LIA board 3 temperature	05	
LIA_B4_TEMP	8	LIA board 4 temperature	06	
LIA_B5_TEMP	8	LIA board 5 temperature	07	
LIA_B6_TEMP	8	LIA board 6 temperature	08	
LIA_B7_TEMP	8	LIA board 7 temperature	09	
LIA_B8_TEMP	8	LIA board 8 temperature	0A	
LIA_B9_TEMP	8	LIA board 9 temperature	0B	
LIA_B10_TEMP	8	LIA board 10 temperature	0C	
LIA_B11_TEMP	8	LIA board 11 temperature	0D	
LIA_B12_TEMP	8	LIA board 12 temperature	0E	
BIAS_TEMP	8	BIAS board temperature	0F	
DAQ_I/F_TEMP	8	DAQ_I/F board temperature	10	

3.2.6. DCU command description

3.2.6.1. Photometer

3.2.6.1.1. *PhotoSampFreq*

Command	Unit	Code	Description
SetPhotoSampFreq	DCU	00	Set the photometer & T/C bolometer sampling frequency division from the photometer bias clock
Parameters	Location	Length	
PhotoBiasDiv	0	8	

Command	Unit	Code	Description
GetPhotoSampFreq	DCU	40	Get the photometer & T/C bolometer sampling frequency division from the photometer bias clock
Returned Parameters	Location	Length	
PhotoBiasDiv	0	8	

3.2.6.1.2. *PhotoBiasFreq*

Command	Unit	Code	Description
SetPhotoBiasFreq	DCU	01	Set the photometer & T/C bolometer sine bias frequency division from the master clock
Parameters	Location	Length	
PhotoMClkDiv	0	9	Min 64; Max 511

Command	Unit	Code	Description
GetPhotoBiasFreq	DCU	41	Get the photometer & T/C bolometer sine bias frequency division from the master clock
Returned Parameters	Location	Length	
PhotoMClkDiv	0	9	Min 64; Max 511

3.2.6.1.3. *PhotoBiasMode*

Command	Unit	Code	Description
SetPhotoBiasMode	DCU	06	Set the photometer & T/C bolometer sine bias mode
Parameters	Location	Length	
PhotoBiasMode	0	8	FF=run ; 00=stop ; 01 to FE = discrete values

Command	Unit	Code	Description
GetPhotoBiasMode	DCU	46	Get the photometer & T/C bolometer sine bias mode
Parameters	Location	Length	

PhotoBiasMode	0	8	FF=run ; 00=stop ; 01 to FE= test values
---------------	---	---	--

3.2.6.1.4. DemodPh

Command	Unit	Code	Description
SetDemodPh	DCU	02	Set the P250 bolometer demodulation phase shift
Parameters	Location	Length	
PhotoPhaseShift	0	8	
PhotoBiasChannel	9	2	0=P250, 1=P350, 2=P500, 3=TC

Command	Unit	Code	Description
GetDemodPh	DCU	42	Set bolometer group demodulation phase shift
Parameters	Location	Length	
PhotoBiasChannel	9	2	0=P250, 1=P350, 2=P500, 3=TC
Returned Parameters			
PhaseShift	0	8	

3.2.6.1.5. PhotoBiasAmpl

Command	Unit	Code	Description
SetPhotoBiasAmpl	DCU	07	Set bolometer group sine bias amplitude
Parameters	Location	Length	
PhotoBiasAmpl	0	8	
PhotoBiasChannel	9	2	0=P250, 1=P350, 2=P500, 3=TC

Command	Unit	Code	Description
GetPhotoBiasAmpl	DCU	47	Set bolometer group sine bias amplitude
Parameters	Location	Length	
PhotoBiasChannel	9	2	0=P250, 1=P350, 2=P500, 3=TC
Returned Parameters	Location	Length	
PhotoBiasAmpl	0	8	

3.2.6.1.6. PhotoHeater

Command	Unit	Code	Description
SetPhotoHeaterVolt	DCU	0B	Set the photometer heater bias voltage
Parameters	Location	Length	
PhotoHeaterVolt	0	8	

Command	Unit	Code	Description
GetPhotoHeater Volt	DCU	4B	Get the photometer heater bias voltage
Parameters	Location	Length	
PhotoHeaterVolt	0	8	

3.2.6.1.7. *PhSWJfetVSS*

Command	Unit	Code	Description
SetPhSWJfetVSS	DCU	0C	Set P250 JFET source voltage
Parameters	Location	Length	
PSW_VSS (Ampl)	0	8	Analogue value = $VSS_{max} \frac{Ampl}{255}$ with $0 \leq Ampl \leq 255$
VSSChannelID	9	3	000=VSS1, 001=VSS2, 010=VSS3, 011=VSS4, 100=VSS5, 101=VSS6

Command	Unit	Code	Description
GetPhSWJfetVSS	DCU	4C	Get P250 JFET source voltage
Parameters	Location	Length	
VSSChannelID	9	3	000=VSS1, 001=VSS2, 010=VSS3, 011=VSS4, 100=VSS5, 101=VSS6
Returned Parameters			
PSW_VSS	0	8	

3.2.6.1.8. *PhMWJfetVSS*

Command	Unit	Code	Description
SetPhMWJfetVSS	DCU	12	Set P350 JFET source voltage
Parameters	Location	Length	
PMW_VSS (Ampl)	0	8	
VSSChannelID	9	2	00=VSS1, 01=VSS2, 10=VSS3, 11=VSS4,

Command	Unit	Code	Description
GetPhMWJfetVSS	DCU	52	Get P350 JFET source voltage
Parameters	Location	Length	
VSSChannelID	9	2	00=VSS1, 01=VSS2, 10=VSS3, 11=VSS4
Returned Parameters			
PMW_VSS	0	8	

3.2.6.1.9. *PhLWJfetVSS*

Command	Unit	Code	Description
SetPhLWJfetVSS	DCU	16	Set JFET source voltage
Parameters	Location	Length	
PLW_VSS (Ampl)	0	8	
VSSChannelID	9	1	0=VSS1, 1=VSS2

Command	Unit	Code	Description
Get_P500_JFET_VSS1	DCU	56	Get JFET source voltage
Parameters	Location	Length	
VSSChannelID	9	1	0=VSS1, 1=VSS2

Returned Parameters			
PSW_VSS	0	8	

3.2.6.2. SetPhSWJfetBias

Command	Unit	Code	Description
SetPhSWJfetBias	DCU	18	Switch the P250 JFETs drain voltage on/off
Parameters	Location	Length	
P250_JFET_1	0	1	
P250_JFET_2	1	1	
P250_JFET_3	2	1	
P250_JFET_4	3	1	
P250_JFET_5	5	1	
P250_JFET_6	6	1	

Command	Unit	Code	Description
GetPhSWJfetBias	DCU	58	Get the P250 JFETs drain voltage status
Parameters	Location	Length	
P250_JFET_1	0	1	
P250_JFET_2	1	1	
P250_JFET_3	2	1	
P250_JFET_4	3	1	
P250_JFET_5	5	1	
P250_JFET_6	6	1	

3.2.6.3. SetPhMLWJfetBias

Command	Unit	Code	Description
SetPhMLWJfetBias	DCU	19	Switch the P350 & P500 JFETs drain voltage on/off
Parameters	Location	Length	
P350_JFET_1	0	1	
P350_JFET_2	1	1	
P350_JFET_3	2	1	
P350_JFET_4	3	1	
P500_JFET_1	5	1	
P500_JFET_2	6	1	

Command	Unit	Code	Description
GetPhMLWJfetBias	DCU	59	Get the P350 & P500 JFETs drain voltage status
Parameters	Location	Length	
P350_JFET_1	0	1	
P350_JFET_2	1	1	
P350_JFET_3	2	1	
P350_JFET_4	3	1	
P500_JFET_1	5	1	
P500_JFET_2	6	1	

3.2.6.3.1. *SetLIAP1Offset to Set LIAP9Offset*

Command	Unit	Code	Description
SetLIAP1Offset	DCU	20	Set one LIA_P1 channel offset value
Parameters	Location	Length	
Offset_P1	0	4	
Channel_P1	4	5	

Command	Unit	Code	Description
SetLIAP2Offset	DCU	21	Set one LIA_P2 channel offset value
Parameters	Location	Length	
Offset_P2	0	4	
Channel_P2	4	5	

Command	Unit	Code	Description
SetLIAP3Offset	DCU	22	Set one LIA_P3 channel offset value
Parameters	Location	Length	
Offset_P3	0	4	
Channel_P3	4	5	

Command	Unit	Code	Description
SetLIAP4Offset	DCU	23	Set one LIA_P4 channel offset value
Parameters	Location	Length	
Offset_P4	0	4	
Channel_P4	4	5	

Command	Unit	Code	Description
SetLIAP5Offset	DCU	24	Set one LIA_P5 channel offset value
Parameters	Location	Length	
Offset_P5	0	4	
Channel_P5	4	5	

Command	Unit	Code	Description
SetLIAP6Offset	DCU	25	Set one LIA_P6 channel offset value
Parameters	Location	Length	
Offset_P6	0	4	
Channel_P6	4	5	

Command	Unit	Code	Description
SetLIAP7Offset	DCU	26	Set one LIA_P7 channel offset value
Parameters	Location	Length	
Offset_P7	0	4	
Channel_P7	4	5	

Command	Unit	Code	Description
SetLIAP8Offset	DCU	27	Set one LIA_P8 channel offset value
Parameters	Location	Length	
Offset_P8	0	4	
Channel_P8	4	5	



DRCU INTERFACE CONTROL DOCUMENT



SAp-SPIRE-CCa-25-00
Issue: 0.6
Date :1/03/02

Command	Unit	Code	Description
SetLIAP9Offset	DCU	28	Set one LIA_P9 channel offset value
Parameters	Location	Length	
Offset_P9	0	4	
Channel_P9	4	5	

3.2.6.4. Spectrometer

3.2.6.4.1. *SpectroSampFreq*

Command	Unit	Code	Description
SetSpectroSampFreq	DCU	30	Set the spectrometer bolometer sampling frequency division from the spectrometer bias clock
Parameters	Location	Length	
SpectroBiasDiv	0	8	

Command	Unit	Code	Description
GetSpectroSampFreq	DCU	70	Get the photometer & T/C bolometer sampling frequency division from the photometer bias clock
Parameters	Location	Length	
SpectroBiasDiv	0	8	

3.2.6.4.2. *SpectroBiasFreq*

Command	Unit	Code	Description
SetSpectroBiasFreq	DCU	31	Set the spectrometer bolometer sine bias frequency division from the master clock
Parameters	Location	Length	
SpectroMClkDiv	0	9	Min 64; Max 511

Command	Unit	Code	Description
GetSpectroBiasFreq	DCU	71	Get the spectrometer bolometer sine bias frequency division from the master clock
Parameters	Location	Length	
SpectroMClkDiv	0	9	Min 64; Max 511

3.2.6.4.3. *SpectroBiasMode*

Command	Unit	Code	Description
SetSpectroBiasMode	DCU	34	Set the spectrometer bolometer sine bias mode
Parameters	Location	Length	
SpectroBiasMode	0	9	FF=run ; 00=stop ; 01 to FE = test values

Command	Unit	Code	Description
GetSpectroBiasMode	DCU	74	Get the spectrometer bolometer sine bias mode
Parameters	Location	Length	
SpectroBiasMode	0	9	FF=run ; 00=stop ; 01 to FE = test values

3.2.6.4.4. *SpectroDemodPh*

Command	Unit	Code	Description
SetSpectroDemodPh	DCU	72	Set the S-SW bolometer demodulation phase shift
Parameters	Location	Length	
SpectroPhaseShift	0	8	
SpectroBiasChannel	9	1	0=SW, 1=LW

Command	Unit	Code	Description
GetSpectroDemodPh	DCU	32	Get the S-SW bolometer demodulation phase shift
Parameters	Location	Length	
SpectroBiasChannel	9	1	
Returned Parameters	Location	Length	
SpectroPhaseShift	0	8	

3.2.6.4.5. *SpectroBiasAmpl*

Command	Unit	Code	Description
SetSpectroBiasAmpl	DCU	35	Set bolometer group sine bias amplitude
Parameters	Location	Length	
PhotoBiasAmpl	0	8	
PhotoBiasChannel	9	2	0=P250, 1=P350, 2=P500, 3=TC

Command	Unit	Code	Description
GetSpectroBiasAmpl	DCU	75	Set bolometer group sine bias amplitude
Parameters	Location	Length	
PhotoBiasChannel	9	2	0=SW, 1=LW
Returned Parameters	Location	Length	
PhotoBiasAmpl	0	8	

3.2.6.4.6. *SpectroHeater*

Command	Unit	Code	Description
SetSpectroHeaterVolt	DCU	38	Set the spectrometer heater bias voltage
Parameters	Location	Length	
SpectroHeaterVolt	0	8	

Command	Unit	Code	Description
GetSpectroHeaterVolt	DCU	78	Set the spectrometer heater bias voltage
Parameters	Location	Length	
SpectroHeaterVolt	0	8	

3.2.6.4.7. *SpSWJfetVSS*

Command	Unit	Code	Description
SetSpSWJfetVSS	DCU	39	Set S-SW JFET source voltage
Parameters	Location	Length	
SSW_VSS (Ampl)	0	8	
VSSChannelID	9	1	0=VSS1, 1=VSS2

Command	Unit	Code	Description
GetSpSWJfetVSS	DCU	12	Get S-SW JFET source voltage
Parameters	Location	Length	
VSSChannelID	9	1	0=VSS1, 1=VSS2
Returned Parameters			
SSW_VSS	0	8	

3.2.6.4.8. *SpLWJfetVSS*

Command	Unit	Code	Description
GetSpLWJfetVSS	DCU	39	Get L-SW JFET source voltage
Parameters	Location	Length	
SLW_VSS	0	8	

Command	Unit	Code	Description
SetSpLWJfetVSS	DCU	7A	Set L-SW JFET source voltage
Returned Parameters	Location	Length	
SLW_VSS	0	8	

3.2.6.4.9. *SetSpSLWJfetBias*

Command	Unit	Code	Description
SetSpSLWJfetBias	DCU	3B	Switch the spectrometer JFETs drain voltage on/off
Parameters	Location	Length	
S-LW_JFET_1	0	1	
S-SW_JFET_1	1	1	
S-SW_JFET_2	2	1	

Command	Unit	Code	Description
GetSpSLWJfetBias	DCU	7B	Get the spectrometer JFETs drain voltage status
Parameters	Location	Length	
S-LW_JFET_1	0	1	
S-SW_JFET_1	1	1	
S-SW_JFET_2	2	1	

3.2.6.4.10. *SetLIAS1Offset to Set LIAS3Offset*

Command	Unit	Code	Description
SetLIAS1Offset	DCU	3C	Set one LIA_S1 channel offset value
Parameters	Location	Length	
Offset_S1	0	4	
Channel_S1	4	5	

Command	Unit	Code	Description
SetLIAS2Offset	DCU	3D	Set one LIA_S2 channel offset value
Parameters	Location	Length	
Offset_S2	0	4	
Channel_S2	4	5	

Command	Unit	Code	Description
SetLIAS3Offset	DCU	3E	Set one LIA_S3 channel offset value
Parameters	Location	Length	
Offset_S3	0	4	
Channel_S3	4	5	

3.2.6.4.11. *SetDataMode*

Command	Unit	Code	Description
SetDataMode	DCU	49	Set modes
Parameters	Location	Length	
DataMode	0	5	Bit 4 : 0=acquisition ; 1=offset Bit 3 : 0=normal ; 1=test Bit 2 to 0 : 0=photometer ; 1=P250 ; 2=P350&T/C ; 3=P500 4=specrometer ; 5=S-LW ; 6=S-SW

Command	Unit	Code	Description
GetDataMode	DCU	69	Get mode
Parameters	Location	Length	
DataMode	0	5	

3.2.6.4.12. *SetFrameNber*

Command	Unit	Code	Description
SetFrameNber	DCU	2A	Set photometer frames acquisition mode
Parameters	Location	Length	
frame	0	8	0=continues; 1 to 255 =number of frames

Command	Unit	Code	Description
GetFrameNber	DCU	6A	Get photometer frames acquisition mode
Parameters	Location	Length	
frame	0	8	0=continues; 1 to 255 =number of frames

3.2.6.4.13. *StartFrame*

Command	Unit	Code	Description
SetstartFrame	DCU	2B	
Parameters	Location	Length	
StartFrame	0	1	1=run ; 0=stop

Command	Unit	Code	Description
GetStartFrame	DCU	6B	
Parameters	Location	Length	
Startframe	0	1	1=run ; 0=stop

3.2.7. DCU parameters description

3.2.7.1. Photometer

Name	Type	Size	Conversion	Limits	Description
Div_photo_sampl	Analogue	8	$F_{sampl} = \frac{F_{bias}}{2.(Div_photo_sampl)}$	0 to 255	
Div_photo_bias	Analogue	9	$F_{BIAS} = \frac{xxMHz}{2.256.(Div_photo_bias)}$	64 to 511	
Mode_photo_bias	Discrete	8	FF=run sine 00 to FE= DC level	0 to 254	
Phase_shift_P250	Analogue	8	$Ph_{xx} = \frac{360^\circ(Phase_shift_xx)}{255}$	0 to 255	
Phase_shift_P350	Analogue	8	$Ph_{xx} = \frac{360^\circ(Phase_shift_xx)}{255}$	0 to 255	
Phase_shift_P500	Analogue	8	$Ph_{xx} = \frac{360^\circ(Phase_shift_xx)}{255}$	0 to 255	
Phase_shift_T/C	Analogue	8	$Ph_{xx} = \frac{360^\circ(Phase_shift_xx)}{255}$	0 to 255	
Ampl_P250	Analogue	8	$Vb_{xx} = \frac{Vbmax.(Ampl_xx)}{255}$	0 to 255	
Ampl_P350	Analogue	8	$Vb_{xx} = \frac{Vbmax.(Ampl_xx)}{255}$	0 to 255	
Ampl_P500	Analogue	8	$Vb_{xx} = \frac{Vbmax.(Ampl_xx)}{255}$	0 to 255	
Ampl_T/C	Analogue	8	$Vb_{xx} = \frac{Vbmax.(Ampl_xx)}{255}$	0 to 255	

Name	Type	Size	Conversion	Limits	Description
Amp_photo_heater	Analogue	8	$V_{h_{xx}} = \frac{V_{hmax}(Ampl_xx)}{255}$	0 to 255	
Ampl_P250_VSS1	Analogue	8	$VSS_{xx} = \frac{VSSmax.(Ampl_xx)}{255}$	0 to 255	
Ampl_P250_VSS2	Analogue	8	$VSS_{xx} = \frac{VSSmax.(Ampl_xx)}{255}$	0 to 255	
Ampl_P250_VSS3	Analogue	8	$VSS_{xx} = \frac{VSSmax.(Ampl_xx)}{255}$	0 to 255	
Ampl_P250_VSS4	Analogue	8	$VSS_{xx} = \frac{VSSmax.(Ampl_xx)}{255}$	0 to 255	
Ampl_P250_VSS5	Analogue	8	$VSS_{xx} = \frac{VSSmax.(Ampl_xx)}{255}$	0 to 255	
Ampl_P250_VSS6	Analogue	8	$VSS_{xx} = \frac{VSSmax.(Ampl_xx)}{255}$	0 to 255	
Ampl_P350_VSS1	Analogue	8	$VSS_{xx} = \frac{VSSmax.(Ampl_xx)}{255}$	0 to 255	
Ampl_P350_VSS2	Analogue	8	$VSS_{xx} = \frac{VSSmax.(Ampl_xx)}{255}$	0 to 255	
Ampl_P350_VSS3	Analogue	8	$VSS_{xx} = \frac{VSSmax.(Ampl_xx)}{255}$	0 to 255	
Ampl_P350_VSS4	Analogue	8	$VSS_{xx} = \frac{VSSmax.(Ampl_xx)}{255}$	0 to 255	
Ampl_P500_VSS1	Analogue	8	$VSS_{xx} = \frac{VSSmax.(Ampl_xx)}{255}$	0 to 255	
Ampl_P500_VSS2	Analogue	8	$VSS_{xx} = \frac{VSSmax.(Ampl_xx)}{255}$	0 to 255	
P250_JFET_1	Discrete	1	0=off ; 1=on		
P250_JFET_2	Discrete	1	0=off ; 1=on		
P250_JFET_3	Discrete	1	0=off ; 1=on		
P250_JFET_4	Discrete	1	0=off ; 1=on		
P250_JFET_5	Discrete	1	0=off ; 1=on		
P250_JFET_6	Discrete	1	0=off ; 1=on		
P350_JFET_1	Discrete	1	0=off ; 1=on		
P350_JFET_2	Discrete	1	0=off ; 1=on		
P350_JFET_3	Discrete	1	0=off ; 1=on		
P350_JFET_4	Discrete	1	0=off ; 1=on		
P500_JFET_1	Discrete	1	0=off ; 1=on		
P500_JFET_2	Discrete	1	0=off ; 1=on		

Name	Type	Size	Conversion	Limits	Description
Channel_P1	Discrete	5	Channel 1 to 32 of LIA_P1		
Channel_P2	Discrete	5	Channel 1 to 32 of LIA_P2		
Channel_P3	Discrete	5	Channel 1 to 32 of LIA_P3		
Channel_P4	Discrete	5	Channel 1 to 32 of LIA_P4		
Channel_P5	Discrete	5	Channel 1 to 32 of LIA_P5		
Channel_P6	Discrete	5	Channel 1 to 32 of LIA_P6		
Channel_P7	Discrete	5	Channel 1 to 32 of LIA_P7		
Channel_P8	Discrete	5	Channel 1 to 32 of LIA_P8		
Channel_P9	Discrete	5	Channel 1 to 32 of LIA_P9		
Offset_P1	Analogue	4			
Offset_P2	Analogue	4			
Offset_P3	Analogue	4			
Offset_P4	Analogue	4			
Offset_P5	Analogue	4			
Offset_P6	Analogue	4			
Offset_P7	Analogue	4			
Offset_P8	Analogue	4			
Offset_P9	Analogue	4			

3.2.7.2. Spectrometer

Name	Type	Size	Conversion	Limits	Description
Div_spectro_sampl	Analogue	8	$F_{sampl} = \frac{F_{bias}}{2 \cdot (Div_photo_sampl)}$	0 to 255	
Div_spectro_bias	Analogue	9	$F_{BIAS} = \frac{xxMHz}{2.256 \cdot (Div_photo_bias)}$	64 to 511	
Mode_spectro_bias	Discrete	8	FF=run sine 00 to FE= DC level	0 to 254	
Phase_shift_S-SW	Analogue	8	$Ph_{xx} = \frac{360^\circ \cdot (Phase_shift_xx)}{255}$	0 to 255	
Phase_shift_S-LW	Analogue	8	$Ph_{xx} = \frac{360^\circ \cdot (Phase_shift_xx)}{255}$	0 to 255	
Ampl_S-SW	Analogue	8	$Vb_{xx} = \frac{Vbmax \cdot (Ampl_xx)}{255}$	0 to 255	
Ampl_S-LW	Analogue	8	$Vb_{xx} = \frac{Vbmax \cdot (Ampl_xx)}{255}$	0 to 255	
Amp_spectro_heater	Analogue	8	$Vh_{xx} = \frac{Vhmax \cdot (Ampl_xx)}{255}$	0 to 255	
Ampl_S-LW_VSS1	Analogue	8	$VSS_{xx} = \frac{VSSmax \cdot (Ampl_xx)}{255}$	0 to 255	
Ampl_S-SW_VSS1	Analogue	8	$VSS_{xx} = \frac{VSSmax \cdot (Ampl_xx)}{255}$	0 to 255	
Ampl_S-SW_VSS2	Analogue	8	$VSS_{xx} = \frac{VSSmax \cdot (Ampl_xx)}{255}$	0 to 255	
S-LW_JFET_1	Discrete	1	0=off ; 1=on		
S-SW_JFET_1	Discrete	1	0=off ; 1=on		
S-SW_JFET_2	Discrete	1	0=off ; 1=on		
Channel_S1	Discrete	5	Channel 1 to 24 of LIA_S1		
Channel_S2	Discrete	5	Channel 1 to 24 of LIA_S2		
Channel_S3	Discrete	5	Channel 1 to 24 of LIA_S3		
Offset_S1	Analogue	4	Offset_S1		
Offset_S2	Analogue	4	Offset_S2		
Offset_S3	Analogue	4	Offset_S3		

Name	Type	Size	Conversion	Limits	Description
mode	Discrete	5	00= acquisition photometer 01= acquisition P250 02= acquisition P350 03= acquisition P500 04= acquisition Spectrometer 05= acquisition S-SW 06= acquisition S-LW 08= Test Pattern photometer 0C= Test Pattern Spectrometer 10= Automatic offset photometer set 14= Automatic offset spectrometer set 18= Get offset photometer 1C= Get offset spectrometer Other = do nothing		
frame	Discrete	8	0=continues; 1 to 255 = number of frames		
start	Discrete	1	1=run ; 0=stop		

3.2.8. DCU typical commanding scenarios

3.2.8.1. DCU Configuration

Steps	Command	Parameters	Comment
1	Set_photo_bias_freq	Div_photo_bias	With a 10 MHz master clock for a photometer bias frequency of 199,3Hz; Div_photo_sampl = 98
2	Set_photo_Samp_freq	Div_photo_sampl	For a photometer sampling frequency of 15,3Hz; Div_photo_sampl=13
3	Set_P250_demod_sht	Phase_shift_P250	The optimised phases shift for each possible bias frequency must be set in a table during the ground calibration (447cases of each type of BDA)
4	Set_P350_demod_sht	Phase_shift_P350	
5	Set_P500_demod_sht	Phase_shift_P500	
6	Set_T/C_demod_sht	Phase_shift_T/C	
7	Set_P250_bias_ampl	Ampl_P250	Optimised amplitude could be determine during the ground calibration
8	Set_P350_bias_ampl	Ampl_P350	
9	Set_P500_bias_ampl	Ampl_P500	
10	Set_T/C_bias_ampl	Ampl_T/C	
11	Set_P250_JFET_VSS1	Ampl_P250_VSS1	Optimised amplitude could be determine during the ground calibration
12	Set_P250_JFET_VSS2	Ampl_P250_VSS2	
13	Set_P250_JFET_VSS3	Ampl_P250_VSS3	
14	Set_P250_JFET_VSS4	Ampl_P250_VSS4	
15	Set_P250_JFET_VSS5	Ampl_P250_VSS5	
16	Set_P250_JFET_VSS6	Ampl_P250_VSS6	
17	Set_P350_JFET_VSS1	Ampl_P350_VSS1	
18	Set_P350_JFET_VSS2	Ampl_P350_VSS2	
19	Set_P350_JFET_VSS3	Ampl_P350_VSS3	
20	Set_P350_JFET_VSS4	Ampl_P350_VSS4	
21	Set_P500_JFET_VSS1	Ampl_P500_VSS1	
22	Set_P500_JFET_VSS2	Ampl_P500_VSS2	
23	Set_P250_JFET_PWR	P250_JFET	All JFET on (P250_JFET=111111)
24	Set_P350&500_JFET_PWR	P350&500_JFET	All JFET on (P350&500_JFET=111111)
25	Set_photo_bias_mode	Mode_photo_bias	Mode = EF
26	Set_photo_heater_ampl	Ampl_photo_heater	Start heat the photometer JFET modules Set Ampl_photo_heater with xx
	Wait XX ms		
27	Set_photo_heater_ampl	Ampl_photo_heater	Stop heat the photometer JFET modules Set Ampl_photo_heater with 00

Steps	Command	Parameters	Comment
28	Set_spectro_bias_freq	Div_spectro_bias	With a 10 MHz master clock for a photometer bias frequency of 160,1Hz; Div_photo_sampl=122
29	Set_spectro_Sampl_freq	Div_spectro_sampl	For a photometer sampling frequency of 80 Hz; Div_photo_sampl=2
30	Set_S-SW_demod_sht	Phase_shift_S-SW	The optimised phases shift for each possible bias frequency must be set in a table during the ground calibration (447cases of each type of BDA)
31	Set_S-LW_demod_sht	Phase_shift_S-LW	
32	Set_S-SW_bias_ampl	Ampl_S-SW	Optimised amplitude could be determine during the ground calibration
33	Set_S-LW_bias_ampl	Ampl_S-LW	
34	Set_S-LW_JFET_VSS1	Ampl_S-LW_VSS1	Optimised amplitude could be determine during the ground calibration
35	Set_S-SW_JFET_VSS1	Ampl_S-SW_VSS1	
36	Set_S-SW_JFET_VSS2	Ampl_S-SW_VSS2	
37	Set_spectro_JFET_PWR	S-LW&S-SW_JFET	All JFET on (S-LW&S-SW_JFET =111111)
38	Set_spectro_bias_mode	Mode_spectro_bias	Mode = EF
39	Set_spectro_heater_ampl	Ampl_spectro_heater	Start heat the spectrometer JFET modules Set Ampl_spectro_heater with xx
	Wait XX ms		
40	Set_spectro_heater_ampl	Ampl_spectro_heater	Stop heat the spectrometer JFET modules Set Ampl_spectro_heater with 00

So after all this steps the spectrometer and the photometer JFETs are running.
All the sine bias parameters and acquisition parameters are loaded.
And the bolometers are bias receive a differential 0V.
So we could choose to run the spectrometer or the photometer.

3.2.8.2. Photometer Configuration

Steps	Command	Parameters	Comment
1	Set_photo_bias_mode	Mode_photo_bias	Mode = FF
	Wait XX ms		After this time the system must be stable

3.2.8.3. Photometer offset setting

3.2.8.3.1. Automatic

Steps	Command	Parameters	Comment
1	Set_start_mode	start	Start=0
2	Set_photo_mode	Mode	Mode = 10
3	Set_start_mode	start	Start=1
	Wait XX ms		All the offset are set
4	Set_start_mode	start	Start=0
5	Set_photo_mode	Mode	Mode = 18
6	Set_start_mode	start	Start=1
	Wait XX ms		All the offset are send to DPU

3.2.8.3.2. Manual

Steps	Command	Parameters	Comment
1	Set_LIA_P1_Offset	Channel_P1 Offset_P1	Channel_P1=0 Offset_P1=X
-	-	-	-
32	Set_LIA_P1_Offset	Channel_P1 Offset_P1	Channel_P1=31 Offset_P1=X
17	Set_LIA_P2_Offset	Channel_P2 Offset_P2	Channel_P2=0 Offset_P2=X
-	-	-	-
32	Set_LIA_P2_Offset	Channel_P2 Offset_P2	Channel_P2=31 Offset_P2=X
-	-	-	-
-	-	-	-
288	Set_LIA_P9_Offset	Channel_P9 Offset_P9	Channel_P9=31 Offset_P9=X

3.2.8.4. Photometer acquisition

3.2.8.4.1. *Continue*

Steps	Command	Parameters	Comment
1	Set_start_mode	start	Start=0
2	Set_mode	Mode	Mode = 00
3	Set_frames_photo	frame	Frame=0
4	Set_start_mode	start	Start=1

3.2.8.4.2. *Discrete*

Steps	Command	Parameters	Comment
1	Set_start_mode	start	Start=0
2	Set_mode	Mode	Mode = 00
3	Set_frames_photo	frame	Frame=x (1 to 255 = number of frames)
4	Set_start_mode	start	Start=1

3.2.8.5. Spectrometer Configuration

Steps	Command	Parameters	Comment
1	Set_Spectro_bias_mode	Mode_Spectro_bias	Mode = FF
	Wait XX ms		After this time the system must be stable

3.2.8.6. Spectrometer offset setting

3.2.8.6.1. *Automatic*

Steps	Command	Parameters	Comment
1	Set_start_mode	start	Start=0
2	Set_Spectro_mode	Mode	Mode = 14
3	Set_start_mode	start	Start=1
	Wait XX ms		All the offset are set
4	Set_start_mode	start	Start=0
5	Set_Spectro_mode	Mode	Mode = 1C
6	Set_start_mode	start	Start=1
	Wait XX ms		All the offset are send to DPU

3.2.8.6.2. *Manual*

Steps	Command	Parameters	Comment
1	Set_LIA_S1_Offset	Channel_S1 Offset_S1	Channel_S1=0 Offset_S1=X

-	-	-	-
32	Set_LIA_S1_Offset	Channel_S1 Offset_S1	Channel_S1=23 Offset_S1=X
17	Set_LIA_S2_Offset	Channel_S2 Offset_S2	Channel_S2=0 Offset_S2=X
-	-	-	-
32	Set_LIA_S2_Offset	Channel_S2 Offset_S2	Channel_S2=23 Offset_S2=X
-	-	-	-
-	-	-	-
288	Set_LIA_S3_Offset	Channel_S3 Offset_S3	Channel_S3=23 Offset_S3=X

3.2.8.7. Spectrometer acquisition

3.2.8.7.1. *Continue*

Steps	Command	Parameters	Comment
1	Set_start_mode	start	Start=0
2	Set_mode	Mode	Mode = 04
4	Set_start_mode	start	Start=1

3.2.9. MCU specific command list summary

3.2.9.1. Command and parameter mapping

The following table shows respectively the bit mapping for CID and PAR field of a low-level command for the DCU.

CID11	CID10 to CID9	CID9 to CID0	PAR15 to PAR0
R/W	Axis Id	Command Code	Parameter(s)

Axis	Axis Id
All	00
SMEC	01
Chopper	10
Jiggle	11

Axis identifier definition

3.2.9.2. SMEC Commands

3.2.9.2.1. Initialisation set commands

Com. Mnemonic	Com. Name	Action
000h	SetEncoderPwr	Power on the encoder led. The led has 8 levels encoded on 3 bits from 0 to max.
001h	SetLVDTPwr	Power on/off the LVDT oscillator (Boolean)
002h	SetLoopMode	Open or close loop mode selection <u>Parameter definition:</u> 00 = Loop opened (0020000h) 01 = Loop closed on Back EMF(0020001h) 10 = Loop closed on LVDT(0020002h) 11 = Loop closed on optical encoder(0020003h)
003h	SetLaunchLatch1	Engage/disengage Launch Latch 1 (0 or 1)
004h	SetLaunchLatch2	Engage/disengage Launch Latch 2 (0 or 1)
005h	SetInitMotion	Starts the motion initialisation procedure (0 or 1)

3.2.9.2.2. General configuration commands

080h	SetScanStart	specifies the scan starting position
880h	GetScanStart	Reads the start position

081h	SetScanSpeed	specifies the velocity to reach the position target (scan speed)
881h	GetScanSpeed	
082h	SetScanEnd	
882h	GetStartScan	0: Scan commanded to stop 1: Scan commanded to run
083h	Update	Cancelled, the update shall be taken into account on each SetStartScan Command
084h	SetScanMode	0: motion stopped 1: position step 2: sawtooth motion 3: triangular motion
085h	SetScanNumber	Specifies the number of scans to be performed

Starts/Stops the scan. (start of trajectory generation and the closed loop control scan according to Scan parameters)

3.2.9.2.3. Control loop and trajectory tuning specific commands

Command Mnemonic	Command Name	Action
100h	SetKpHigh	Proportional gain of the digital PID controller
101h	SetKpLow	
102h	SetKdHigh	Derivative Gain of the digital PID controller
103h	SetKdLow	
104h	SetDerivFilterHigh	Sets the filtering time constant to calculate the derivative term.
105h	SetDerivFilterLow	
106h	SetKiHigh	Integral gain of the digital PID controller
107h	SetKiLow	
108h	SetIntegrationLimit	Loads/Reads the integration saturation for the integral compensation of the servo
109h	Set PositionErrorLimit	determine/reads the position error value that causes an error on the servo
10Ah	SetNotchParamHigh	Parameters for notch filtering of mechanical modes. Here is the pole compensation of the first parasitic mechanical mode
10Bh	SetNotchParamLow	

3.2.9.2.4. HK specific get commands

980h	GetSmecStatus	reads the Activity Status Register. This Status Register can only be read and no bit can be cleared since the word is refreshed by the chipset.
981h	GetActualPosition	returns the last absolute position
982h	GetActualVelocity	Get the instantaneous (20 Hz filtered) velocity
983h	GetMeanSpeed	Actual scan mean measured speed Allows to verify the velocity scan error
984h	GetMeanPositionError	Returns the mean position error over a scan

3.2.9.3. CHOP COMMANDS

To be Completed

3.2.9.3.1. Initialisation set commands

Com. Mnemonic	Com. Name	Parameter / Action
200h	SetSensorPwr	On/Off (0 /1) : Power on magnetoresistive sensor.
201h	Reserve	
202h	SetChopLoopMode	Open or close loop mode selection <u>Parameter definition:</u> 00 = Loop opened (2020000h) 01 = Loop closed on Back EMF(2020001h) 10 = Loop closed on magnetoresistive(2020002h)
203h	SetChopLaunchLatch	Engage/disengage Launch Latch (0 or 1)

3.2.9.3.2. General configuration commands

280h	SetPosition0	specifies the y0 position step
A80h	GetPosition0	
281h	SetPosition1	specifies the y1 position step
A81h	GetPosition1	
282h	SetChopPeriod	Specifies the chopping cycle
A82h	GetChopPeriod	
284h	SetChopMode (alias MoveChop)	0: Chopper commanded to stop 1: Chopper commanded to run in step mode 2: Chopper commanded to run in toggle mode
285h	SetScanNumber	Specifies the number of scans to be performed

3.2.9.3.3. Control loop and trajectory tuning specific commands

Command Mnemonic	Command Name	Action
300h	SetKpHigh	Proportional gain of the digital PID controller
301h	SetKpLow	
302h	SetKdHigh	Derivative Gain of the digital PID controller
303h	SetKdLow	
304h	SetDerivFilterHigh	Sets the filtering time constant to calculate the derivative term.
305h	SetDerivFilterLow	
306h	SetKiHigh	Integral gain of the digital PID controller
307h	SetKiLow	
308h	SetIntegrationLimit	Loads/Reads the integration saturation for the integral compensation of the servo

309h	Set PositionErrorLimit	determine/reads the position error value that causes an error on the servo
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3.2.9.3.4. *HK specific get commands*

B80h	GetChopStatus	reads the Activity Status Register. This Status Register can only be read and no bit can be cleared since the word is refreshed by the chipset.
B81h	GetActualPosition	returns the last absolute position
B82h	GetMeanPositionError	Returns the mean position error over a scan

TO BE COMPLETED

3.2.9.4. **JIGGLE COMMANDS**

Idem than Chopper commands with command mnemonics + 200h

3.2.9.5. **Telemetry & Trace configuration commands**

#	Parameter	Action
600h	SetTelemetry	Activate or inhibits the possible predefined packets to be sent
601h	SetTelemetrySampling	Set the sampling rate of the telemetry packets
602h	Set TraceSampling	Sets the time period, expressed in ms, between successive trace points
603h	SetTraceBuffer	Sets the length of the trace data buffer.
604h	SetTraceParam#1	parameter identifier to be put in the trace frame up to 6 values In the trace frame, the 2 first data are the data name and the data sampling.
605h	SetTraceParam#2	
606h	SetTraceParam#3	
607h	SetTraceParam#4	
608h	SetTraceParam#5	
609h	SetTraceParam#6	

3.2.9.6. **HK and miscellaneous commands**

680h	SetDPUPollingTime	Set a maximum time between 2 commands before a IO Error code is generated, meaning a communication problem
E81h	ReadMemory	Returns the value of whatever DSP memory mapping

3.2.10. MCU typical commanding scenarios

3.2.10.1. SMEC Commanding scenarios

3.2.10.1.1. SMEC initialisation procedure

Previous State: The Main Power supply switch on

	Command to be sent	Action	Remarks - Error switch to degraded mode procedure
1	SetEncoderPwr(on)	Power on the optical encoder led	
2	GetEncoderSignalsStatus()	Verify if the optical encoder works properly	Goto procedure #2 'Initialisation in degraded mode'
3	SetLoopMode (on optical encoder)	Close the loop on optical encoder	It is recommended to move the SMEC while latched thanks to the latch clearance of few 10 microns
4	GetSMEC Status()	Verify if the loop is closed properly	
5	SetLVDTPwr(on)	Power on the LVDT Oscillator	
6	GetLVDTStatus	Verify the oscillator works properly	
7	SetLaunchLatch1(off)	Disengage Launch Latch 1	
8	GetLaunchLatch1Status	Verify the first launch latch disengagement	
9	SetLaunchLatch2(off)	Engage/disengage Launch Latch 2	
10	GetLaunchLatch2Status	Verify the launch latch #2 disengagement	
11	SetInitMotion(on)	Starts the motion initialisation procedure (0 or 1)	Consists in applying the mechanism on mechanical stop for absolute position reference capture
12	GetSMECStatus	Verify if the motion is properly initialised	

AT THIS STAGE, THE SMEC_m IS INITIALISED, WAITING IN CLOSED LOOP CONTROL AT HOME POSITION. Next possible State: operating the SMEC in nominal mode.

3.2.10.2. Commanding the SMEC

#	Command to be sent	Parameter	Remark
1	SetScanMode	0	SMEC stopped
2	SetScanSpeed	Scan Speed	
3	SetScanNumber	Number of scan	
4	SetScanStart	number of counts from home at which to start scientific part of scan	
5	SetScanEnd	number of counts from home position of end of scientific part of scan	
6	SetTelemetrySampling	Bit related to SMEC telemetry packet and encoder count sample value	
7	SetTelemetry	Bit related to SMEC telemetry packet = 1	generate a SMEC data sample at every i counts
8	SetScanMode	on: can be sawtooth,triangular,step	The motion is started with set up parameters

- If the scan is running while configuration is set up, parameters shall not be taken into account and the command reply shall indicate an error to DPU
- This operation should be followed by a flush_fifo command to the DPU
- Scan quality information should be put in memory for reading as housekeeping data (it will need to be associated with a scan number)

3.2.10.3. Commanding the Chopper

Chopping can be commanded in the MCU in the following ways:
CHOP(y0,y1)

3.2.10.3.1. Automatic

#	Command to be sent	Parameter	Remark
1	SetChopPosition0	(y0)	
2	SetChopPosition1	(y1)	
3	SetChopPeriod	Period	
4	SetTelemetrySample	Sample interval	
5	SetChopSamples	number of samples per chop position	
6	SetChopCycles	Number of steps 0 = indefinite chopping	
7	SetChopMode	1 : Automatic Step mode	Update parameters and starts chopping

3.2.10.3.2. Command Driven

#	Command to be sent	Parameter	Remark
1	SetChopPosition0	y0	
2	SetChopPosition1	y1	
3	SetChopPeriod	Period	
4	SetTelemetrySample	Sample interval	
5	SetChopSamples	number of samples per chop position	
6	SetChopMode	2 :Toggle Mode	Update parameters and starts chopping
7	SetChopMode	2 :Toggle Mode	Move the chopper
8	SetChopMode	2 : Toggle Mode	Move the chopper
9	SetChopMode	Toggle Mode	Move the chopper
	etc		

3.2.10.4. Commanding the Jiggle and Chopper

Jiggle is commanded in the following way:

Input: z, y0,y1 for each jiggle position

JIGGLEANDCHOP(z,y0,y1,.....)

#	Command to be sent	Parameter	Remark
1	SetJigPosition	z	
2	SetChopPosition0	y0	
3	SetChopPosition1	y1	
4	SetJigMode	1 :Step Mode	This updates parameters and Move jiggle
5	SetChopMode	1 :Step Mode	Move the chopper
6	SetJigPosition	z'	
7	SetChopPosition0	y0'	
8	SetChopPosition1	y1'	
9	SetJigMode	1 :Step Mode	This updates parameters and Move jiggle
10	SetChopMode	1 :Step Mode	Move the chopper
	Etc....		

3.2.11. SCU specific command list summary

3.2.11.1. Command and parameter mapping

The following table shows respectively the bit mapping for CID and PAR field of a low-level command for the DCU.

CID11	CID10 to CID0	PAR15 to PAR0
R/W	Command Code	Parameter(s)

3.2.11.2. Write/read commands

Command Name	Argument(s)	Ranges List	Command verification	Execution Delay

3.2.11.3. Read only commands

Command Name	Argument(s)	Ranges List	Command verification	Execution Delay

3.2.12. SCU command description

3.2.12.1. Write only commands

3.2.12.1.1. *FrRequest*

Command	Unit	Code	Description
SetFrRequest	SCU	tbd	Initiate frame sequence transfer
Parameters	Location	Length	
NA			

3.2.12.2. Read/Write commands

3.2.12.2.1. *FrameRate*

Command	Unit	Code	Description
SetFramRate	SCU	tbd	Set frame rate
Parameters	Location	Length	
FramRate	0	8	

Command	Unit	Code	Description
GetFramRate	SCU	tbd	Return frame rate
Returned Parameters	Location	Length	
FramRate	0	8	

3.2.12.2.2. *SeqLength*

Command	Unit	Code	Description
SetSeqLength	SCU	tbd	Set number of frame per sequence (0 meaning infinit)
Parameters	Location	Length	
SeqLength	0	8	

Command	Unit	Code	Description
GetFramRate	SCU	tbd	Return number of frame per sequence (0 meaning infinit)
Returned Parameters	Location	Length	
SeqLength	0	8	

3.2.12.2.3. TempOnOff

Command	Unit	Code	Description
SetTempOnOff	SCU	tbd	Set sub K and FPU temperature probes on/off
Parameters	Location	Length	
TempOnOff	0	8	12bits on/off word

Command	Unit	Code	Description
GetTempOnOff	SCU	tbd	Return sub K and FPU temperature probes on/off
Returned Parameters	Location	Length	
TempOnOff	0	8	12bits on/off word

3.2.12.2.4. SubKpFreq

Command	Unit	Code	Description
SetSubKpFreq	SCU	tbd	Set sub K temperature probe bias frequency
Parameters	Location	Length	
SubKpFreq	0	8	

Command	Unit	Code	Description
GetSubKpFreq	SCU	tbd	Return sub K temperature probe bias frequency
Returned Parameters	Location	Length	
SubKpFreq	0	8	

3.2.12.2.5. DCDCOnOff

Command	Unit	Code	Description
SetDCDCOnOff	SCU	tbd	Set DCDC on/off command word
Parameters	Location	Length	
DCDCOnOff	0	5	

Command	Unit	Code	Description
GetSubKpFreq	SCU	tbd	Return DCDC on/off command word
Returned Parameters	Location	Length	
DCDCOnOff	0	5	

3.2.12.2.6. LPHBias1

Command	Unit	Code	Description
SetLPHBias1	SCU	tbd	Set value of current applied to Low Power Heater 1

Parameters	Location	Length	
LPHBias1	0	12	Current value

Command	Unit	Code	Description
GetLPHBias1	SCU	tbd	Get voltage across Low Power Heater 1
Returned Parameters	Location	Length	
LPHBias1	0	12	Heater voltage analog value

3.2.12.2.7. LPHBias2

Command	Unit	Code	Description
SetLPHBias2	SCU	tbd	Set value of current applied to Low Power Heater 2
Parameters	Location	Length	
LPHBias2	0	12	Current value

Command	Unit	Code	Description
GetLPHBias2	SCU	tbd	Get voltage across Low Power Heater 2
Returned Parameters	Location	Length	
LPHBias2	0	12	Heater voltage analog value

3.2.12.2.8. LPHBias3

Command	Unit	Code	Description
SetLPHBias3	SCU	tbd	Set value of current applied to Low Power Heater 3
Parameters	Location	Length	
LPHBias3	0	12	Current value

Command	Unit	Code	Description
GetLPHBias3	SCU	tbd	Get voltage across Low Power Heater 3
Returned Parameters	Location	Length	
LPHBias3	0	12	Heater voltage analog value

3.2.12.2.9. HPHBias4

Command	Unit	Code	Description
SetHPHBias4	SCU	tbd	Set value of current applied to High Power Heater 4 (Sorption Pump)
Parameters	Location	Length	
HPHBias4	0	12	Current value

Command	Unit	Code	Description
GetHPHBias4	SCU	tbd	Get voltage across High Power Heater 4 (Sorption Pump)
Returned Parameters	Location	Length	
HPHBias4	0	12	Heater voltage analog value

3.2.12.2.10. StimBias1

Command	Unit	Code	Description
SetStimBias1	SCU	tbd	Set value of current applied to Stimulus Source 1 (xxxxx)
Parameters	Location	Length	
StimBias1	0	12	Current value

Command	Unit	Code	Description
GetStimBias1	SCU	tbd	Get current in Stimulus Source 1 (xxxxx)
Returned Parameters	Location	Length	
StimBias1	0	12	Stimulus source current analog value

3.2.12.2.11. StimBias2

Command	Unit	Code	Description
SetStimBias2	SCU	tbd	Set value of current applied to Stimulus Source 2 (xxxxx)
Parameters	Location	Length	
StimBias2	0	12	Current value

Command	Unit	Code	Description
GetStimBias2	SCU	tbd	Get current in Stimulus Source 2 (xxxxx)
Returned Parameters	Location	Length	
StimBias2	0	12	Stimulus source current analog value

3.2.12.2.12. StimBias3

Command	Unit	Code	Description
SetStimBias3	SCU	tbd	Set value of current applied to Stimulus Source 3 (xxxxx)
Parameters	Location	Length	
StimBias3	0	12	Current value

Command	Unit	Code	Description
GetStimBias3	SCU	tbd	Get current in Stimulus Source 3 (xxxxx)
Returned Parameters	Location	Length	
StimBias3	0	12	Stimulus source current analog value

3.2.12.3. Read only commands

3.2.12.3.1. StimVolt1

Command	Unit	Code	Description
GetStimVolt1	SCU	tbd	Get voltage across Stimulus Source 1
Parameters	Location	Length	
StimVolt1	0	12	Voltage analog value

3.2.12.3.2. StimVolt2

Command	Unit	Code	Description
GetStimVolt2	SCU	tbd	Get voltage across Stimulus Source 2
Parameters	Location	Length	
StimVolt2	0	12	Voltage analog value

3.2.12.3.3. StimVolt3

Command	Unit	Code	Description
GetStimVolt3	SCU	tbd	Get voltage across Stimulus Source 3
Parameters	Location	Length	
StimVolt3	0	12	Voltage analog value

3.2.12.3.4. ScuCHTp05

Command	Unit	Code	Description
GetScuCHTp05	SCU	tbd	Return value of +05V of SCU/CCHK&TEMP
Returned Parameter(s)	Location	Length	
ScuCHTp05	0	12	Voltage analog value

3.2.12.3.5. ScuCHTp09

Command	Unit	Code	Description
GetScuCHTp09	SCU	tbd	Return value of +09V of SCU/CCHK&TEMP
Returned Parameter(s)	Location	Length	
ScuCHTp09	0	12	Voltage analog value

3.2.12.3.6. ScuCHTn09

Command	Unit	Code	Description
GetScuCHTn09	SCU	tbd	Return value of -09V of SCU/CCHK&TEMP
Returned Parameter(s)	Location	Length	
ScuCHTn09	0	12	Voltage analog value

3.2.12.3.7. FpuTemp01

Command	Unit	Code	Description
GetFpuTemp01	SCU	tbd	Return FPU temperature probe 01 current value (pr_name)
Returned Parameter(s)	Location	Length	
	0	12	Probe current analog value (function of the temperature)

3.2.12.3.8. FpuTemp02

Command	Unit	Code	Description
GetFpuTemp02	SCU	tbd	Return FPU temperature probe 02 current value (pr_name)
Returned Parameter(s)	Location	Length	
FpuTemp02	0	12	Probe current analog value (function of the temperature)

3.2.12.3.9. FpuTemp03

Command	Unit	Code	Description
GetFpuTemp03	SCU	tbd	Return FPU temperature probe 03 current value (pr_name)
Returned Parameter(s)	Location	Length	
FpuTemp03	0	12	Probe current analog value (function of the temperature)

3.2.12.3.10. FpuTemp04

Command	Unit	Code	Description
GetFpuTemp04	SCU	tbd	Return FPU temperature probe 04 current value (pr_name)
Returned Parameter(s)	Location	Length	
FpuTemp04	0	12	Probe current analog value (function of the temperature)

3.2.12.3.11. FpuTemp05

Command	Unit	Code	Description
GetFpuTemp05	SCU	tbd	Return FPU temperature probe 05 current value (pr_name)
Returned Parameter(s)	Location	Length	
FpuTemp05	0	12	Probe current analog value (function of the temperature)

3.2.12.3.12. FpuTemp06

Command	Unit	Code	Description
GetFpuTemp06	SCU	tbd	Return FPU temperature probe 06 current value (pr_name)
Returned Parameter(s)	Location	Length	
FpuTemp06	0	12	Probe current analog value (function of the temperature)

3.2.12.3.13. FpuTemp07

Command	Unit	Code	Description
GetFpuTemp07	SCU	tbd	Return FPU temperature probe 07 current value (pr_name)
Returned Parameter(s)	Location	Length	
FpuTemp07	0	12	Probe current analog value (function of the temperature)

3.2.12.3.14. FpuTemp08

Command	Unit	Code	Description
GetFpuTemp01	SCU	tbd	Return FPU temperature probe 01 current value (pr_name)
Returned Parameter(s)	Location	Length	
FpuTemp01	0	12	Probe current analog value (function of the temperature)

3.2.12.3.15. FpuTemp09

Command	Unit	Code	Description
GetFpuTemp01	SCU	tbd	Return FPU temperature probe 01 current value (pr_name)
Returned Parameter(s)	Location	Length	
FpuTemp01	0	12	Probe current analog value (function of the temperature)

3.2.12.3.16. FpuTemp10

Command	Unit	Code	Description
GetFpuTemp01	SCU	tbd	Return FPU temperature probe 01 current value (pr_name)
Returned Parameter(s)	Location	Length	
FpuTemp01	0	12	Probe current analog value (function of the temperature)

3.2.12.3.17. FpuTemp11

Command	Unit	Code	Description
GetFpuTemp01	SCU	tbd	Return FPU temperature probe 01 current value (pr_name)
Returned Parameter(s)	Location	Length	
FpuTemp01	0	12	Probe current analog value (function of the temperature)

3.2.12.3.18. FpuTemp12

Command	Unit	Code	Description
GetFpuTemp01	SCU	tbd	Return FPU temperature probe 01 current value (pr_name)
Returned Parameter(s)	Location	Length	
FpuTemp01	0	12	Probe current analog value (function of the temperature)

3.2.12.3.19. FpuTemp13

Command	Unit	Code	Description
GetFpuTemp01	SCU	tbd	Return FPU temperature probe 01 current value (pr_name)
Returned Parameter(s)	Location	Length	
FpuTemp01	0	12	Probe current analog value (function of the temperature)

3.2.12.3.20. FpuTemp14

Command	Unit	Code	Description
GetFpuTemp01	SCU	tbd	Return FPU temperature probe 01 current value (pr_name)
Returned Parameter(s)	Location	Length	
FpuTemp01	0	12	Probe current analog value (function of the temperature)

3.2.12.3.21. FpuTemp15

Command	Unit	Code	Description
GetFpuTemp01	SCU	tbd	Return FPU temperature probe 01 current value (pr_name)
Returned Parameter(s)	Location	Length	
FpuTemp01	0	12	Probe current analog value (function of the temperature)

3.2.12.3.22. FpuTemp16

Command	Unit	Code	Description
GetFpuTemp01	SCU	tbd	Return FPU temperature probe 01 current value (pr_name)
Returned Parameter(s)	Location	Length	
FpuTemp01	0	12	Probe current analog value (function of the temperature)

3.2.12.3.23. SubKTempP

Command	Unit	Code	Description
GetSubKTempP	SCU	tbd	Return subK temperature probe voltage value (pr_name)
Returned Parameter(s)	Location	Length	
SubKTempP	0	12	Probe voltage analog value (function of the temperature)

3.2.12.3.24. CcuTempRd

Command	Unit	Code	Description
GetCcuTempRd	SCU	tbd	Return CCHK board temperature sensor value
Returned Parameter(s)	Location	Length	
CcuTempRd	0	12	Probe current analog value (function of the temperature)

3.2.12.3.25. TcuTempRd

Command	Unit	Code	Description
GetTcuTempRd	SCU	tbd	Return TEMP board temperature sensor value
Returned Parameter(s)	Location	Length	
TcuTempRd	0	12	Probe current analog value (function of the temperature)

3.2.12.3.26. PsuTempRd

Command	Unit	Code	Description
Get PsuTempRd	SCU	tbd	Return PSU board temperature sensor value
Returned Parameter(s)	Location	Length	
PsuTempRd	0	12	Probe current analog value (function of the temperature)

3.2.13. SCU parameters description

Name	Type	Size	Conversion	Limits	Description
FramRate	Analogue	8		0 to 255	
SeqLength					
TempOnOff	Discrete				
SubKpFreq					
DCDCOnOff					
LPHBias1					
LPHBias2					
LPHBias3					
HPHBias4					
StimBias1					
StimBias2					
StimBias3					
StimVolt1					
StimVolt2					
StimVolt3					
ScuCHTp05					
ScuCHTp09					
ScuCHTn09					
FpuTemp01					
FpuTemp02					
FpuTemp03					
FpuTemp04					
FpuTemp05					
FpuTemp06					
FpuTemp07					
FpuTemp08					
FpuTemp09					
FpuTemp10					
FpuTemp11					
FpuTemp12					
FpuTemp13					
FpuTemp14					
FpuTemp15					
FpuTemp16					
SubKTempP					
CcuTempRd					
TcuTempRd					
PsuTempRd					

3.2.14. SCU typical commanding scenarios

3.3. Data Interface

3.3.1. General Information

The Data Interface is dedicated to data transfer from subsystem to DPU. Three independent “Data Interface” are required allowing simultaneous DRCU data transfer.

This interface is unidirectional: data are transferred from the DRCU sub-units to the DPU acquisition electronics. Fixed data packets are defined according to sub-unit operating mode. This data packet contents both scientific data (i.e. bolometer signal) and/or housekeeping parameters.

3.3.2. Overall Interface Diagram

The Command Interface diagram is given in figure 2.2. Prime and Redundant interfaces are shown.

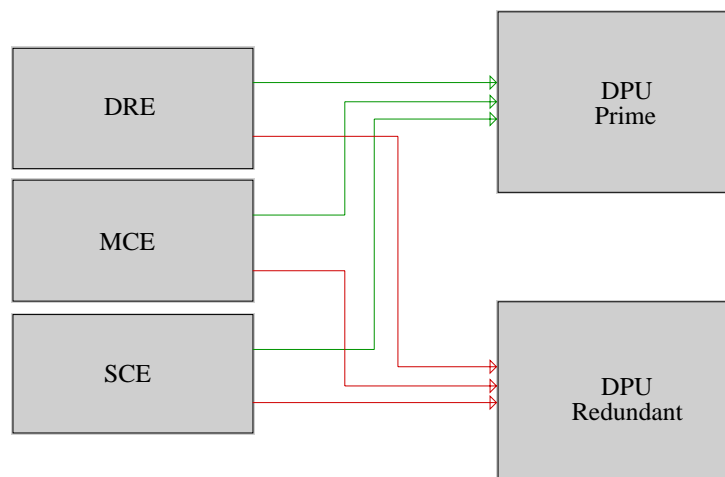


Figure 3.2-a

3.3.3. Interface Circuit

The interface is a synchronous serial link based on one data line (DTA) associated to a clock line (CLK) for bit synchronisation and a gate line (GAT) for word synchronisation. Each sub-unit implements a complete set of signals: that is the DPU implements 3 totally independent Data interfaces each having 3 receivers (as shown by figure 3.3-a).

The interface uses the balanced line RS422 electrical standard based on 26C31 and 26C32 transmitter and receiver type respectively.

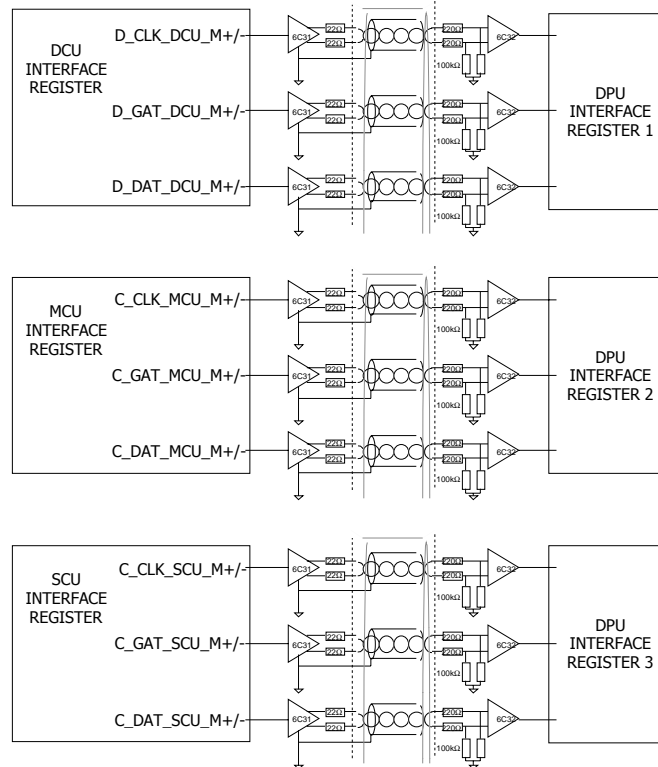


Figure 3.3-a - Electrical configuration

3.3.4. Word definition

Word definition is subsystem dependent. Data are currently 16-bit encoded and correspond to bolometer signal, mechanisms motion parameters, instrument temperature and all other housekeeping channels.

In order to deal with the latch-up effect of the analogue to digital converters (see RD01), which cause the generation of wrong data until the converter recovers full performances, a specific “invalid” data identifier is defined. This avoids the DRCU to transfer unpredictable packet length following a cosmic ray impact on the converter and later on-ground misanalysis.

These data words are defined as follow:

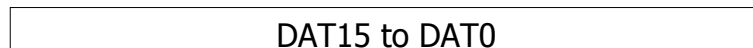


Figure 3.4-a - Data Word Definition

DAT15 to DAT0: data

Note: • MSB (DAT15) is transmitted first

3.3.5. General Frame Definition

Data frame length and structure are defined regarding the DRCU sub-unit and its mode of operation. The sub-systems data structures are encapsulated into a common frame structure as described bellow (except two MCU modes).

The frame is composed of:

- a length word
- a frame ID
- a data structure
- **a frame time**
- a check word

3.3.5.1. Length

The “length” field (16 bits) is placed at the head of the frame. It indicates the number of 16-bit words of the frame (including all the fields). Along with the “frame ID” and “check word” fields this field allows frame consistency checking by the receiver unit.

3.3.5.2. Frame ID

The “frame ID” field is a 16-bit word following the “length” word. Along with the “length” field and the “check” word it allows data consistency checking. In case the check fails the DPU takes action to resynchronise with the data stream.

The purpose of the frame ID is to enable identifying to frame after packing by the DPU. A specific code is allocated for each frame type of each DRCU S/S. The following table shows the identifier allocation:

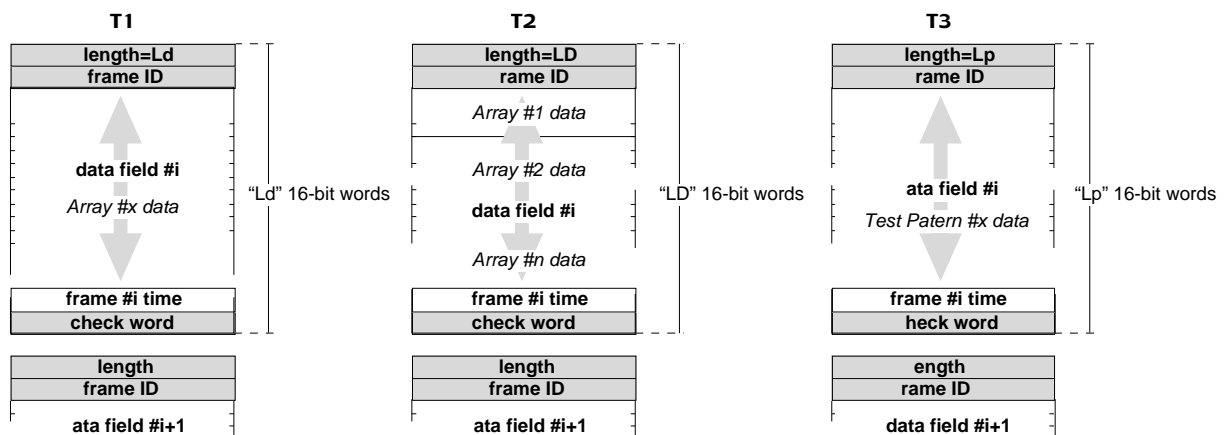
UNIT	Frame Type	Frame ID (hex)
DCU	Ph Full Array	00
DCU	Sp Full array	01
DCU	P-SW	02
DCU	P-MW	03
DCU	P-LW	04
DCU	S-SW	05
DCU	S-LW	06
DCU	Test Pattern	07
DCU	Ph Offset	08
DCU	Sp Offset	09
DCU	Not Allocated	0A-0F
MCU	SMEC scan	10
MCU	SMEC Step	11
MCU	Chop	12

UNIT	Frame Type	Frame ID (hex)
MCU	Jiggle	13
MCU	Trace	14
MCU	Test Pattern	15
MCU	Not Allocated	16-1F
SCU	HSK	20
SCU	Test Pattern	21
SCU	Not Allocated	22-2F

3.3.5.3. Data structure

3.3.5.3.1. DCU Frames Definition

The four frame structures of the DCU are defined as follow:



The following cross table shows the corresponding Frame ID for each DCU configuration status:

DCU Configuration	Frame ID	Frame Format	Length
Photo. Full Array	00	T2	301
Spectro. Full Array	01	T2	69
P-SW	02	T1	
P-MW	03	T1	
P-LW	04	T1	301
S-SW	05	T1	
S-LW	06	T1	
Test Pattern	07	T3	301
Ph Offset	08	T2	301
Sp Offset	09	T2	69

Remind: the DCU data interface configuration is configured by means of the “SetDataMode” command.

For the T2 frame length it assumed:

- the photometer is composed of 288 bolometers
- the spectrometer is composed of 56 bolometers
- along with the imaging bolometers we transfer 3 thermometry bolometers

3.3.5.3.2. *Photometer Full Array pixel arrangement*

ADC1	ADC2	ADC3	ADC4	ADC5	ADC6
CH1/LIA_P1	CH16/LIA_P2	CH1/LIA_P4	CH16/LIA_P5	CH1/LIA_P7	CH16/LIA_P8
CH16/LIA_P1	CH1/LIA_P3	CH16/LIA_P4	CH1/LIA_P6	CH16/LIA_P7	CH1/LIA_P9
CH1/LIA_P2	CH16/LIA_P3	CH1/LIA_P5	CH16/LIA_P6	CH1/LIA_P8	CH16/LIA_P9
CH2/LIA_P1	CH17/LIA_P2	CH2/LIA_P4	CH17/LIA_P5	CH2/LIA_P7	CH17/LIA_P8
CH17/LIA_P1	CH2/LIA_P3	CH17/LIA_P4	CH2/LIA_P6	CH17/LIA_P7	CH2/LIA_P9
CH2/LIA_P2	CH17/LIA_P3	CH2/LIA_P5	CH17/LIA_P6	CH2/LIA_P8	CH17/LIA_P9
CH3/LIA_P1	CH18/LIA_P2	CH3/LIA_P4	CH18/LIA_P5	CH3/LIA_P7	CH18/LIA_P8
CH18/LIA_P1	CH3/LIA_P3	CH18/LIA_P4	CH3/LIA_P6	CH18/LIA_P7	CH3/LIA_P9
CH3/LIA_P2	CH18/LIA_P3	CH3/LIA_P5	CH18/LIA_P6	CH3/LIA_P8	CH18/LIA_P9
CH4/LIA_P1	CH19/LIA_P2	CH4/LIA_P4	CH19/LIA_P5	CH4/LIA_P7	CH19/LIA_P8
CH19/LIA_P1	CH4/LIA_P3	CH19/LIA_P4	CH4/LIA_P6	CH19/LIA_P7	CH4/LIA_P9
CH4/LIA_P2	CH19/LIA_P3	CH4/LIA_P5	CH19/LIA_P6	CH4/LIA_P8	CH19/LIA_P9
CH5/LIA_P1	CH20/LIA_P2	CH5/LIA_P4	CH20/LIA_P5	CH5/LIA_P7	CH20/LIA_P8
CH20/LIA_P1	CH5/LIA_P3	CH20/LIA_P4	CH5/LIA_P6	CH20/LIA_P7	CH5/LIA_P9
CH5/LIA_P2	CH20/LIA_P3	CH5/LIA_P5	CH20/LIA_P6	CH5/LIA_P8	CH20/LIA_P9
CH6/LIA_P1	CH21/LIA_P2	CH6/LIA_P4	CH21/LIA_P5	CH6/LIA_P7	CH21/LIA_P8
CH21/LIA_P1	CH6/LIA_P3	CH21/LIA_P4	CH6/LIA_P6	CH21/LIA_P7	CH6/LIA_P9
CH6/LIA_P2	CH21/LIA_P3	CH6/LIA_P5	CH21/LIA_P6	CH6/LIA_P8	CH21/LIA_P9
CH7/LIA_P1	CH22/LIA_P2	CH7/LIA_P4	CH22/LIA_P5	CH7/LIA_P7	CH22/LIA_P8
CH22/LIA_P1	CH7/LIA_P3	CH22/LIA_P4	CH7/LIA_P6	CH22/LIA_P7	CH7/LIA_P9
CH7/LIA_P2	CH22/LIA_P3	CH7/LIA_P5	CH22/LIA_P6	CH7/LIA_P8	CH22/LIA_P9
CH8/LIA_P1	CH23/LIA_P2	CH8/LIA_P4	CH23/LIA_P5	CH8/LIA_P7	CH23/LIA_P8
CH23/LIA_P1	CH8/LIA_P3	CH23/LIA_P4	CH8/LIA_P6	CH23/LIA_P7	CH8/LIA_P9
CH8/LIA_P2	CH23/LIA_P3	CH8/LIA_P5	CH23/LIA_P6	CH8/LIA_P8	CH23/LIA_P9
CH9/LIA_P1	CH24/LIA_P2	CH9/LIA_P4	CH24/LIA_P5	CH9/LIA_P7	CH24/LIA_P8
CH24/LIA_P1	CH9/LIA_P3	CH24/LIA_P4	CH9/LIA_P6	CH24/LIA_P7	CH9/LIA_P9
CH9/LIA_P2	CH24/LIA_P3	CH9/LIA_P5	CH24/LIA_P6	CH9/LIA_P8	CH24/LIA_P9
CH10/LIA_P1	CH25/LIA_P2	CH10/LIA_P4	CH25/LIA_P5	CH10/LIA_P7	CH25/LIA_P8
CH25/LIA_P1	CH10/LIA_P3	CH25/LIA_P4	CH10/LIA_P6	CH25/LIA_P7	CH10/LIA_P9
CH10/LIA_P2	CH25/LIA_P3	CH10/LIA_P5	CH25/LIA_P6	CH10/LIA_P8	CH25/LIA_P9
CH11/LIA_P1	CH26/LIA_P2	CH11/LIA_P4	CH26/LIA_P5	CH11/LIA_P7	CH26/LIA_P8
CH26/LIA_P1	CH11/LIA_P3	CH26/LIA_P4	CH11/LIA_P6	CH26/LIA_P7	CH11/LIA_P9
CH11/LIA_P2	CH26/LIA_P3	CH11/LIA_P5	CH26/LIA_P6	CH11/LIA_P8	CH26/LIA_P9
CH12/LIA_P1	CH27/LIA_P2	CH12/LIA_P4	CH27/LIA_P5	CH12/LIA_P7	CH27/LIA_P8

CH27/LIA_P1	CH12/LIA_P3	CH27/LIA_P4	CH12/LIA_P6	CH27/LIA_P7	CH12/LIA_P9
CH12/LIA_P2	CH27/LIA_P3	CH12/LIA_P5	CH27/LIA_P6	CH12/LIA_P8	CH27/LIA_P9
CH13/LIA_P1	CH28/LIA_P2	CH13/LIA_P4	CH28/LIA_P5	CH13/LIA_P7	CH28/LIA_P8
CH28/LIA_P1	CH13/LIA_P3	CH28/LIA_P4	CH13/LIA_P6	CH28/LIA_P7	CH13/LIA_P9
CH13/LIA_P2	CH28/LIA_P3	CH13/LIA_P5	CH28/LIA_P6	CH13/LIA_P8	CH28/LIA_P9
CH14/LIA_P1	CH29/LIA_P2	CH14/LIA_P4	CH29/LIA_P5	CH14/LIA_P7	CH29/LIA_P8
CH29/LIA_P1	CH14/LIA_P3	CH29/LIA_P4	CH14/LIA_P6	CH29/LIA_P7	CH14/LIA_P9
CH14/LIA_P2	CH29/LIA_P3	CH14/LIA_P5	CH29/LIA_P6	CH14/LIA_P8	CH29/LIA_P9
CH15/LIA_P1	CH30/LIA_P2	CH15/LIA_P4	CH30/LIA_P5	CH15/LIA_P7	CH30/LIA_P8
CH30/LIA_P1	CH15/LIA_P3	CH30/LIA_P4	CH15/LIA_P6	CH30/LIA_P7	CH15/LIA_P9
CH15/LIA_P2	CH30/LIA_P3	CH15/LIA_P5	CH30/LIA_P6	CH15/LIA_P8	CH30/LIA_P9
CH16/LIA_P1	CH31/LIA_P2	CH16/LIA_P4	CH31/LIA_P5	CH16/LIA_P7	CH31/LIA_P8
CH31/LIA_P1	CH16/LIA_P3	CH31/LIA_P4	CH16/LIA_P6	CH31/LIA_P7	CH16/LIA_P9
CH16/LIA_P2	CH31/LIA_P3	CH16/LIA_P5	CH31/LIA_P6	CH16/LIA_P8	CH31/LIA_P9

3.3.5.3.3. *Spectrometer Full Array pixel arrangement*

ADC1	ADC2	ADC3	ADC4	ADC5	ADC6
CH1/LIA_S1	CH13/LIA_S1	CH1/LIA_S2	CH13/LIA_S2	CH1/LIA_S3	CH13/LIA_S3
CH2/LIA_S1	CH14/LIA_S1	CH2/LIA_S2	CH14/LIA_S2	CH2/LIA_S3	CH14/LIA_S3
CH3/LIA_S1	CH15/LIA_S1	CH3/LIA_S2	CH15/LIA_S2	CH3/LIA_S3	CH15/LIA_S3
CH4/LIA_S1	CH16/LIA_S1	CH4/LIA_S2	CH16/LIA_S2	CH4/LIA_S3	CH16/LIA_S3
CH5/LIA_S1	CH17/LIA_S1	CH5/LIA_S2	CH17/LIA_S2	CH5/LIA_S3	CH17/LIA_S3
CH6/LIA_S1	CH18/LIA_S1	CH6/LIA_S2	CH18/LIA_S2	CH6/LIA_S3	CH18/LIA_S3
CH7/LIA_S1	CH19/LIA_S1	CH7/LIA_S2	CH19/LIA_S2	CH7/LIA_S3	CH19/LIA_S3
CH8/LIA_S1	CH20/LIA_S1	CH8/LIA_S2	CH20/LIA_S2	CH8/LIA_S3	CH20/LIA_S3
CH9/LIA_S1	CH21/LIA_S1	CH9/LIA_S2	CH21/LIA_S2	CH9/LIA_S3	CH21/LIA_S3
CH10/LIA_S1	CH22/LIA_S1	CH10/LIA_S2	CH22/LIA_S2	CH10/LIA_S3	CH22/LIA_S3
CH11/LIA_S1	CH23/LIA_S1	CH11/LIA_S2	CH23/LIA_S2	CH11/LIA_S3	CH23/LIA_S3
CH12/LIA_S1	CH24/LIA_S1	CH12/LIA_S2	CH24/LIA_S2	CH12/LIA_S3	CH24/LIA_S3

The last word of the data field has a specific meaning: it informs the DPU of occurrence of analog to digital converter latch-up or S/S to DPU interface fault and then of the risk to pack corrupted data. When a flag or more is set the related data of the current frame have to be discarded during on-ground data processing.

The meaning of this word depends on the data interface mode.

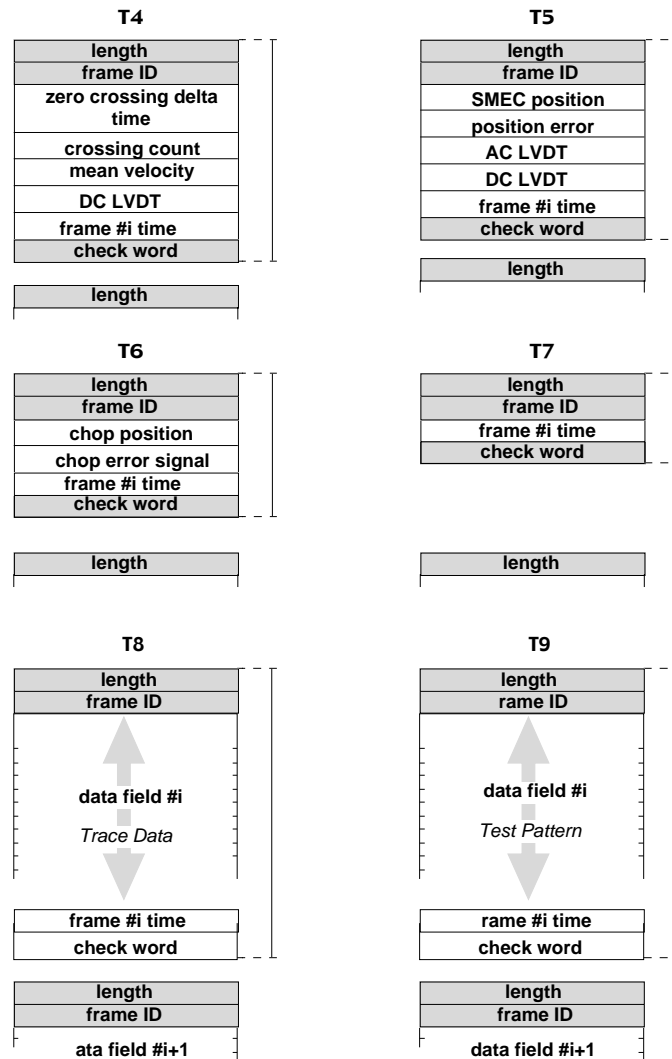
See table above for details

DCU Configuration	Frame Format	# of flags
Photo. Array Subset	T1	1
Spectro. Array Subset	T1	1
Photo. Full Array	T2	6

Spectro. Full Array	T2	2
Test Pattern	T3	0
Photo. Offset table	T2	0
Spectro Offset table	T2	0

3.3.5.3.4. MCU Frame Definition

The four frame structures of the MCU are defined as follow:



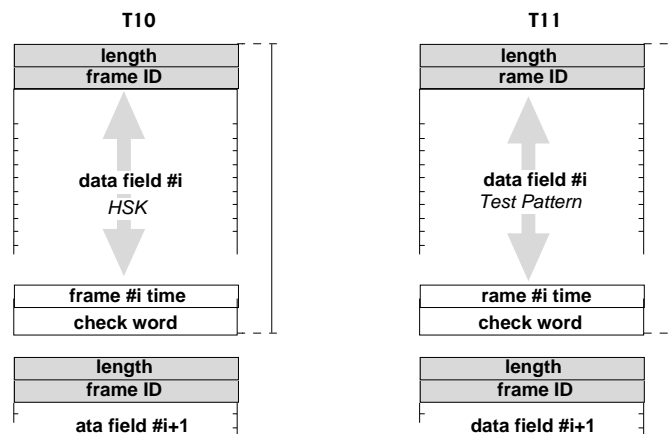
The following cross table shows the corresponding Frame ID for each MCU configuration status:

Configuration Status	Frame ID	Frame Format	Length
SMEC Scan	10	T4	8
SMEC step	11	T5	7
Chop	12	T6	7
Jiggle	13	T7	5
Trace	14	T8	TBD

Test Pattern	15	T9	TBD
--------------	----	----	-----

3.3.5.3.5. SCU Frame Definition

The two frame structures of the SCU are defined as follow:



The following cross table shows the corresponding Frame Structure Type for each SCU configuration status:

Configuration Status	Frame Format	Frame ID	Length
HSK	T10	20	
Test Pattern	T11	21	

The last word of the data field has a specific meaning: it informs the DPU of occurrence of analog to digital converter latch-up or S/S to DPU interface fault and then of the risk to pack corrupted data. When a flag or more is set the related data of the current frame have to be discarded during on-ground data processing.

The meaning of this word depends on the data interface mode.

See table above for details

SCU Configuration	FST	# of flags
HSK	T8	1
Test Pattern	T9	1

3.3.5.4. Frame time

The “frame time” field follows the data structure area. It is a 32-bit word filled with the contents of the subsystem “time tag” counters. In order to keep data frame synchronisation for the 3 subsystems this counter is driving by a single clock signal and reset by a broadcast

command. The clock is derived from the CLK line of the Command interface and the resolution is then 3.2 μ s. The full range of the counter is then above 13740 s (229 min); this means the DPU have to sent the reset command at least every 229 min in order to keep synchronisation between the 3 DRCU sub-systems.

The subsystem time counter shall be effectively reset within 10 (tbc) μ s from the command reception and with a maximum skew between subsystems of 3 μ s.

3.3.5.5. Check word

The “check” word ends the data frame. Along with the “header” and “length” field it allows frame consistency checking. It is calculated by exclusive or of all frame words.

3.3.6. Test pattern

The purpose of this mode is to generate variable and predictable digital data for test and verification activities. Instead of transmitting a fixed pattern it implements a pseudo random generator.

When in test pattern mode the DRCU interface control logic substitutes the data with a pseudo-random sequence generated by a 16-bit linear feedback shift register (see RD2). The DRCU unit features 3 independent LFSR each corresponding to a data interface. Additionally each LFSR is initialised with a specific vector as show bellow:

3.3.7. Interface Timing

For detailed interface timing see AD01.

3.3.8. Timing Performance

The NRZ data rate is fixed at 1 Mbits per second (max is 2.5 Mbps).

Max data rate = $1 / (1 \mu\text{s} \times (16+1)) = 58,823$ data per second

3.3.9. Data Rate Estimations

4. Electrical interfaces with S/C

Electrical interfaces with the S/C are of two kinds. One is connected to a PCDU port for DRCU power supply while the second is connected to RTU for shutter sub-system monitoring.

4.1. PCDU interface

4.1.1. Electrical characteristics

The following table gives a summary of this interface:

Connector Id(s)	HS_FCU_J05 HS_FCU_J06
Pin number(s)	2, 7
Interface type	Input
Signal type	DC voltage
Voltage range (nominal)	26 to 29 V
Voltage range (operating)	0 to 35 V
Maximum Power (average)	91.84 W
Current range	See Power Profile §4.1.2
Reference pin(s) (return line)	4, 8
Corresponding command(s)	NA
Source impedance ²	< 200 mΩ for f < 1kHz ≤ 50 Ω for f > 1MHz

For further dynamic performance refer to AD1 §5.9.5

4.1.2. Power profile

Mode	Power Consumption (W)	Comment
Observing Photometer(average)	91.84	Nominal operation
Observing Spectrometer (average)	56.77	
Recycling	34.51	Nominal operation
Stand-by	33.88	Nominal operation
MCU boot	38.34	DRCU power on

² See LISN characteristics (§9.5.6.9) for detailed description

5. Interface with FPU

The DRCU units interface with the FPU by means of a large number of analog interfaces. Those interfaces are related to the detector, mechanism, cooler, calibrators and thermometer sub-systems respectively.

5.1. DCU interface

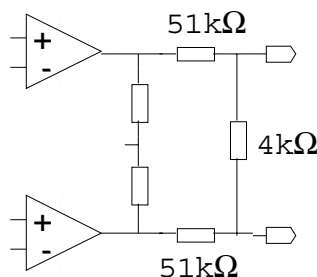
5.1.1. Seeing Bolometer Bias Interface

The bolometer bias interface consists of 6 individual balanced ports has described here after.

5.1.1.1. Electrical characteristics

Connector Id(s)	HSDCU_J29 to HSDCU_J32
Pin number(s)	
Interface type	Output
Signal type	AC voltage
Voltage Range	0 to 100 mV
Current range	tbd
Transmission mode	Balanced
Reference pin(s) (return line)	See
Source impedance	< 4 k Ω
Load impedance (range)	
AC characteristics	
Waveform	Sine
Frequency	50 – 300 Hz
Transition Time	NA
Corresponding command(s) <i>Photometer:</i>	SetPhotoBiasFreq SetPhotoBiasAmpl
Corresponding command(s) <i>Spectrometer:</i>	SetSpectroBiasFreq SetSpectroBiasAmpl

5.1.1.2. Interface circuitry

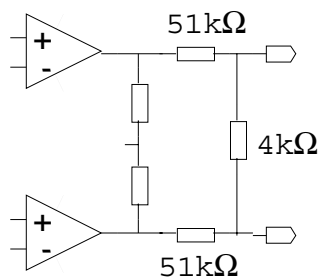


5.1.2. T/C Bolometer Bias Interface

5.1.2.1. Electrical characteristics

Connector Id(s)	HSDCU_Jxx HSDCU_Jxx
Pin number(s)	
Interface type	Output
Signal type	AC voltage
Voltage Range	0 to 500 mV
Current range	tbd
Transmission mode	Balanced
Reference pin(s) (return line)	
Source impedance	< 4 k Ω
Load impedance (range)	
AC characteristics	
Waveform	Sine
Frequency	50 – 300 Hz
Transition Time	NA
Corresponding command(s)	Set....BiasFreq Set....BiasAmpl

5.1.2.2. Interface circuitry

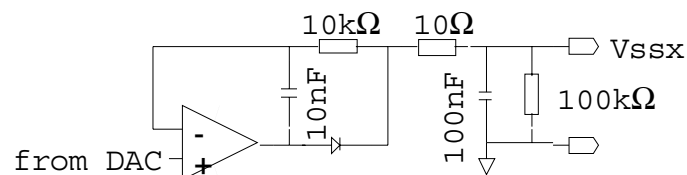


5.1.3. JFET Vss bias interface

5.1.3.1. Electrical characteristics

Connector Id(s)	HSDCU_J29 to HSDCU_J32
Pin number(s)	
Interface type	Output
Signal type	DC voltage
Voltage Range	0 to -5 V
Current range	0 to 5 mA
Transmission mode	Single
Reference pin(s) (return line)	
Source impedance	10 Ω
Load impedance (range)	NA
Corresponding command(s) <i>Photometer:</i>	SetPhotoJfetVss SetPhotoJfetPwr
Corresponding command(s) <i>Spectrometer:</i>	SetSpectroJfetVss SetSpectroJfetPwr

5.1.3.2. Interface circuitry

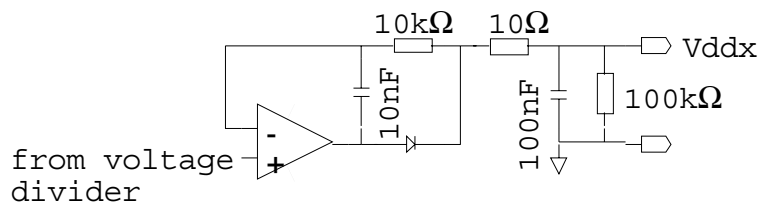


5.1.4. JFET Vdd bias interface

5.1.4.1. Electrical characteristics

Connector Id(s)	HSDCU_J29 to HSDCU_J32
Allocated pin(s)	
Interface type	Output
Signal type	DC voltage
Voltage Range	1.5 to 4 V
Current range	0 to 5 mA
Transmission mode	Single
Reference pin(s) (return line)	
Source impedance	10 Ω
Load impedance (range)	
Corresponding command(s)	NA
Corresponding command(s) <i>Photometer:</i>	SetPhotoJfetPwr
Corresponding command(s) <i>Spectrometer:</i>	SetSpectroJfetPwr

5.1.4.2. Interface circuitry

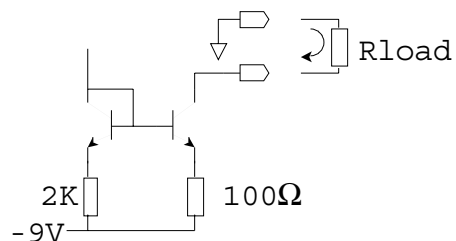


5.1.5. Heater bias interface

5.1.5.1. Electrical characteristics

Connector Id(s)	HS_DCU_J29 HS_DCU_J32
Allocated pin(s)	
Interface type	Output
Signal type	DC voltage
Voltage Range <i>Photometer</i>	0 to 5 V
Voltage Range <i>Spectrometer</i>	0 to 3 V
Current range <i>Photometer</i>	0 to 10 mA
Current Range <i>Spectrometer</i>	0 to 25 mA
Transmission mode	Single
Reference pin(s) (return line)	
Source impedance	NA
Load impedance (range)	TBD
Corresponding command(s) <i>Photometer</i>	SetSpectroHeaterPwr
Corresponding command(s) <i>Spectrometer</i>	SetPhotoHeaterPwr

5.1.5.2. Interface circuitry

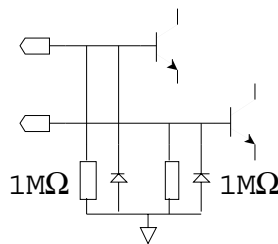


5.1.6. Photometer JFET signal interface

5.1.6.1. Electrical characteristics

Connector Id(s)	HSDCU_J05 to HSDCU_J22
Allocated pin(s)	See §6.3.3
Interface type	Input
Signal type	AC voltage
Voltage range	0 to 11 mVrms
Transmission mode	Balanced
Reference pin(s) (return line)	See §6.3.3
Source impedance	7 k Ω
Load impedance	1 M Ω
AC characteristics	
Waveform	Sine
Frequency	50 – 300 Hz
Transition Time	NA
Corresponding command(s)	NA

5.1.6.2. Interface circuitry

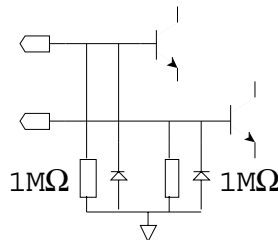


5.1.7. Spectrometer JFET signal interface

5.1.7.1. Electrical characteristics

Connector Id(s)	HSDCU_J23 HSDCU_J28
Allocated pin(s)	See §6.3.3
Interface type	Input
Signal type	AC voltage
Voltage range	0 to 17 mVrms
Transmission mode	Balanced
Reference pin(s) (return line)	See §6.3.3
Source impedance	7 kΩ
Load impedance	1 MΩ
AC characteristics	
Waveform	Sine
Frequency	50 – 300 Hz
Transition Time	NA
Corresponding command(s)	NA

5.1.7.2. Interface circuitry



5.2. MCU interface

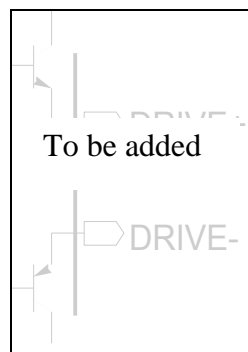
5.2.1. SMEC Drive coil

5.2.1.1. Excitation

5.2.1.1.1. *Electrical characteristics*

Connector Id(s)	HSFCU_J HSFCU_J
Allocated pin(s)	
Interface type	
Signal type	
Voltage range	
Transmission mode	
Reference pin(s) (return line)	
Source impedance	
Load impedance	
AC characteristics	
Waveform	
Frequency	
Transition Time	
Corresponding command(s)	

5.2.1.1.2. *Interface circuitry*

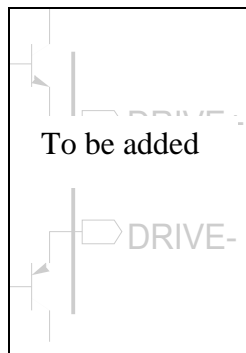


5.2.1.2. Supply Sense

5.2.1.2.1. *Electrical characteristics*

Connector Id(s)	HSFCU_J HSFCU_J
Allocated pin(s)	
Interface type	
Signal type	
Voltage range	
Transmission mode	
Reference pin(s) (return line)	
Source impedance	
Load impedance	
AC characteristics	
Waveform	
Frequency	
Transition Time	
Corresponding command(s)	

5.2.1.2.2. *Interface circuitry*

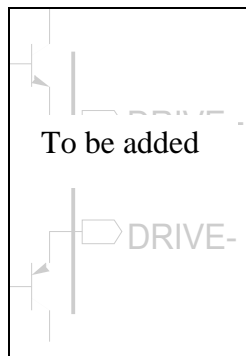


5.2.2. SMEC position sensor LED

5.2.2.1. Electrical characteristics

Connector Id(s)	HSFCU_J HSFCU_J
Allocated pin(s)	
Interface type	
Signal type	
Voltage range	
Transmission mode	
Reference pin(s) (return line)	
Source impedance	
Load impedance	
AC characteristics	
Waveform	
Frequency	
Transition Time	
Corresponding command(s)	

5.2.2.1.1. *Interface circuitry*

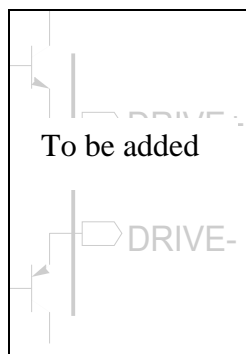


5.2.3. SMEC position sensor photodiode

5.2.3.1. Electrical characteristics

Connector Id(s)	HSFCU_J HSFCU_J
Allocated pin(s)	
Interface type	
Signal type	
Voltage range	
Transmission mode	
Reference pin(s) (return line)	
Source impedance	
Load impedance	
AC characteristics	
Waveform	
Frequency	
Transition Time	
Corresponding command(s)	

5.2.3.2. Interface circuitry

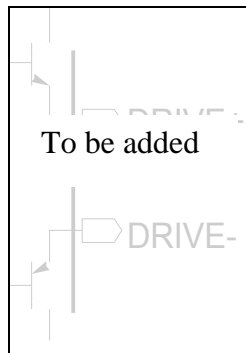


5.2.4. SMEC position sensor supply

5.2.4.1. Electrical characteristics

Connector Id(s)	HSFCU_J HSFCU_J
Allocated pin(s)	
Interface type	
Signal type	
Voltage range	
Transmission mode	
Reference pin(s) (return line)	
Source impedance	
Load impedance	
AC characteristics	
Waveform	
Frequency	
Transition Time	
Corresponding command(s)	

5.2.4.2. Interface circuitry

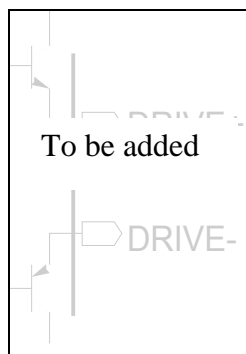


5.2.5. SMEC position sensor photodiode

5.2.5.1. Electrical characteristics

Connector Id(s)	HSFCU_J HSFCU_J
Allocated pin(s)	
Interface type	
Signal type	
Voltage range	
Transmission mode	
Reference pin(s) (return line)	
Source impedance	
Load impedance	
AC characteristics	
Waveform	
Frequency	
Transition Time	
Corresponding command(s)	

5.2.5.2. Interface circuitry

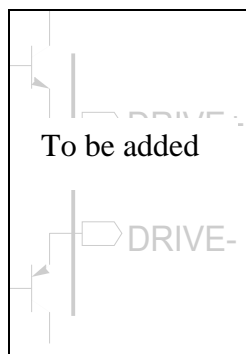


5.2.6. SMEC launch latch supply

5.2.6.1. Electrical characteristics

Connector Id(s)	HSFCU_J HSFCU_J
Allocated pin(s)	
Interface type	
Signal type	
Voltage range	
Transmission mode	
Reference pin(s) (return line)	
Source impedance	
Load impedance	
AC characteristics	
Waveform	
Frequency	
Transition Time	
Corresponding command(s)	

5.2.6.2. Interface circuitry

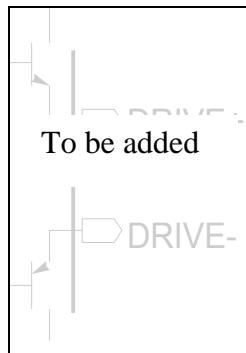


5.2.7. SMEC launch confirmation

5.2.7.1. Electrical characteristics

Connector Id(s)	HSFCU_J HSFCU_J
Allocated pin(s)	
Interface type	
Signal type	
Voltage range	
Transmission mode	
Reference pin(s) (return line)	
Source impedance	
Load impedance	
AC characteristics	
Waveform	
Frequency	
Transition Time	
Corresponding command(s)	

5.2.7.2. Interface circuitry

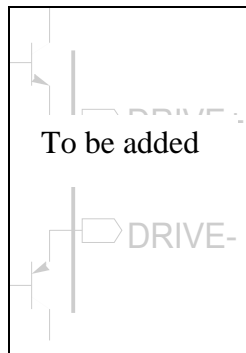


5.2.8. SMEC LVDT coil supply

5.2.8.1. Electrical characteristics

Connector Id(s)	HSFCU_J HSFCU_J
Allocated pin(s)	
Interface type	
Signal type	
Voltage range	
Transmission mode	
Reference pin(s) (return line)	
Source impedance	
Load impedance	
AC characteristics	
Waveform	
Frequency	
Transition Time	
Corresponding command(s)	

5.2.8.2. Interface circuitry



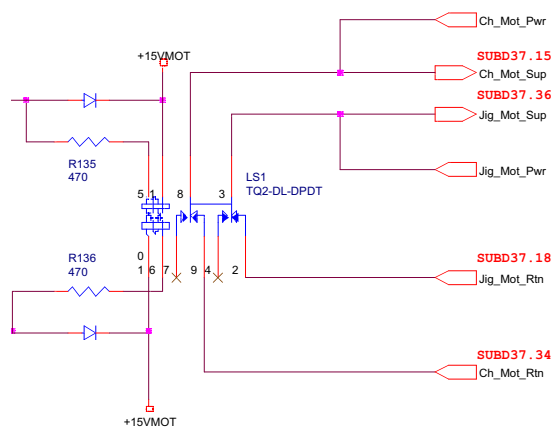
5.2.9. Chop sensor

5.2.9.1. Supply

5.2.9.1.1. Electrical characteristics

Connector Id(s)	HSFCU_J HSFCU_J
Allocated pin(s)	
Interface type	
Signal type	
Voltage range	
Transmission mode	
Reference pin(s) (return line)	
Source impedance	
Load impedance	
AC characteristics	
Waveform	
Frequency	
Transition Time	
Corresponding command(s)	

5.2.9.1.2. Interface circuitry

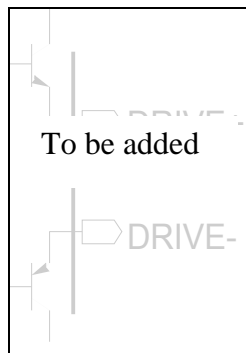


5.2.9.2. Sense

5.2.9.2.1. *Electrical characteristics*

Connector Id(s)	HSFCU_J HSFCU_J
Allocated pin(s)	
Interface type	
Signal type	
Voltage range	
Transmission mode	
Reference pin(s) (return line)	
Source impedance	
Load impedance	
AC characteristics	
Waveform	
Frequency	
Transition Time	
Corresponding command(s)	

5.2.9.2.2. *Interface circuitry*

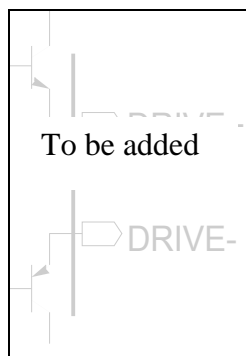


5.2.10. Chop sensor output

5.2.10.1.1. *Electrical characteristics*

Connector Id(s)	HSFCU_J HSFCU_J
Allocated pin(s)	
Interface type	
Signal type	
Voltage range	
Transmission mode	
Reference pin(s) (return line)	
Source impedance	
Load impedance	
AC characteristics	
Waveform	
Frequency	
Transition Time	
Corresponding command(s)	

5.2.10.2. **Interface circuitry**



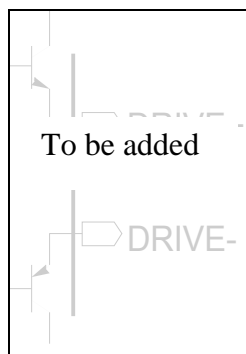
5.2.11. Jiggle sensor

5.2.11.1. Supply

5.2.11.1.1. *Electrical characteristics*

Connector Id(s)	HSFCU_J HSFCU_J
Allocated pin(s)	
Interface type	
Signal type	
Voltage range	
Transmission mode	
Reference pin(s) (return line)	
Source impedance	
Load impedance	
AC characteristics	
Waveform	
Frequency	
Transition Time	
Corresponding command(s)	

5.2.11.1.2. *Interface circuitry*

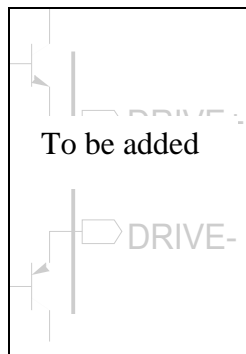


5.2.11.2. Sense

5.2.11.2.1. Electrical characteristics

Connector Id(s)	HSFCU_J HSFCU_J
Allocated pin(s)	
Interface type	
Signal type	
Voltage range	
Transmission mode	
Reference pin(s) (return line)	
Source impedance	
Load impedance	
AC characteristics	
Waveform	
Frequency	
Transition Time	
Corresponding command(s)	

5.2.11.3. Interface circuitry

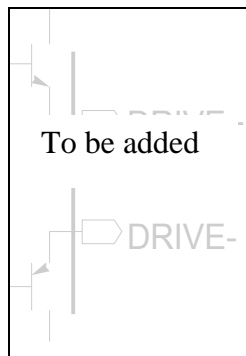


5.2.12. Launch latch sensor

5.2.12.1.1. *Electrical characteristics*

Connector Id(s)	HSFCU_J HSFCU_J
Allocated pin(s)	
Interface type	
Signal type	
Voltage range	
Transmission mode	
Reference pin(s) (return line)	
Source impedance	
Load impedance	
AC characteristics	
Waveform	
Frequency	
Transition Time	
Corresponding command(s)	

5.2.12.2. **Interface circuitry**

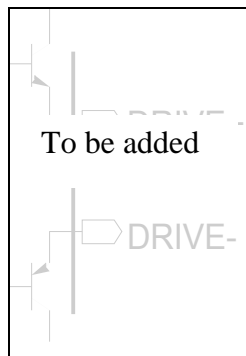


5.2.13. Launch latch coil supply

5.2.13.1.1. *Electrical characteristics*

Connector Id(s)	HSFCU_J HSFCU_J
Allocated pin(s)	
Interface type	
Signal type	
Voltage range	
Transmission mode	
Reference pin(s) (return line)	
Source impedance	
Load impedance	
AC characteristics	
Waveform	
Frequency	
Transition Time	
Corresponding command(s)	

5.2.13.2. **Interface circuitry**



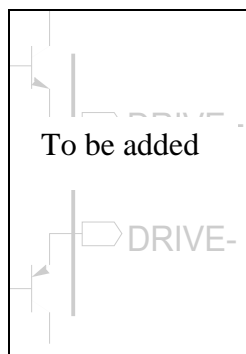
5.2.14. Chop motor

5.2.14.1. Supply

5.2.14.1.1. *Electrical characteristics*

Connector Id(s)	HSFCU_J HSFCU_J
Allocated pin(s)	
Interface type	
Signal type	
Voltage range	
Transmission mode	
Reference pin(s) (return line)	
Source impedance	
Load impedance	
AC characteristics	
Waveform	
Frequency	
Transition Time	
Corresponding command(s)	

5.2.14.1.2. *Interface circuitry*

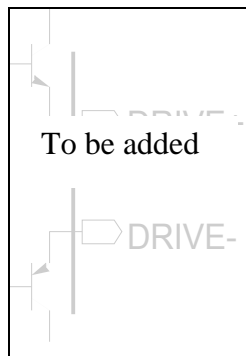


5.2.14.2. Sense

5.2.14.2.1. Electrical characteristics

Connector Id(s)	HSFCU_J HSFCU_J
Allocated pin(s)	
Interface type	
Signal type	
Voltage range	
Transmission mode	
Reference pin(s) (return line)	
Source impedance	
Load impedance	
AC characteristics	
Waveform	
Frequency	
Transition Time	
Corresponding command(s)	

5.2.14.2.2. Interface circuitry



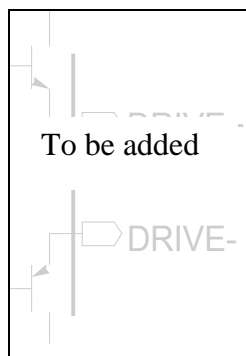
5.2.15. Jiggle motor

5.2.15.1. Supply

5.2.15.1.1. *Electrical characteristics*

Connector Id(s)	HSFCU_J HSFCU_J
Allocated pin(s)	
Interface type	
Signal type	
Voltage range	
Transmission mode	
Reference pin(s) (return line)	
Source impedance	
Load impedance	
AC characteristics	
Waveform	
Frequency	
Transition Time	
Corresponding command(s)	

5.2.15.1.2. *Interface circuitry*

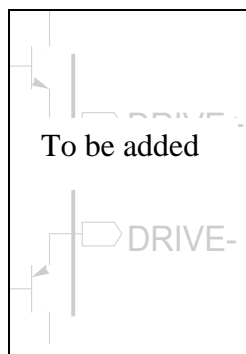


5.2.15.2. Sense

5.2.15.2.1. *Electrical characteristics*

Connector Id(s)	HSFCU_J HSFCU_J
Allocated pin(s)	
Interface type	
Signal type	
Voltage range	
Transmission mode	
Reference pin(s) (return line)	
Source impedance	
Load impedance	
AC characteristics	
Waveform	
Frequency	
Transition Time	
Corresponding command(s)	

5.2.15.2.2. *Interface circuitry*



5.3. SCU interfaces

5.3.1. Temperature Probes – “300 mK”

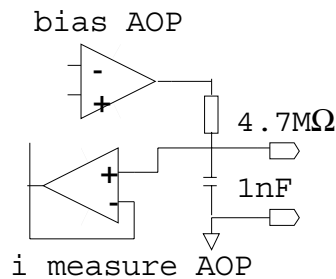
This interface is a 4-wire input/output type as described bellow:

5.3.1.1. Probe bias

5.3.1.1.1. Electrical characteristics

Connector Id(s)	HS_FCU_J23 HS_FCU_J24
Allocated pin(s)	1
Interface type	Output
Signal type	AC current
Current range	0 / 40nA
Transmission mode	Balanced
Reference pin(s) (return lines)	2
Source impedance	4.7 MΩ
AC characteristics	
Waveform	Square
Frequency	10 to 30 Hz
Transition Time	< 1 ms
Corresponding command(s)	TPBiasOnOff SubKpRate

5.3.1.1.2. Interface circuitry

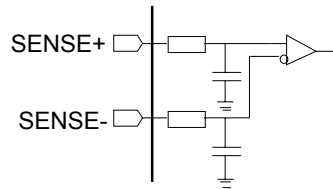


5.3.1.2. Probe sense

5.3.1.2.1. Electrical characteristics

Connector Id(s)	HS_FCU_J23 HS_FCU_J24
Pin number(s)	18
Interface type	Input
Signal type	AC voltage
Voltage range	0 to 6 mVpp
Transmission mode	Balanced
Reference pin(s) (return line)	35
Load impedance	> 1 M Ω
Corresponding command(s)	NA

5.3.1.2.2. Interface circuitry



5.3.2. Standard Temperature Probes

This interface is a 4-wire input/output type as described bellow:

5.3.2.1. Probe bias

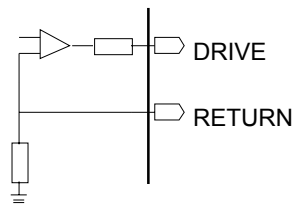
5.3.2.1.1. *Electrical characteristics*

Connector Id(s)	HS_SCU_J21 HS_SCU_J22
Pin number(s)	1, 4, 6
Interface type	Output
Signal type	DC voltage
Voltage	0 / 20 mV
Current range	0-200 μ A
Transmission mode	Single
Reference pin (return line)	2, 5, 7
Source impedance	
Load impedance	100 Ω - 100k Ω
Corresponding command(s)	TPBiasOnOff

Connector Id(s)	HS_SCU_J23 HS_SCU_J24
Pin number(s)	1, 3, 4, 6, 7, 9, 10, 12, 13
Interface type	Output
Signal type	DC voltage
Voltage	0 / 20 mV
Current range	0-200 μ A
Transmission mode	Single
Reference pin (return line)	19, 5, 22, 8, 24, 25, 11, 28, 14
Source impedance	
Load impedance	100 Ω - 100k Ω
Corresponding command(s)	TPBiasOnOff

Connector Id(s)	HS_SCU_J25 HS_SCU_J26
Pin number(s)	1, 4, 6
Interface type	Output
Signal type	DC voltage
Voltage	0 / 20 mV
Current range	0-200 μ A
Transmission mode	Single
Reference pin (return line)	9, 11, 14
Source impedance	
Load impedance	100 Ω - 100k Ω
Corresponding command(s)	TPBiasOnOff

5.3.2.1.2. *Interface circuitry*



5.3.2.2. Probe sense

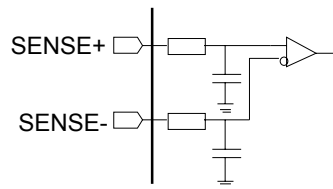
5.3.2.2.1. Electrical characteristics

Connector Id(s)	HS_FCU_J21 HS_FCU_J22
Pin number(s)	9, 11, 14
Interface type	Input
Signal type	DC current
Current range	0 to 200 μ A
Transmission mode	Balanced
Reference pin(s) (return line)	10, 12, 17
Load impedance	

Connector Id(s)	HS_FCU_J23 HS_FCU_J24
Pin number(s)	20, 21, 23, 24, 26, 27, 29, 30
Interface type	Input
Signal type	DC current
Current range	0 to 200 μ A
Transmission mode	Balanced
Reference pin(s) (return line)	36, 37, 39, 40, 42, 44, 45, 47
Load impedance	

Connector Id(s)	HS_FCU_J25 HS_FCU_J26
Pin number(s)	2, 5, 7
Interface type	Input
Signal type	DC Current
Current range	0 to 200 μ A
Transmission mode	Balanced
Reference pin(s) (return line)	10, 12, 15
Load impedance	

5.3.2.2.2. *Interface circuitry*



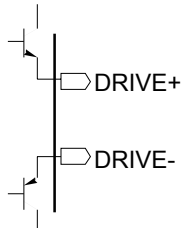
5.3.3. Heaters

5.3.3.1. Sorption pump

5.3.3.1.1. *Electrical characteristics*

Connector Id(s)	HSFCU_J11 HSFCU_J12
Pin number(s)	1, 2
Interface type	Output
Signal type	DC current
Current range	0 to 40 mA
Short current	100 mA
Voltage range	- 15 V to +15 V
Transmission mode	Balanced
Reference pin(s) (return lines)	14, 15
Source impedance	
Corresponding command(s)	HHeaterI

5.3.3.1.2. *Interface circuitry*

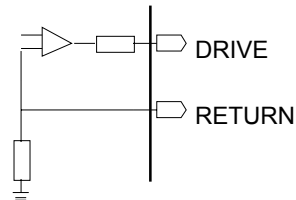


5.3.3.2. Heat switches

5.3.3.2.1. *Electrical characteristics*

Connector Id(s)	HSFCU_J11 HSFCU_J12
Pin number(s)	
Interface type	Output
Signal type	DC current
Current range	0 to 2 mA
Voltage range	0 to 9 V
Transmission mode	Balanced
Reference pin(s) (return line)	
Load impedance	
Corresponding command(s)	LHeaterI1 LHeaterI2

5.3.3.2.2. *Interface circuitry*

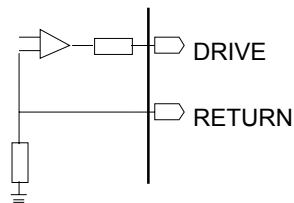


5.3.3.3. Thermal strap

5.3.3.3.1. *Electrical characteristics*

Connector Id(s)	HSFCU_J11 HSFCU_J12
Pin number(s)	
Interface type	Output
Signal type	DC current
Current range	0 to x mA
Voltage range	0 to 9 V
Transmission mode	Balanced
Reference pin(s) (return line)	
Load impedance	
Corresponding command(s)	LHeaterI3

5.3.3.3.2. *Interface circuitry*



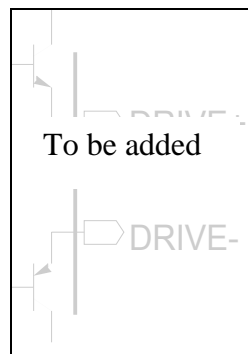
5.3.4. Calibrator

5.3.4.1. Flood type

5.3.4.1.1. *Electrical characteristics*

Connector Id(s)	HSFCU_J11 HSFCU_J12
Pin number(s)	
Interface type	Output
Signal type	DC current
Current range	0 to x mA
Voltage range	0 to 9 V
Transmission mode	Balanced
Reference pin(s) (return line)	
Load impedance	
Corresponding command(s)	

5.3.4.1.2. *Interface circuitry*

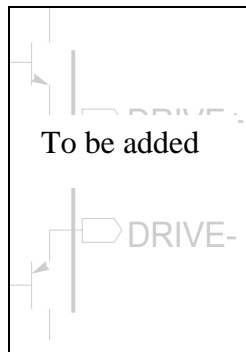


5.3.4.2. Point source type

5.3.4.2.1. Electrical characteristics

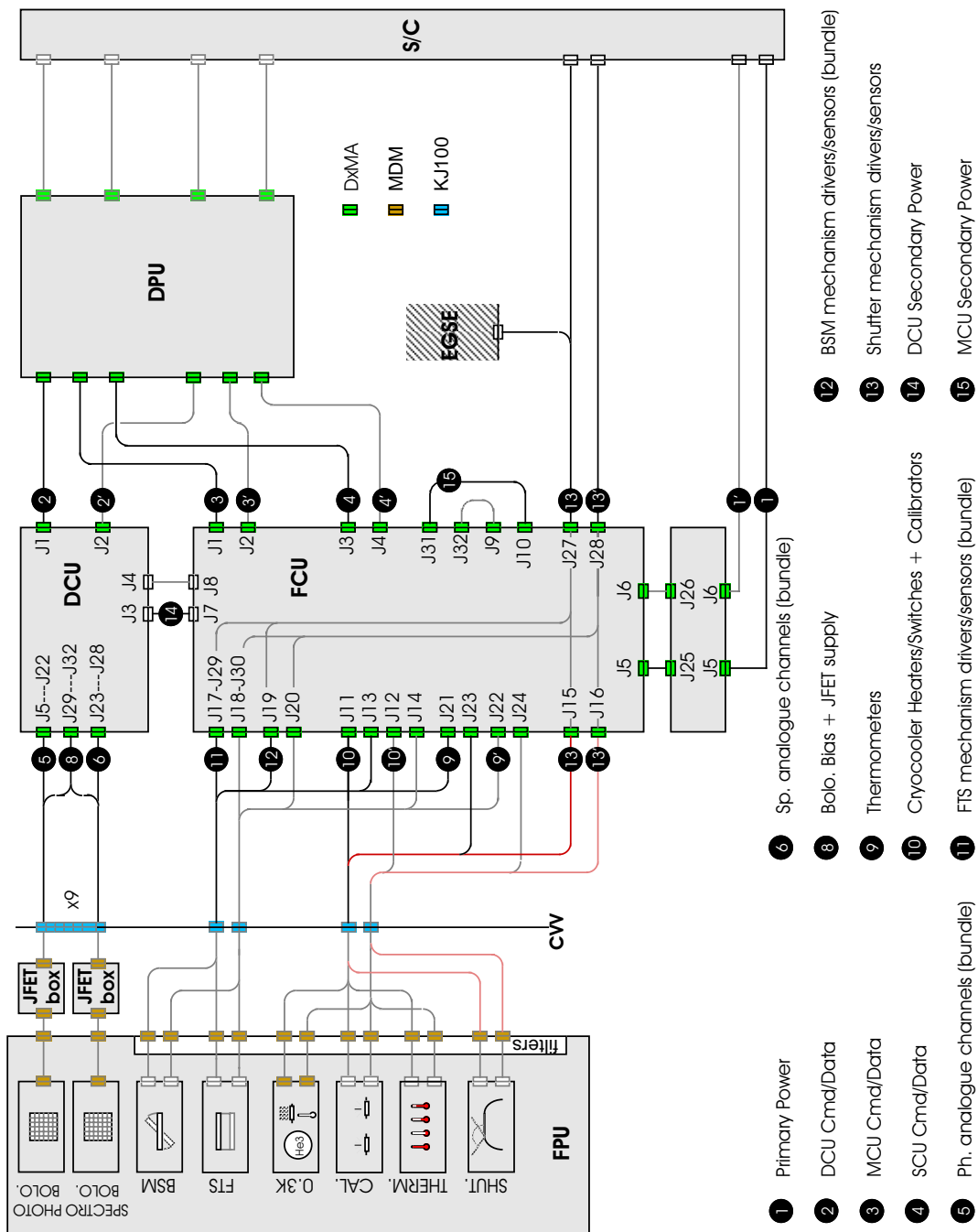
Connector Id(s)	HSFCU_J11 HSFCU_J12
Pin number(s)	
Interface type	Output
Signal type	DC current
Current range	0 to x mA
Voltage range	0 to 9 V
Transmission mode	Balanced
Reference pin(s) (return line)	
Load impedance	
Corresponding command(s)	

5.3.4.2.2. Interface circuitry



6. Connectors and Harness Definition

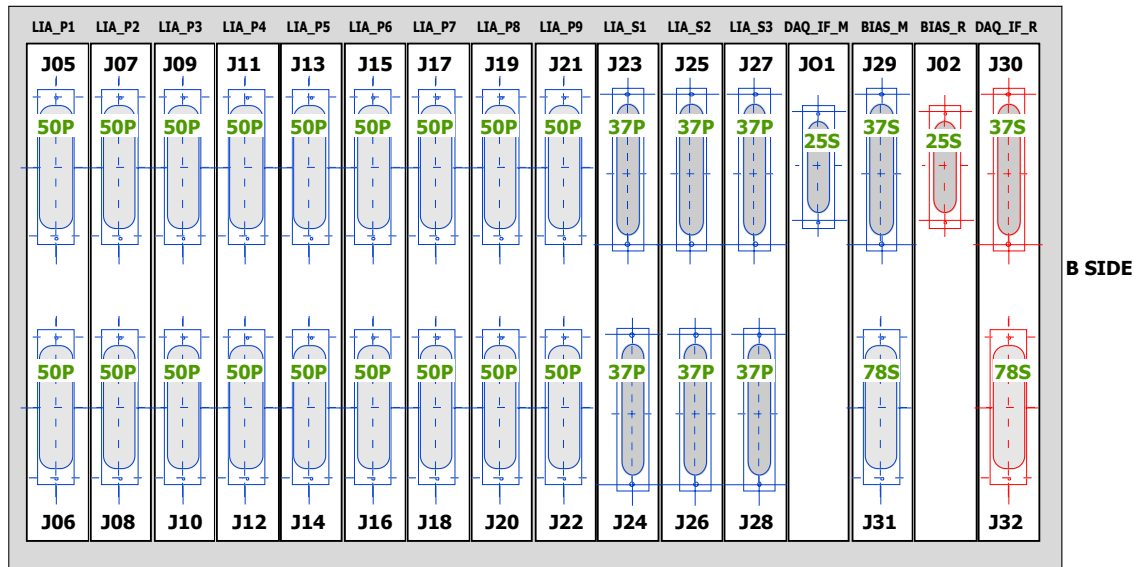
6.1. Overall harness configuration



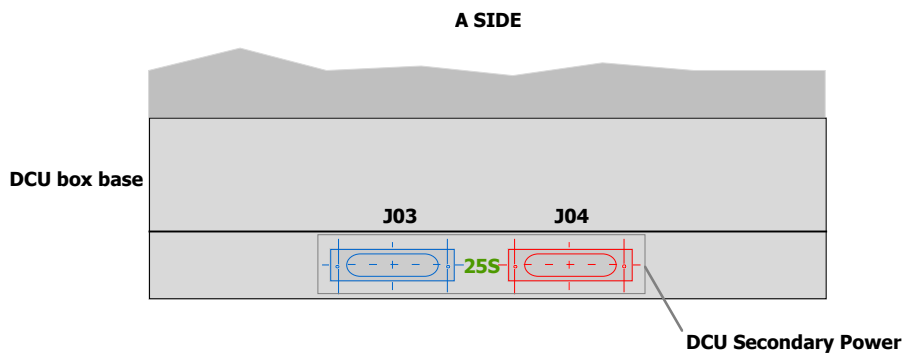
6.2. Connector layout on box

6.2.1. DCU box

6.2.1.1. Top View

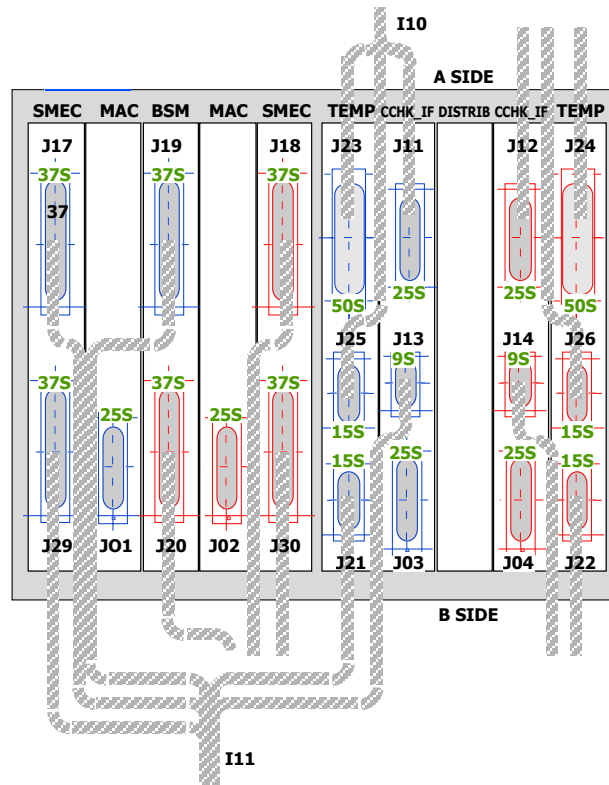


6.2.1.2. Lateral View

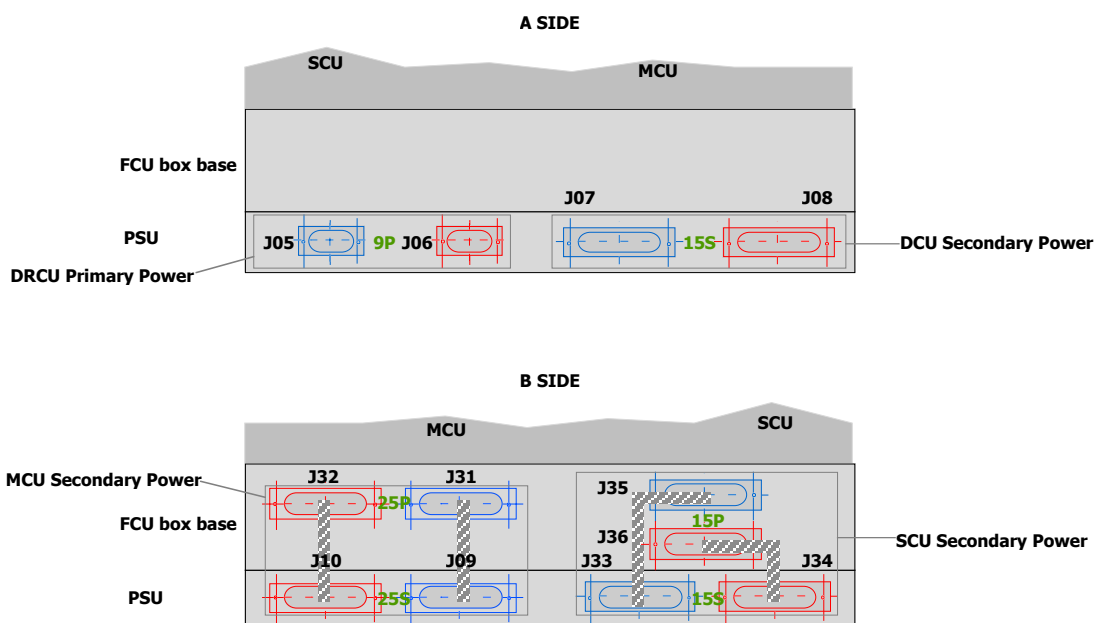


6.2.2. FCU box

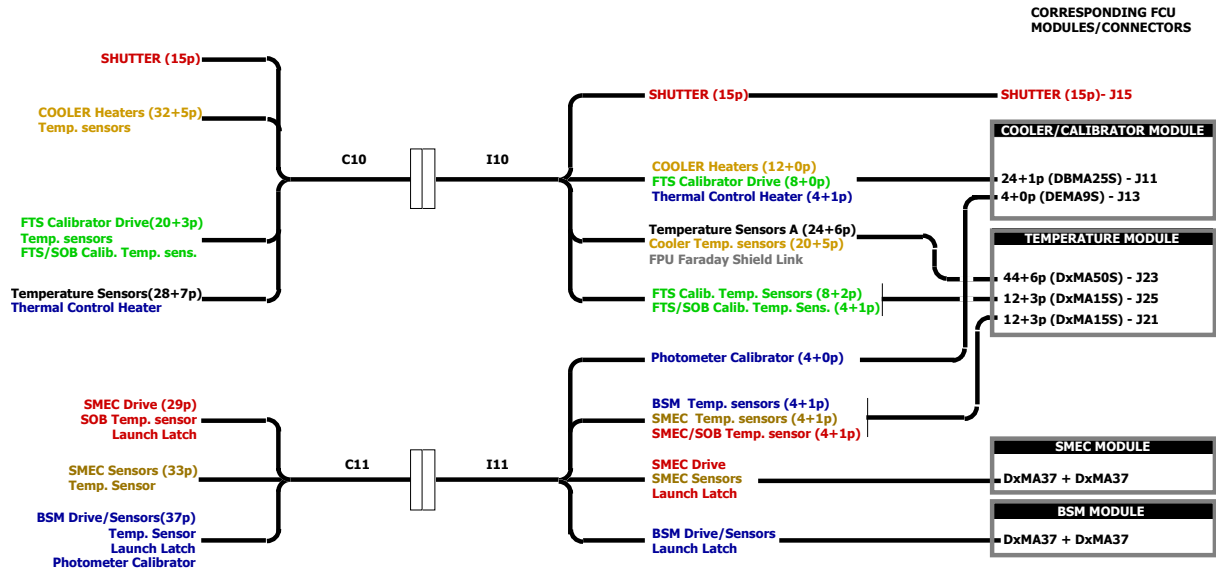
6.2.2.1. Top View



6.2.2.2. Lateral Views



6.2.3. DRCU to FPU harness tail configuration



6.3. Connector list

S/S	Connector Id	Connector Type	Interface Name
DCU	J01	DBMA25S	DAQ_IF_M / DPU_M
	J02	DBMA25S	DAQ_IF_R / DPU_R
	J03	DCMA25P	DCU / PSU_M
	J04	DCMA25P	DCU / PSU_R
	J05	DDMA50P	LIA_P_1 / FPU
	J06	DDMA50P	LIA_P_1 / FPU
	J07	DDMA50P	LIA_P_2 / FPU
	J08	DDMA50P	LIA_P_2 / FPU
	J09	DDMA50P	LIA_P_3 / FPU
	J10	DDMA50P	LIA_P_3 / FPU
	J11	DDMA50P	LIA_P_4 / FPU
	J12	DDMA50P	LIA_P_4 / FPU
	J13	DDMA50P	LIA_P_5 / FPU
	J14	DDMA50P	LIA_P_5 / FPU
	J15	DDMA50P	LIA_P_6 / FPU
	J16	DDMA50P	LIA_P_6 / FPU
	J17	DDMA50P	LIA_P_7 / FPU
	J18	DDMA50P	LIA_P_7 / FPU
	J19	DDMA50P	LIA_P_8 / FPU
	J20	DDMA50P	LIA_P_8 / FPU
	J21	DDMA50P	LIA_P_9 / FPU
	J22	DDMA50P	LIA_P_9 / FPU
	J23	DDMA37P	LIA_S_1 / FPU
	J24	DDMA37P	LIA_S_1 / FPU
	J25	DDMA37P	LIA_S_2 / FPU
	J26	DDMA37P	LIA_S_2 / FPU
	J27	DDMA37P	LIA_S_3 / FPU
	J28	DDMA37P	LIA_S_3 / FPU
	J29	DDMA37S	BIAS_M / FPU
	J30	DDMA37S	BIAS_R / FPU
	J31	DBMA78S	BIAS_M / FPU
	J32	DBMA78S	BIAS_R / FPU
MCU	J01	DBMA25S	MAC_M / DPU_M
MCU	J02	DBMA25S	MAC_R / DPU_R
SCU	J03	DBMA25S	CCHK_IF_M / DPU_M
SCU	J04	DBMA25S	CCHK_IF_R / DPU_R
PSU	J05	DEMA9P	PSU_M / PCDU_M
PSU	J06	DEMA9P	PSU_R / PCDU_R
PSU	J07	DBMA15S	PSU_M / DCU
PSU	J08	DBMA15S	PSU_R / DCU
PCU	J09	DCMA25S	PSU_M / MCU_M
PCU	J10	DCMA25S	PSU_R / MCU_R
SCU	J11	DBMA25S	CCHK_IF_M / FPU_COOL_CAL_M
SCU	J12	DBMA25S	CCHK_IF_R / FPU_COOL_CAL_R
SCU	J13	DEMA9S	CCHK_IF_M / FPU_PH_STIM_M
SCU	J14	DEMA9S	CCHK_IF_R / FPU_PH_STIM_R
FCU	J15	NA	NA

S/S	Connector Id	Connector Type	Interface Name
FCU	J16	NA	NA
MCU	J17	DCMA37S	SMEC_M / FPU_SMECm_1_M
MCU	J18	DCMA37S	SMEC_M / FPU_SMECm_2_M
MCU	J19	DCMA37S	BSM_M / FPU_BSM_M
MCU	J20	DCMA37S	BSM_R / FPU_BSM_R
SCU	J21	DAMA15S	TEMP_M / FPU_TS_1_M
SCU	J22	DAMA15S	TEMP_R / FPU_TS_1_R
SCU	J23	DDMA50S	TEMP_M / FPU_TS_2_M
SCU	J24	DDMA50S	TEMP_R / FPU_TS_2_R
SCU	J25	DAMA15S	TEMP_M / FPU_MEC_TS_M
SCU	J26	DAMA15S	TEMP_R / FPU_MEC_TS_R
FCU	J27	NA	NA
FCU	J28	NA	NA
MCU	J29	DCMA37S	SMEC_M / FPU_SMECm_2_M
MCU	J30	DCMA37S	SMEC_R / FPU_SMECm_2_R
MCU	J31	DCMA25P	MCU_M / PSU_M
MCU	J32	DCMA25P	MCU_R / PSU_R
PSU	J33	DAMA15S	PSU_M / SCU_M
PSU	J34	DAMA15S	PSU_R / SCU_R
SCU	J35	DAMA15P	SCU_M / PSU_M
SCU	J36	DAMA15P	SCU_R / PSU_R

6.4. Connectors Description

6.4.1. Interfaces with DPU

Unit : DCU
 Sub-unit/Module : DAQ_IF
 Connector Identifier : J01
 Connector Type : DBMA25S
 Connector Name : HSDCU_J01

Pin #	Signal Name	EMC Class	Comment
1			
2	C_CLK_DCU_P+	2	Twisted with 15
3	C_CMD_DCU_P+	2	Twisted with 16
4	C_RES_DCU_P+	2	Twisted with 17
5	C_RES_SHD	2	Connected DCU side only
6			
7			
8	D_CLK_DCU_P+	2	Twisted with 21
9	D_CLK_SHD	2	Connected DCU side only
10	D_DAT_DCU_P+	2	Twisted with 22
11	D_GAT_DCU_P+	2	Twisted with 24
12	D_GAT_SHD	2	Connected DCU side only
13	-		
14	C_SHD	2	Connected DPU side only
15	C_CLK_DCU_P-	2	Twisted with 2
16	C_CMD_DCU_P-	2	Twisted with 3
17	C_RES_DCU_P-	2	Twisted with 4
18			
19			
20			
21	D_CLK_DCU_P-	2	Twisted with 15
22	D_DAT_DCU_P-	2	Twisted with 10
23	D_SHD	2	Connected DCU side only
24	D_GAT_DCU_P-	2	Twisted with 11
25	-		

Unit : FCU
 Sub-unit/Module : MCU/MAC
 Connector Identifier : J01
 Connector Type : DBMA25S
 Connector Name : HSFCU_J01

Pin #	Signal Name	EMC Class	Signal Description
1			
2	C CLK MCU P+	2	Twisted with 15
3	C CMD MCU P+	2	Twisted with 16
4	C RES MCU P+	2	Twisted with 17
5	C RES SHD	2	Connected MCU side only
6			
7			
8	D CLK MCU P+	2	Twisted with 21
9	D CLK SHD	2	Connected MCU side only
10	D DAT MCU P+	2	Twisted with 22
11	D GAT MCU P+	2	Twisted with 24
12	D GAT SHD	2	Connected MCU side only
13	-		
14	C SHD	2	Connected DPU side only
15	C CLK MCU P-	2	Twisted with 2
16	C CMD MCU P-	2	Twisted with 3
17	C RES MCU P-	2	Twisted with 4
18			
19			
20			
21	D CLK MCU P-	2	Twisted with 15
22	D DAT MCU P-	2	Twisted with 10
23	D SHD	2	Connected MCU side only
24	D GAT MCU P-	2	Twisted with 11
25	-		

Unit : FCU
Sub-unit/Module : SCU/CCHK_IF
Connector Identifier : J03
Connector Type : DBMA25S
Connector Name : HSFCU_J03

Pin #	Signal Name	EMC Class	Signal Description
1			
2	C CLK SCU P+	2	Twisted with 15
3	C CMD SCU P+	2	Twisted with 16
4	C RES SCU P+	2	Twisted with 17
5	C RES SHD	2	Connected SCU side only
6			
7			
8	D CLK SCU P+	2	Twisted with 21
9	D CLK SHD	2	Connected SCU side only
10	D DAT SCU P+	2	Twisted with 22
11	D GAT SCU P+	2	Twisted with 24
12	D GAT SHD	2	Connected SCU side only
13	-		
14	C SHD	2	Connected DPU side only
15	C CLK SCU P-	2	Twisted with 2
16	C CMD SCU P-	2	Twisted with 3
17	C RES SCU P-	2	Twisted with 4
18			
19			
20			
21	D CLK SCU P-	2	Twisted with 15
22	D DAT SCU P-	2	Twisted with 10
23	D SHD	2	Connected SCU side only
24	D GAT SCU P-	2	Twisted with 11
25	-		

Unit : DCU
Sub-unit/Module : DAQ_IF
Connector Identifier : J02
Connector Type : DBMA25S
Connector Name : HSDCU_J02

Pin #	Signal Name	EMC Class	Signal Description
1			
2	C CLK DCU R+	2	Twisted with 15
3	C CMD DCU R+	2	Twisted with 16
4	C RES DCU R+	2	Twisted with 17
5	C RES SHD	2	Connected DCU side only
6			
7			
8	D CLK DCU R+	2	Twisted with 21
9	D CLK SHD	2	Connected DCU side only
10	D DAT DCU R+	2	Twisted with 22
11	D GAT DCU R+	2	Twisted with 24
12	D GAT SHD	2	Connected DCU side only
13	-		
14	C SHD	2	Connected DPU side only
15	C CLK DCU R-	2	Twisted with 2
16	C CMD DCU R-	2	Twisted with 3
17	C RES DCU R-	2	Twisted with 4
18			
19			
20			
21	D CLK DCU R-	2	Twisted with 15
22	D DAT DCU R-	2	Twisted with 10
23	D SHD	2	Connected DCU side only
24	D GAT DCU R-	2	Twisted with 11
25	-		

Unit : FCU
 Sub-unit/Module : MCU/MAC
 Connector Identifier : J02
 Connector Type : DBMA25S
 Connector Name : HSFCU_J02

Pin #	Signal Name	EMC Class	Signal Description
1			
2	C_CLK_MCU_R+	2	Twisted with 15
3	C_CMD_MCU_R+	2	Twisted with 16
4	C_RES_MCU_R+	2	Twisted with 17
5	C_RES_SHD	2	Connected MCU side only
6			
7			
8	D_CLK_MCU_R+	2	Twisted with 21
9	D_CLK_SHD	2	Connected MCU side only
10	D_DAT_MCU_R+	2	Twisted with 22
11	D_GAT_MCU_R+	2	Twisted with 24
12	D_GAT_SHD	2	Connected MCU side only
13	-		
14	C_SHD	2	Connected DPU side only
15	C_CLK_MCU_R-	2	Twisted with 2
16	C_CMD_MCU_R-	2	Twisted with 3
17	C_RES_MCU_R-	2	Twisted with 4
18			
19			
20			
21	D_CLK_MCU_R-	2	Twisted with 15
22	D_DAT_MCU_R-	2	Twisted with 10
23	D_SHD	2	Connected MCU side only
24	D_GAT_MCU_R-	2	Twisted with 11
25	-		

Unit : FCU
Sub-unit/Module : SCU/CCHK_IF
Connector Identifier : J04
Connector Type : DBMA25S
Connector Name : HSDCU_J04

Pin #	Signal Name	EMC Class	Signal Description
1			
2	C CLK SCU R+	2	Twisted with 15
3	C CMD SCU R+	2	Twisted with 16
4	C RES SCU R+	2	Twisted with 17
5	C RES SHD	2	Connected SCU side only
6			
7			
8	D CLK SCU R+	2	Twisted with 21
9	D CLK SHD	2	Connected SCU side only
10	D DAT SCU R+	2	Twisted with 22
11	D GAT SCU R+	2	Twisted with 24
12	D GAT SHD	2	Connected SCU side only
13	-		
14	C SHD	2	Connected DPU side only
15	C CLK SCU R-	2	Twisted with 2
16	C CMD SCU R-	2	Twisted with 3
17	C RES SCU R-	2	Twisted with 4
18			
19			
20			
21	D CLK SCU R-	2	Twisted with 15
22	D DAT SCU R-	2	Twisted with 10
23	D SHD	2	Connected SCU side only
24	D GAT SCU R-	2	Twisted with 11
25	-		

6.4.2. Interfaces with S/C

Unit : FCU
 Sub-unit : PSU
 Connector Identifier : J05
 Connector Type : DBMA9P
 Connector Name : HSFCU_J05

Pin #	Signal Name	EMC Class	Signal Description
1			
2	PWR_28V_P	1	
3			
4	RTN_PWR_P	1	
5			
6			
7	PWR_28V_P	1	
8	RTN_PWR_P	1	
9			

Unit : FCU
 Sub-unit : PSU
 Connector Identifier : J06
 Connector Type : DBMA9P
 Connector Name : HSFCU_J06

Pin #	Signal Name	EMC Class	Signal Description
1			
2	PWR_28V_P	1	
3			
4	RTN_PWR_P	1	
5			
6			
7	PWR_28V_P	1	
8	RTN_PWR_P	1	
9			

Unit : FCU
 Sub-unit/Module : Shutter (Main)
 Connector Identifier : J27
 Connector Type : DCMA25P
 Connector Name : HSFCU_J27

Pin #	Signal Name	EMC Class	Signal Description
1	Shutter Actuator Position Sensor +		
2	Shutter Latch Sense +		
3	Shutter Sense Shld		
4	Shutter Shutter Vane Heater+		
5	Shutter Stepper Drive Phase B +		
6	Shutter Temp Sensor Bias+		
7	Shutter Common Temp V		
8	Shutter Temp Sensor Bias -/Shld		
9	SMEC launch latch # 1 confirmation -		
10	SMEC launch latch # 2 confirmation +		
11	SMEC launch latch # 2 confirmation Shield		
12	BSM Launch latch confirmation -		
14	Shutter Actuator Position Sensor -		
15	Shutter Latch Sense -		
16	Shutter Latch Drive +		
17	Shutter Stepper Drive Phase A +		
18	Shutter Power Ground / Rtn. as shld		
19	Shutter Vane Temp V+		
20	Shutter Actuator Temp V-		
21	SMEC launch latch # 1 confirmation +		
22	SMEC launch latch # 1 confirmation Shield		
23	SMEC launch latch # 2 confirmation -		
24	BSM Launch latch confirmation +		
25	BSM Launch latch confirmation Shield		

Unit : FCU
 Sub-unit/Module : Shutter (Redundant)
 Connector Identifier : J28
 Connector Type : DCMA9P
 Connector Name : HSFCU_J05

Pin #	Signal Name	EMC Class	Signal Description
1	Shutter Actuator Position Sensor +		
2	Shutter Latch Sense +		
3	Shutter Sense Shld		
4	Shutter Shutter Vane Heater+		
5	Shutter Stepper Drive Phase B +		
6	Shutter Temp Sensor Bias+		
7	Shutter Common Temp V		
8	Shutter Temp Sensor Bias -/Shld		
9	SMEC launch latch # 1 confirmation -		
10	SMEC launch latch # 2 confirmation +		
11	SMEC launch latch # 2 confirmation Shield		
12	BSM Launch latch confirmation -		
14	Shutter Actuator Position Sensor -		
15	Shutter Latch Sense -		
16	Shutter Latch Drive +		
17	Shutter Stepper Drive Phase A +		
18	Shutter Power Ground / Rtn. as shld		
19	Shutter Vane Temp V+		
20	Shutter Actuator Temp V-		
21	SMEC launch latch # 1 confirmation +		
22	SMEC launch latch # 1 confirmation Shield		
23	SMEC launch latch # 2 confirmation -		
24	BSM Launch latch confirmation +		
25	BSM Launch latch confirmation Shield		

6.4.3. Interfaces with FPU

6.4.3.1. DCU Interfaces

6.4.3.1.1. LIA_P Module

Unit : DCU
 Sub-unit/Module : LIA_P
 Connector Identifier : J05, J07, J09, J11, J13, J15, J17, J19, J21
 Connector Type : DDMA50P
 Connector Name : HSDCU_J05 to HSDCU_J21

Pin #	Signal Name	EMC Class	Signal Description
1	Channel 1 +	3	
18	Channel 1 -	3	
34	Channel 1gnd shld	3	
2	Channel 2 +	3	
19	Channel 2 -	3	
35	Channel 2gnd shld	3	
3	Channel 3 +	3	
20	Channel 3 -	3	
36	Channel 3gnd shld	3	
4	Channel 4 +	3	
21	Channel 4 -	3	
37	Channel 4gnd shld	3	
5	Channel 5 +	3	
22	Channel 5 -	3	
38	Channel 5gnd shld	3	
6	Channel 6 +	3	
23	Channel 6 -	3	
39	Channel 6gnd shld	3	
7	Channel 7 +	3	
24	Channel 7 -	3	
40	Channel 7gnd shld	3	
8	Channel 8 +	3	
25	Channel 8 -	3	
41	Channel 8gnd shld	3	
9	GND WIRE	3	
42	FPU Faraday Shield Link	3	
26	Channel 9 +	3	
10	Channel 9 -	3	
43	Channel 9gnd shld	3	
27	Channel 10 +	3	
11	Channel 10 -	3	
44	Channel 10gnd shld	3	
28	Channel 11 +	3	

12	Channel 11 -	3	
45	Channel 11gnd shld	3	
29	Channel 12 +	3	
13	Channel 12 -	3	
46	Channel 12gnd shld	3	
30	Channel 13 +	3	
14	Channel 13 -	3	
47	Channel 13gnd shld	3	
31	Channel 14 +	3	
15	Channel 14 -	3	
48	Channel 14gnd shld	3	
32	Channel 15 +	3	
16	Channel 15 -	3	
49	Channel 15gnd shld	3	
33	Channel 16 +	3	
17	Channel 16 -	3	
50	Channel 16gnd shld	3	

Unit : DCU
 Sub-unit/Module : LIA_P
 Connector Identifier : J06, J08, J10, J12, J14, J16, J18, J20, J22
 Connector Type : DDMA50P
 Connector Name : HSDCU_J06 to HSDCU_J22

Pin #	Signal Name	EMC Class	Signal Description
1	Channel 1 +	3	
18	Channel 1 -	3	
34	Channel 1gnd shld	3	
2	Channel 2 +	3	
19	Channel 2 -	3	
35	Channel 2gnd shld	3	
3	Channel 3 +	3	
20	Channel 3 -	3	
36	Channel 3gnd shld	3	
4	Channel 4 +	3	
21	Channel 4 -	3	
37	Channel 4gnd shld	3	
5	Channel 5 +	3	
22	Channel 5 -	3	
38	Channel 5gnd shld	3	
6	Channel 6 +	3	
23	Channel 6 -	3	
39	Channel 6gnd shld	3	
7	Channel 7 +	3	
24	Channel 7 -	3	
40	Channel 7gnd shld	3	
8	Channel 8 +	3	
25	Channel 8 -	3	
41	Channel 8gnd shld	3	
9	GND WIRE	3	
42	FPU Faraday Shield Link	3	
26	Channel 9 +	3	
10	Channel 9 -	3	
43	Channel 9gnd shld	3	
27	Channel 10 +	3	
11	Channel 10 -	3	
44	Channel 10gnd shld	3	
28	Channel 11 +	3	
12	Channel 11 -	3	
45	Channel 11gnd shld	3	
29	Channel 12 +	3	
13	Channel 12 -	3	
46	Channel 12gnd shld	3	
30	Channel 13 +	3	
14	Channel 13 -	3	
47	Channel 13gnd shld	3	
31	Channel 14 +	3	

15	Channel 14 –	3	
48	Channel 14gnd shld	3	
32	Channel 15 +	3	
16	Channel 15 -	3	
49	Channel 15gnd shld	3	
33	Channel 16 +	3	
17	Channel 16 -	3	
50	Channel 16gnd shld	3	

6.4.3.1.2. LIA_S Module

Unit : DCU
 Sub-unit/Module : LIA_S
 Connector Identifier : J23, J25, J27
 Connector Type : DDMA37P
 Connector Name : HSDCU_J23, HSDCU_J25, HSDCU_J27

Pin #	Signal Name	EMC Class	Signal Description
1	Channel 1gnd shld	3	
2	Channel 1 -	3	
3	Channel 2 +	3	
4	Channel 3gnd shld	3	
5	Channel 3 -	3	
6	Channel 4 +	3	
7	Channel 5gnd shld	3	
8	Channel 5 -	3	
9	Channel 6 +	3	
10	FPU Faraday Shield Link	3	
11	Channel 7 +	3	
12	Channel 8 -	3	
13	Channel 8gnd shld	3	
14	Channel 9 +	3	
15	Channel 10 -	3	
16	Channel 10gnd shld	3	
17	Channel 11 +	3	
18	Channel 12 -	3	
19	Channel 12gnd shld	3	
20	Channel 1 +	3	
21	Channel 2gnd shld	3	
22	Channel 2 -	3	
23	Channel 3 +	3	
24	Channel 4gnd shld	3	
25	Channel 4 -	3	
26	Channel 5 +	3	
27	Channel 6gnd shld	3	
28	Channel 6 -	3	
29	Channel 7 -	3	
30	Channel 7gnd shld	3	
31	Channel 8 +	3	
32	Channel 9 -	3	
33	Channel 9gnd shld	3	
34	Channel 10 +	3	
35	Channel 11 -	3	
36	Channel 11gnd shld	3	
37	Channel 12 +	3	

Unit : DCU
 Sub-unit/Module : LIA_S
 Connector Identifier : J24, J26, J28
 Connector Type : DDMA37P
 Connector Name : HSDCU_ J24, HSDCU_ J26, HSDCU_ J28

Pin#	Signal Name	EMC Class	Signal Description
1	Channel 1gnd shld	3	
2	Channel 13 -	3	
3	Channel 14 +	3	
4	Channel 15gnd shld	3	
5	Channel 15 -	3	
6	Channel 16 +	3	
7	Channel 17gnd shld	3	
8	Channel 17 -	3	
9	Channel 18 +	3	
10	GND WIRE	3	
11	Channel 19 +	3	
12	Channel 20 -	3	
13	Channel 1gnd shld	3	
14	Channel 21 +	3	
15	Channel 22 -	3	
16	Channel 22gnd shld	3	
17	Channel 23 +	3	
18	Channel 24 -	3	
19	Channel 24gnd shld	3	
20	Channel 13 +	3	
21	Channel 1gnd shld	3	
22	Channel 14 -	3	
23	Channel 15 +	3	
24	Channel 16gnd shld	3	
25	Channel 16 -	3	
26	Channel 17 +	3	
27	Channel 18gnd shld	3	
28	Channel 18 -	3	
29	Channel 19 -	3	
30	Channel 19gnd shld	3	
31	Channel 20 +	3	
32	Channel 21 -	3	
33	Channel 21gnd shld	3	
34	Channel 22 +	3	
35	Channel 23 -	3	
36	Channel 23gnd shld	3	
37	Channel 24 +	3	

6.4.3.1.3. *BIAS Module*

Unit : DCU
 Sub-unit/Module : BIAS_P (Main)
 Connector Identifier : J29
 Connector Type : DDMA78S
 Connector Name : HSDCU_J29

Pin#	Signal Name	EMC Class	Signal Description
1	Vdd1_P		
2	Vss1_P		
3	Vdd2_P		
4	Vdd3_P		
5	Vss3_P		
6	PBias_P250		
7	Gnd_Bias_Ph		
8	Gnd_Bias_Ph		
9	Nheater_PSW1		
10	Vdd7_P		
11	Vss7_P		
12	Vdd8_P		
13	PBias_P350		
14	Nbias_P350		
15	Nheater_PMW1		
16	Gnd_Bias_Ph		
17	Vss11_P		
18	Vdd12_P		
19	Vss12_P		
20	Gnd_Bias_Ph		
21	Gnd_Bias_Ph		
22	Gnd_Bias_Ph		
23	Vss2_P		
24	Gnd_Bias_Ph		
25	Gnd_Bias_Ph		
26	Nbias_250		
27	Gnd_Bias_Ph		
28	Gnd_Bias_Ph		
29	Gnd_Bias_Ph		
30	Gnd_Bias_Ph		
31	Vss8_P		
32	Gnd_Bias_Ph		
33	Gnd_Bias_Ph		
34	Gnd_Bias_Ph		
35	Gnd_Bias_Ph		
36	Vdd11_P		
37	Gnd_Bias_Ph		
38	Gnd_Bias_Ph		

39	Nheater_PLW1		
40	Gnd_Bias_Ph		
41	Vdd4_P		
42	Gnd_Bias_Ph		
43	Gnd_Bias_Ph		
44	Vss6_P		
45	Gnd_Bias_Ph		
46	Gnd_Bias_Ph		
47	Pbias_P250		
48	Gnd_Bias_Ph		
49	Nheater_PSW2		
50	Gnd_Bias_Ph		
51	Gnd_Bias_Ph		
52	Vss10_P		
53	Gnd_Bias_Ph		
54	Gnd_Bias_Ph		
55	Gnd_Bias_Ph		
56	Gnd_Bias_Ph		
57	Nbias_P500		
58	Gnd_Bias_Ph		
59	Gnd_Bias_Ph		
60	Vss4_P		
61	Vdd5_P		
62	Vss5_P		
63	Vdd6_P		
64	Nbias_P250		
65	Pbias_P250		
66	Nbias_P250		
67	Nheater_PSW3		
68	Gnd_Bias_Ph		
69	Vdd9_P		
70	Vss9_P		
71	Vdd10_P		
72	Nbias_P350		
73	Pbias_P350		
74	Nheater_PMW2		
75	Pbias_P500		
76	Nbias_P500		
77	Pbias_P500		
78	Gnd_Bias_Ph		

Unit : DCU
 Sub-unit/Module : BIAS_S (Main)
 Connector Identifier : J31
 Connector Type : DCMA37S
 Connector Name : HSDCU_J31

Pin#	Signal Name	EMC Class	Signal Description
1	PBias_TC		
2	Gnd_Bias_Ph		
3	Vdd_TC		
4	Gnd_Bias_Ph		
5	NHeater_TC		
6	NBias_SLW		
7	Gnd_Bias_Sp		
8	Vss1_P		
9	Gnd_Bias_Sp		
10	NBias_SSW		
11	Gnd_Bias_Sp		
12	PBias_SSW		
13	Vss2_S		
14	Vdd3_S		
15	Gnd_Bias_Sp		
16	NHeater_SLW		
17	Gnd_Bias_Sp		
18	NHeater_SSW		
19	Gnd_Bias_Sp		
20	NBias_TC		
21	Vss_TC		
22	Gnd_Bias_Ph		
23	Gnd_Bias_Ph		
24	PBias_SLW		
25	Vdd1_S		
26	Gnd_Bias_Sp		
27	Gnd_Bias_Sp		
28	PBias_SSW		
29	NBias_SSW		
30	Gnd_Bias_Sp		
31	Vdd2_S		
32	Gnd_Bias_Sp		
33	Vss3_S		
34	Gnd_Bias_Sp		
35	Gnd_Bias_Sp		
36	Gnd_Bias_Sp		
37	Gnd_Bias_Sp		

Unit : DCU
 Sub-unit/Module : BIAS_P (Redundant)
 Connector Identifier : J30
 Connector Type : DDMA78S
 Connector Name : HSDCU_J30

Pin#	Signal Name	EMC Class	Signal Description
1	Vdd1_P		
2	Vss1_P		
3	Vdd2_P		
4	Vdd3_P		
5	Vss3_P		
6	PBias_P250		
7	Gnd_Bias_Ph		
8	Gnd_Bias_Ph		
9	Nheater_PSW1		
10	Vdd7_P		
11	Vss7_P		
12	Vdd8_P		
13	PBias_P350		
14	Nbias_P350		
15	Nheater_PMW1		
16	Gnd_Bias_Ph		
17	Vss11_P		
18	Vdd12_P		
19	Vss12_P		
20	Gnd_Bias_Ph		
21	Gnd_Bias_Ph		
22	Gnd_Bias_Ph		
23	Vss2_P		
24	Gnd_Bias_Ph		
25	Gnd_Bias_Ph		
26	Nbias_250		
27	Gnd_Bias_Ph		
28	Gnd_Bias_Ph		
29	Gnd_Bias_Ph		
30	Gnd_Bias_Ph		
31	Vss8_P		
32	Gnd_Bias_Ph		
33	Gnd_Bias_Ph		
34	Gnd_Bias_Ph		
35	Gnd_Bias_Ph		
36	Vdd11_P		
37	Gnd_Bias_Ph		
38	Gnd_Bias_Ph		
39	Nheater_PLW1		
40	Gnd_Bias_Ph		
41	Vdd4_P		
42	Gnd_Bias_Ph		

43	Gnd_Bias_Ph		
44	Vss6_P		
45	Gnd_Bias_Ph		
46	Gnd_Bias_Ph		
47	Pbias_P250		
48	Gnd_Bias_Ph		
49	Nheater_PSW2		
50	Gnd_Bias_Ph		
51	Gnd_Bias_Ph		
52	Vss10_P		
53	Gnd_Bias_Ph		
54	Gnd_Bias_Ph		
55	Gnd_Bias_Ph		
56	Gnd_Bias_Ph		
57	Nbias_P500		
58	Gnd_Bias_Ph		
59	Gnd_Bias_Ph		
60	Vss4_P		
61	Vdd5_P		
62	Vss5_P		
63	Vdd6_P		
64	Nbias_P250		
65	Pbias_P250		
66	Nbias_P250		
67	Nheater_PSW3		
68	Gnd_Bias_Ph		
69	Vdd9_P		
70	Vss9_P		
71	Vdd10_P		
72	Nbias_P350		
73	Pbias_P350		
74	Nheater_PMW2		
75	Pbias_P500		
76	Nbias_P500		
77	Pbias_P500		
78	Gnd_Bias_Ph		

Unit : DCU
 Sub-unit/Module : BIAS_S (Redundant)
 Connector Identifier : J32
 Connector Type : DCMA37S
 Connector Name : HSDCU_J32

Pin#	Signal Name	EMC Class	Signal Description
1	PBias_TC		
2	Gnd_Bias_Ph		
3	Vdd_TC		
4	Gnd_Bias_Ph		
5	NHeater_TC		
6	NBias_SLW		
7	Gnd_Bias_Sp		
8	Vss1_P		
9	Gnd_Bias_Sp		
10	NBias_SSW		
11	Gnd_Bias_Sp		
12	PBias_SSW		
13	Vss2_S		
14	Vdd3_S		
15	Gnd_Bias_Sp		
16	NHeater_SLW		
17	Gnd_Bias_Sp		
18	NHeater_SSW		
19	Gnd_Bias_Sp		
20	NBias_TC		
21	Vss_TC		
22	Gnd_Bias_Ph		
23	Gnd_Bias_Ph		
24	PBias_SLW		
25	Vdd1_S		
26	Gnd_Bias_Sp		
27	Gnd_Bias_Sp		
28	PBias_SSW		
29	NBias_SSW		
30	Gnd_Bias_Sp		
31	Vdd2_S		
32	Gnd_Bias_Sp		
33	Vss3_S		
34	Gnd_Bias_Sp		
35	Gnd_Bias_Sp		
36	Gnd_Bias_Sp		
37	Gnd_Bias_Sp		

6.4.3.2. FCU Interfaces

6.4.3.2.1. SMEC Module

Unit : FCU
 Sub-unit : MCU/SMEC (Main)
 Connector Identifier : J17
 Connector Type : DCMA37P
 Connector Name : HSFCU_J17

Pin #	Signal name	Signal function	Max. current
1	S_Mot_Coil_P	SMEC drive coil I+	100 mA
2	S_Mot_Coil_N	SMEC drive coil I-	100 mA
20	S_Mot_Coil_Shd	SMEC drive coil shld	N/A
4	S_Mot_Bemf_P	SMEC drive coil supply sense	10 μ A
5	S_Mot_Bemf_N	SMEC drive coil return sense	10 μ A
23	S_Mot_Bemf_Shd	SMEC drive coil supply sense shield	N/A
6		NC	
7	LEDA	SMEC position sensor Led power supply	1 mA
8	LEDC	SMEC position sensor Led power return	1 mA
26	LED_Shd	Shield	N/A
10	IPD1A	SMEC position sensor photodiode #1 I+	20 μ A
11	IPD1C	SMEC position sensor photodiode #1 I-	20 μ A
29	IPD1_SHD	Shield	N/A
13	IPD2A	SMEC position sensor photodiode #2 I+	20 μ A
14	IPD2C	SMEC position sensor photodiode #2 I-	20 μ A
32	IPD2_Shd	Shield	N/A
16	IPD3A	SMEC position sensor photodiode #3 I+	20 μ A
17	IPD3C	SMEC position sensor photodiode #3 I-	20 μ A
35	IPD3_Shd	Shield	N/A
21	S_Mot_Coil_P	SMEC drive coil I+ (rob)	100 mA
22	S_Mot_Coil_N	SMEC drive coil I- (rob)	100 mA
3	S_Mot_Coil_Shd	SMEC drive coil shld rob)	N/A
24		NC	
25		NC	
27	-3V	SMEC position sensor power supply	1 mA
28	-3V	SMEC position sensor power return	1 mA
9	POS_POWER_Shd	Shield	N/A
30	CRPD1A	SMEC pos. sensor photodiode #1 feedback +	10 μ A
31	CRPD1C	SMEC pos. sensor photodiode #1 feedback -	10 μ A
12	CRPD1_SHD	Shield	N/A
33	CRPD2A	SMEC pos. sensor photodiode #2 feedback +	10 μ A
34	CRPD2C	SMEC pos. sensor photodiode #2 feedback -	10 μ A
15	CRPD2_Shd	Shield	N/A
36	CRPD3A	SMEC pos. sensor photodiode #3 feedback +	10 μ A

Unit : FCU
Sub-unit : MCU/SMEC (Redundant)
Connector Identifier : J18
Connector Type : DCMA37P
Connector Name : HSFCU_J18

Pin #	Signal name	Signal function	Max. current
1	S_Mot_Coil_P	SMEC drive coil I+	100 mA
2	S_Mot_Coil_N	SMEC drive coil I-	100 mA
20	S_Mot_Coil_Shd	SMEC drive coil shld	N/A
4	S_Mot_Bemf_P	SMEC drive coil supply sense	10 μ A
5	S_Mot_Bemf_N	SMEC drive coil return sense	10 μ A
23	S_Mot_Bemf_Shd	SMEC drive coil supply sense shield	N/A
6		NC	
7	LEDA	SMEC position sensor Led power supply	1 mA
8	LEDC	SMEC position sensor Led power return	1 mA
26	LED_Shd	Shield	N/A
10	IPD1A	SMEC position sensor photodiode #1 I+	20 μ A
11	IPD1C	SMEC position sensor photodiode #1 I-	20 μ A
29	IPD1_SHD	Shield	N/A
13	IPD2A	SMEC position sensor photodiode #2 I+	20 μ A
14	IPD2C	SMEC position sensor photodiode #2 I-	20 μ A
32	IPD2_Shd	Shield	N/A
16	IPD3A	SMEC position sensor photodiode #3 I+	20 μ A
17	IPD3C	SMEC position sensor photodiode #3 I-	20 μ A
35	IPD3_Shd	Shield	N/A
21	S_Mot_Coil_P	SMEC drive coil I+ (rob)	100 mA
22	S_Mot_Coil_N	SMEC drive coil I- (rob)	100 mA
3	S_Mot_Coil_Shd	SMEC drive coil shld rob)	N/A
24		NC	
25		NC	
27	-3V	SMEC position sensor power supply	1 mA
28	-3V	SMEC position sensor power return	1 mA
9	POS_POWER_Shd	Shield	N/A
30	CRPD1A	SMEC pos. sensor photodiode #1 feedback +	10 μ A
31	CRPD1C	SMEC pos. sensor photodiode #1 feedback -	10 μ A
12	CRPD1_SHD	Shield	N/A
33	CRPD2A	SMEC pos. sensor photodiode #2 feedback +	10 μ A
34	CRPD2C	SMEC pos. sensor photodiode #2 feedback -	10 μ A
15	CRPD2_Shd	Shield	N/A
36	CRPD3A	SMEC pos. sensor photodiode #3 feedback +	10 μ A
37	CRPD3C	SMEC pos. sensor photodiode #3 feedback -	10 μ A
18	CRPD3_Shd	Shield	N/A

Unit : FCU
 Sub-unit : MCU/SMEC (Main)
 Connector Identifier : J29
 Connector Type : DCMA37P
 Connector Name : HSFCU_J29

Pin #	Signal name	Signal function	Max. current
1	S_LL#1_Coil_P	SMEC launch latch #1 power supply	400 mA / 50 ms
2	S_LL#1_Coil_N	SMEC launch latch #1 power return	400 mA / 50 ms
20	S_LL#1_Coil_Shd	Shield	N/A
3		Reserved	
4		Reserved	
5		Reserved	
7		Reserved	
8		Reserved	
9		Reserved	
10	S_LL#2_Stat_P	SMEC launch latch # 2 confirmation + (TBC)	1 mA
11	S_LL#2_Stat_N	SMEC launch latch # 2 confirmation - (TBC)	1 mA
29	S_LL#2_Stat_Shd	Shield	N/A
13	LVDT_PRIM_P	SMEC LVDT primary coil power supply (P)	5 mA
14	LVDT_PRIM_N	SMEC LVDT primary coil power supply (N)	5 mA
32	LVDT_PRIM_Shd	Shield	N/A
15	LVDT_SECA_P	SMEC LVDT secondary coil # 1 signal (P)	50 μ A
16	LVDT_SECA_N	SMEC LVDT secondary coil # 1 signal (N)	50 μ A
34	LVDT_SECA_Shd	Shield	N/A
17	LVDT_SECB_P	SMEC LVDT secondary coil # 2 signal (P)	50 μ A
18	LVDT_SECB_N	SMEC LVDT secondary coil # 2 signal (N)	50 μ A
36	LVDT_SECB_Shd	Shield	N/A
19			
21		Reserved	
22		Reserved	
23		Reserved	
24	S_LL#2_Coil_P	SMEC launch latch #2 power supply (TBC)	400 mA / 50 ms
25	S_LL#2_Coil_N	SMEC launch latch #2 power return (TBC)	400 mA / 50 ms
6	S_LL#2_Coil_Shd	Shield	N/A
26		Reserved	
27		Reserved	
28		Reserved	
30	S_LL#1_Stat_P	SMEC launch latch # 1 confirmation +	1 mA
31	S_LL#1_Stat_N	SMEC launch latch # 1 confirmation -	1 mA
12	S_LL#1_Stat_Shd	Shield	N/A
33			
35			
37			

Unit : FCU
Sub-unit : MCU/SMEC (Redundant)
Connector Identifier : J30
Connector Type : DCMA37P
Connector Name : HSFCU_J30

Pin #	Signal name	Signal function	Max. current
1	S_LL#1_Coil_P	SMEC lauch latch #1 power supply	400 mA / 50 ms
2	S_LL#1_Coil_N	SMEC lauch latch #1 power return	400 mA / 50 ms
20	S_LL#1_Coil_Shd	Shield	N/A
3		Reserved	
4		Reserved	
5		Reserved	
7		Reserved	
8		Reserved	
9		Reserved	
10	S_LL#2_Stat_P	SMEC lauch latch # 2 confirmation + (TBC)	1 mA
11	S_LL#2_Stat_N	SMEC lauch latch # 2 confirmation - (TBC)	1 mA
29	S_LL#2_Stat_Shd	Shield	N/A
13	LVDT PRIM_P	SMEC LVDT primary coil power supply (P)	5 mA
14	LVDT PRIM_N	SMEC LVDT primary coil power supply (N)	5 mA
32	LVDT PRIM_Shd	Shield	N/A
15	LVDT SECA_P	SMEC LVDT secondary coil # 1 signal (P)	50 μ A
16	LVDT SECA_N	SMEC LVDT secondary coil # 1 signal (N)	50 μ A
34	LVDT SECA_Shd	Shield	N/A
17	LVDT SECB_P	SMEC LVDT secondary coil # 2 signal (P)	50 μ A
18	LVDT SECB_N	SMEC LVDT secondary coil # 2 signal (N)	50 μ A
36	LVDT SECB_Shd	Shield	N/A
19			
21		Reserved	
22		Reserved	
23		Reserved	
24	S_LL#2_Coil_P	SMEC lauch latch #2 power supply (TBC)	400 mA / 50 ms
25	S_LL#2_Coil_N	SMEC lauch latch #2 power return (TBC)	400 mA / 50 ms
6	S_LL#2_Coil_Shd	Shield	N/A
26		Reserved	
27		Reserved	
28		Reserved	
30	S_LL#1_Stat_P	SMEC lauch latch # 1 confirmation +	1 mA
31	S_LL#1_Stat_N	SMEC lauch latch # 1 confirmation -	1 mA
12	S_LL#1_Stat_Shd	Shield	N/A
33			
35			
37			

6.4.3.2.2. BSM Module

Unit : FCU
 Sub-unit : MCU/BSM (Main)
 Connector Identifier : J19
 Connector Type : DCMA37S
 Connector Name : HSFCU_J19

Pin #	Name	Signal function	Electrical signal
1	Ch Sens Sup	Chop sensor supply	I = 1 mA
20	Ch Sens Rtn	Chop sensor return	I = 1 mA
22	Ch Sens Shd1	Chop sensor supply screen	U = 0 V
2	Ch Sens Sup Meas	Chop sensor supply sense	U = 0.4 V
3	Ch Sens Rtn Meas	Chop sensor return sense	U = 0 V
21	Ch Sens O/P	Chop sensor o/p	U = 0,4V
4	Jig Sens Sup	Jiggle sensor supply	I = 1 mA
23	Jig Sens Ret	Jiggle sensor return	U = 0 V
5	Jig Sens Sup Meas	Jiggle sensor supply sense	U = 0.4 V
6	Jig Sens Rtn Meas	Jiggle sensor return sense	U = 0 V
24	Jig Sens O/P	Jiggle sensor o/p	U = 0,4V
12	B LL Sens Sup	Launch latch sensor	U = 5 V
30	B LL Sens Rtn	Launch latch sensor return	U = 0 V
31	LL Sens Shd	Launch latch sensor screen	U = 0 V
13	B LL Sup	Launch latch coil supply	I = 400 mA
14	B LL Rtn	Launch latch coil return	I = 400 mA
33	LL Shd	Launch latch coil screen	I = 0 mA
15	Ch Mot Sup	Chop motor supply	I = 40 mA
34	Ch Mot Rtn	Chop motor return	I = 40 mA
17	Ch Mot Shd	Chop motor screen	U = 0 V
16	Ch Bemf Meas P	Chop motor supply sense	U = 15 V
35	Ch Bemf Meas N	Chop motor return sense	U = 0 V
36	Jig Mot Sup	Jiggle motor supply	I = 40 mA
18	Jig Mot Rtn	Jiggle motor return	I = 40 mA
37	Jig Bemf Meas P	Jiggle motor supply sense	U = 15 V
19	Jig Bemf Meas N	Jiggle motor return sense	U = 0 V
7		Reserved	
8		Reserved	
9		not connected	
10		Reserved	
11		Reserved	
25		Reserved	
26		Reserved	
27		Reserved	
28		Reserved	
29		Reserved	
32		not connected	

Unit : FCU
 Sub-unit : MCU/BSM (Redundant)
 Connector Identifier : J20
 Connector Type : DCMA37S
 Connector Name : HSFCU_J20

Pin #	Name	Signal function	Electrical signal
1	Ch Sens Sup	Chop sensor supply	I = 1 mA
20	Ch Sens Rtn	Chop sensor return	I = 1 mA
22	Ch Sens Shd1	Chop sensor supply screen	U = 0 V
2	Ch Sens Sup Meas	Chop sensor supply sense	U = 0.4 V
3	Ch Sens Rtn Meas	Chop sensor return sense	U = 0 V
21	Ch Sens O/P	Chop sensor o/p	U = 0,4V
4	Jig Sens Sup	Jiggle sensor supply	I = 1 mA
23	Jig Sens Ret	Jiggle sensor return	U = 0 V
5	Jig Sens Sup Meas	Jiggle sensor supply sense	U = 0.4 V
6	Jig Sens Rtn Meas	Jiggle sensor return sense	U = 0 V
24	Jig Sens O/P	Jiggle sensor o/p	U = 0,4V
12	B LL Sens Sup	Launch latch sensor	U = 5 V
30	B LL Sens Rtn	Launch latch sensor return	U = 0 V
31	LL Sens Shd	Launch latch sensor screen	U = 0 V
13	B LL Sup	Launch latch coil supply	I = 400 mA
14	B LL Rtn	Launch latch coil return	I = 400 mA
33	LL Shd	Launch latch coil screen	I = 0 mA
15	Ch Mot Sup	Chop motor supply	I = 40 mA
34	Ch Mot Rtn	Chop motor return	I = 40 mA
17	Ch Mot Shd	Chop motor screen	U = 0 V
16	Ch Bemf Meas P	Chop motor supply sense	U = 15 V
35	Ch Bemf Meas N	Chop motor return sense	U = 0 V
36	Jig Mot Sup	Jiggle motor supply	I = 40 mA
18	Jig Mot Rtn	Jiggle motor return	I = 40 mA
37	Jig Bemf Meas P	Jiggle motor supply sense	U = 15 V
19	Jig Bemf Meas N	Jiggle motor return sense	U = 0 V
7		Reserved	
8		Reserved	
9		not connected	
10		Reserved	
11		Reserved	
25		Reserved	
26		Reserved	
27		Reserved	
28		Reserved	
29		Reserved	
32		not connected	

6.4.3.3. SCU Interfaces

6.4.3.3.1. TEMP Module

Unit : FCU
 Sub-unit/Module : SCU/TEMP (Main)
 Connector Identifier : J21
 Connector Type : DAMA15S
 Connector Name : HSFCU_J21

Pin#	Signal Name	EMC Class	Signal Description
1			BSM temperature drive+
9			BSM temperature sense+
10			BSM temperature sense-
2			BSM temperature drive-
3			BSM temperature shield
4			SMEC temperature drive+
11			SMEC temperature sense+
12			SMEC temperature sense-
5			SMEC temperature drive-
13			SMEC temperature shield
6			SMEC/SOB I/F temperature drive+
14			SMEC/SOB I/F temperature sense+
15			SMEC/SOB I/F temperature sense-
7			SMEC/SOB I/F temperature drive-
8			SMEC/SOB I/F temperature shield

Unit : FCU
 Sub-unit/Module : SCU/TEMP (Main)
 Connector Identifier : J23
 Connector Type : DDMA50S
 Connector Name : HSFCU_J23

Pin#	Signal Name	EMC Class	Signal Description
1			Evaporator temperature drive+
2			Evaporator temperature drive-
18			Evaporator temperature sense+
35			Evaporator temperature sense-
34			Evaporator temperature shield
3			Sorption Pump temperature drive+
19			Sorption Pump temperature drive-
20			Sorption Pump temperature sense+
36			Sorption Pump temperature sense-
4			Sorption Pump HS temperature drive+
5			Sorption Pump HS temperature drive-
21			Sorption Pump HS temperature sense+
37			Sorption Pump HS temperature sense-
38			Cooler temperature probe shields
6			Evaporator HS temperature drive+
22			Evaporator HS temperature drive-
23			Evaporator HS temperature sense+
39			Evaporator HS temperature sense-
7			Thermal Shunt temperature drive+
8			Thermal Shunt temperature drive-
24			Thermal Shunt temperature sense+
40			Thermal Shunt temperature sense-
41			FPU Faraday Shield Link
9			SOB temperature drive+
25			SOB temperature drive-
26			SOB temperature sense+
42			SOB temperature sense-
43			SOB & Spect. Det. Box probe shields
10			Spect. Det. Box temperature drive+
11			Spect. Det. Box temperature drive-
27			Spect. Det. Box temperature sense+
44			Spect. Det. Box temperature sense-
12			Phot. Det. Box temperature drive+
28			Phot. Det. Box temperature drive-
29			Phot. Det. Box temperature sense+
45			Phot. Det. Box temperature sense-
46			Phot. Det. Box & Opt. S/bench shields
13			Optical Sub-bench temperature drive+
14			Optical Sub-bench temperature drive-
30			Optical Sub-bench temperature sense+
47			Optical Sub-bench temperature sense-
15			FPU Input Baffle temperature drive+

31			FPU Input Baffle temperature drive
32			FPU Input Baffle temperature sense+
48			FPU Input Baffle temperature sense-
49			FPU i/p baffle & BSM/SOB I/F shields
16			BSM/SOB I/F temperature drive+
17			BSM/SOB I/F temperature drive-
33			BSM/SOB I/F temperature sense+
50			BSM/SOB I/F temperature sense-

Unit : FCU
 Sub-unit/Module : SCU/TEMP (Main)
 Connector Identifier : J25
 Connector Type : DAMA15S
 Connector Name : HSFCU_J25

Pin#	Signal Name	EMC Class	Signal Description
1			Spect. Stim. Flange temperature drive+
9			Spect. Stim. Flange temperature drive-
2			Spect. Stim. Flange temperature sense+
10			Spect. Stim. Flange temperature sense-
3			Spect. Stim. Flange shield
4			HS Spect. Stim. 4% temperature drive+
11			HS Spect. Stim. 4% temperature drive-
5			HS Spect. Stim. 4% temperature sense+
12			HS Spect. Stim. 4% temperature sense-
13			HS Spect. Stim. 4% shield
6			HS Spect. Stim. 2% temperature drive+
14			HS Spect. Stim. 2% temperature drive-
7			HS Spect. Stim. 2% temperature sense+
15			HS Spect. Stim. 2% temperature sense-
13			HS Spect. Stim. 2% shield

Unit : FCU
 Sub-unit/Module : SCU/TEMP (Redundant)
 Connector Identifier : J22
 Connector Type : DAMA15S
 Connector Name : HSFCU_J22

Pin#	Signal Name	EMC Class	Signal Description
1			BSM temperature drive+
9			BSM temperature sense+
10			BSM temperature sense-
2			BSM temperature drive-
3			BSM temperature shield
4			SMEC temperature drive+
11			SMEC temperature sense+
12			SMEC temperature sense-
5			SMEC temperature drive-
13			SMEC temperature shield
6			SMEC/SOB I/F temperature drive+
14			SMEC/SOB I/F temperature sense+
15			SMEC/SOB I/F temperature sense-
7			SMEC/SOB I/F temperature drive-
8			SMEC/SOB I/F temperature shield

Unit : FCU
 Sub-unit/Module : SCU/TEMP (Redundant)
 Connector Identifier : J24
 Connector Type : DDMA50S
 Connector Name : HSFCU_J24

Pin#	Signal Name	EMC Class	Signal Description
1			Evaporator temperature drive+
2			Evaporator temperature drive-
18			Evaporator temperature sense+
35			Evaporator temperature sense-
34			Evaporator temperature shield
3			Sorption Pump temperature drive+
19			Sorption Pump temperature drive-
20			Sorption Pump temperature sense+
36			Sorption Pump temperature sense-
4			Sorption Pump HS temperature drive+
5			Sorption Pump HS temperature drive-
21			Sorption Pump HS temperature sense+
37			Sorption Pump HS temperature sense-
38			Cooler temperature probe shields
6			Evaporator HS temperature drive+
22			Evaporator HS temperature drive-
23			Evaporator HS temperature sense+
39			Evaporator HS temperature sense-
7			Thermal Shunt temperature drive+
8			Thermal Shunt temperature drive-
24			Thermal Shunt temperature sense+
40			Thermal Shunt temperature sense-
41			FPU Faraday Shield Link
9			SOB temperature drive+
25			SOB temperature drive-
26			SOB temperature sense+
42			SOB temperature sense-
43			SOB & Spect. Det. Box probe shields
10			Spect. Det. Box temperature drive+
11			Spect. Det. Box temperature drive-
27			Spect. Det. Box temperature sense+
44			Spect. Det. Box temperature sense-
12			Phot. Det. Box temperature drive+
28			Phot. Det. Box temperature drive-
29			Phot. Det. Box temperature sense+
45			Phot. Det. Box temperature sense-
46			Phot. Det. Box & Opt. S/bench shields
13			Optical Sub-bench temperature drive+
14			Optical Sub-bench temperature drive-
30			Optical Sub-bench temperature sense+
47			Optical Sub-bench temperature sense-
15			FPU Input Baffle temperature drive+

31			FPU Input Baffle temperature drive
32			FPU Input Baffle temperature sense+
48			FPU Input Baffle temperature sense-
49			FPU i/p baffle & BSM/SOB I/F shields
16			BSM/SOB I/F temperature drive+
17			BSM/SOB I/F temperature drive-
33			BSM/SOB I/F temperature sense+
50			BSM/SOB I/F temperature sense-

Unit : FCU
 Sub-unit/Module : SCU/TEMP (Redundant)
 Connector Identifier : J26
 Connector Type : DAMA15S
 Connector Name : HSFCU_J26

Pin#	Signal Name	EMC Class	Signal Description
1			Spect. Stim. Flange temperature drive+
9			Spect. Stim. Flange temperature drive-
2			Spect. Stim. Flange temperature sense+
10			Spect. Stim. Flange temperature sense-
3			Spect. Stim. Flange shield
4			HS Spect. Stim. 4% temperature drive+
11			HS Spect. Stim. 4% temperature drive-
5			HS Spect. Stim. 4% temperature sense+
12			HS Spect. Stim. 4% temperature sense-
13			HS Spect. Stim. 4% shield
6			HS Spect. Stim. 2% temperature drive+
14			HS Spect. Stim. 2% temperature drive-
7			HS Spect. Stim. 2% temperature sense+
15			HS Spect. Stim. 2% temperature sense-
13			HS Spect. Stim. 2% shield

6.4.3.3.2. CCHK_IF Module

Unit : FCU
 Sub-unit/Module : SCU/CCHK (Main)
 Connector Identifier : J11
 Connector Type : DBMA25S
 Connector Name : HSFCU_J11

Pin #	Signal Name	EMC Class	Signal Description
1			Sorption Pump heater I+_A
2			Sorption Pump heater I+_B
14			Sorption Pump heater I-_A
15			Sorption Pump heater I-_B
3			Sorption Pump Heat Switch heater I+_A
4			Sorption Pump Heat Switch heater I+_B
16			Sorption Pump Heat Switch heater I-_A
17			Sorption Pump Heat Switch heater I-_B
5			Evaporator Heat Switch heater I+_A
6			Evaporator Heat Switch heater I+_B
18			Evaporator Heat Switch heater I-_A
19			Evaporator Heat Switch heater I-_B
7			HS Spect. 4% heater I+_A
8			HS Spect. 4% heater I+_B
20			HS Spect. 4% heater I-_A
21			HS Spect. 4% heater I-_B
9			HS Spect. 2% heater I+_A
10			HS Spect. 2% heater I+_B
22			HS Spect. 2% heater I-_A
23			HS Spect. 2% heater I-_B
11			300-mK Thermal Control Heater I+_A
12			300-mK Thermal Control Heater I+_B
24			300-mK Thermal Control Heater I-_A
25			300-mK Thermal Control Heater I-_B
13			300-mK Thermal Control Heater shield.

Unit : FCU
 Sub-unit/Module : SCU/CCHK (Main)
 Connector Identifier : J13
 Connector Type : DEMA9S
 Connector Name : HSFCU_J13

Pin#	Signal Name	EMC Class	Signal Description
1			
2			Photometer Point Stim. heater I+_A
3			Photometer Point Stim. heater I+_B
4			Screen
5			
6			
7			Photometer Point Stim. heater I-_A
8			Photometer Point Stim. heater I-_B
9			

Unit : FCU
 Sub-unit/Module : SCU/CCHK (Redundant)
 Connector Identifier : J12
 Connector Type : DBMA25S
 Connector Name : HSFCU_J12

Pin #	Signal Name	EMC Class	Signal Description
1			Sorption Pump heater I+_A
2			Sorption Pump heater I+_B
14			Sorption Pump heater I-_A
15			Sorption Pump heater I-_B
3			Sorption Pump Heat Switch heater I+_A
4			Sorption Pump Heat Switch heater I+_B
16			Sorption Pump Heat Switch heater I-_A
17			Sorption Pump Heat Switch heater I-_B
5			Evaporator Heat Switch heater I+_A
6			Evaporator Heat Switch heater I+_B
18			Evaporator Heat Switch heater I-_A
19			Evaporator Heat Switch heater I-_B
7			HS Spect. 4% heater I+_A
8			HS Spect. 4% heater I+_B
20			HS Spect. 4% heater I-_A
21			HS Spect. 4% heater I-_B
9			HS Spect. 2% heater I+_A
10			HS Spect. 2% heater I+_B
22			HS Spect. 2% heater I-_A
23			HS Spect. 2% heater I-_B
11			300-mK Thermal Control Heater I+_A
12			300-mK Thermal Control Heater I+_B
24			300-mK Thermal Control Heater I-_A
25			300-mK Thermal Control Heater I-_B
13			300-mK Thermal Control Heater shld.

Unit : FCU
Sub-unit/Module : SCU/CCHK (Redundant)
Connector Identifier : J14
Connector Type : DEMA9S
Connector Name : HSFCU_J14

Pin#	Signal Name	EMC Class	Signal Description
1			
2			Photometer Point Stim. heater I+_A
3			Photometer Point Stim.heater I+_B
4			Screen
5			
6			
7			Photometer Point Stim.heater I- _A
8			Photometer Point Stim.heater I- _B
9			

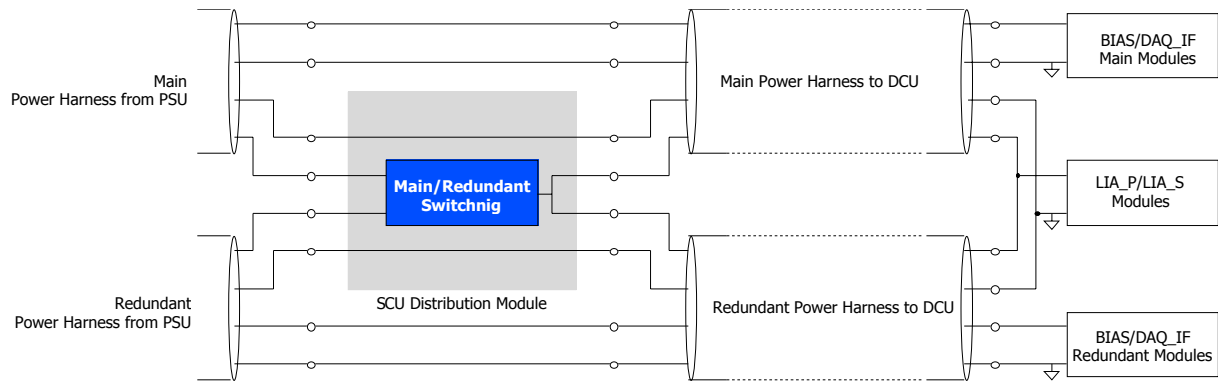
7. Grounding Scheme

8. Appendix – DRCU Sub-system interconnections

8.1. PSU to DCU interface

This interface concerns exclusively secondary power lines distribution to the DCU electronics. This interface corresponds to the external routing of power lines from the distribution board to the DCU box. No other interface is identified between these to sub-systems.

8.1.1. Interface Description



8.1.2. Interface definition

Pin #	Signal Name	EMC Class	Signal Description
1	LIA_P_P9V	1	
2	LIA_P_GND9V	1	
3	LIA_P_N9V	1	
4	LIA_S_P9V	1	
5	LIA_S_GND9V	1	
6	LIA_S_N9V	1	
7	PDAQ_P9V	1	
8	PDAQ_GND9V	1	
9	PDAQ_N9V	1	
10	PDAQ_P5V	1	
11	LIA_S_P5V	1	
12	LIA_P_P5V	1	
13	Chassis	1	
14	LIA_P_P9V	1	
15	LIA_P_GND9V	1	
16	LIA_P_N9V	1	
17	LIA_S_P9V	1	
18	LIA_S_GND9V	1	
19	LIA_S_N9V	1	

20	PDAQ_P9V	1	
21	PDAQ_GND9V	1	
22	PDAQ_N9V	1	
23	PDAQ_GND9V	1	
24	LIA_P_GND5V	1	
25	LIA_S_GND5V	1	

8.2. PSU to MCU interface

This interface concerns exclusively secondary power lines distribution to the MCU electronics. This interface corresponds to the internal routing of power lines from the distribution board to the MCU back plane. No other interface is identified between these to sub-systems.

Unit : MCU (Main)
 Sub-unit/Module :
 Connector Identifier : J31
 Connector Type : DBMA25P
 Connector Name : HSFCU_J31

Pin #	Function	Symbol	Remarks
1	+5 V prime	+5VdigP	
2	+5 V prime	+5VdigP	
3	+5 V prime	+5VdigP	
4			
5	+ 13.5 V prime	+13VanalogP	
6	+ 13.5 V prime	+13VanalogP	
7	- 13.5 V prime	-13VanalogP	
8	- 13.5 V prime	-13VanalogP	
9			
10	+ 15 V prime	+15VmotP	
11	+ 15 V prime	+15VmotP	
12	- 15 V prime	-15VmotP	
13	- 15 V prime	-15VmotP	
14	0 V digital prime	0VdigP	connected to 0VanalogP inside the MAC board
15	0 V digital prime	0VdigP	connected to 0VanalogP inside the MAC board
16	0 V digital prime	0VdigP	connected to 0VanalogP inside the MAC board
17			
18	0 V analog prime	0VanalogP	connected to 0VdigP inside the MAC board
19	0 V analog prime	0VanalogP	connected to 0VdigP inside the MAC board
20	0 V analog prime	0VanalogP	connected to 0VdigP inside the MAC board
21	0 V analog prime	0VanalogP	connected to 0VdigP inside the MAC board
22			
23	0 V motor prime	0VmotP	must be connected to 0VanalogP in the PSU
24	0 V motor prime	0VmotP	must be connected to 0VanalogP in the PSU
25	0 V motor prime	0VmotP	must be connected to 0VanalogP in the PSU

Unit : MCU (redundant)
 Sub-unit/Module :
 Connector Identifier : J32
 Connector Type : DBMA25P
 Connector Name : HSFCU_J32

Pin #	Function	Symbol	Remarks
1	+5 V prime	+5VdigP	
2	+5 V prime	+5VdigP	
3	+5 V prime	+5VdigP	
4			
5	+ 13.5 V prime	+13VanalogP	
6	+ 13.5 V prime	+13VanalogP	
7	- 13.5 V prime	-13VanalogP	
8	- 13.5 V prime	-13VanalogP	
9			
10	+ 15 V prime	+15VmotP	
11	+ 15 V prime	+15VmotP	
12	- 15 V prime	-15VmotP	
13	- 15 V prime	-15VmotP	
14	0 V digital prime	0VdigP	connected to 0VanalogP inside the MAC board
15	0 V digital prime	0VdigP	connected to 0VanalogP inside the MAC board
16	0 V digital prime	0VdigP	connected to 0VanalogP inside the MAC board
17			
18	0 V analog prime	0VanalogP	connected to 0VdigP inside the MAC board
19	0 V analog prime	0VanalogP	connected to 0VdigP inside the MAC board
20	0 V analog prime	0VanalogP	connected to 0VdigP inside the MAC board
21	0 V analog prime	0VanalogP	connected to 0VdigP inside the MAC board
22			
23	0 V motor prime	0VmotP	must be connected to 0VanalogP in the PSU
24	0 V motor prime	0VmotP	must be connected to 0VanalogP in the PSU
25	0 V motor prime	0VmotP	must be connected to 0VanalogP in the PSU

8.3. PSU to SCU interface

This interface concerns exclusively secondary power lines distribution to the FCU electronics for distribution to all the relevant S/S. No other interface is identified between these to sub-systems.

Unit : SCU (main)
 Sub-unit/Module :
 Connector Identifier : J36
 Connector Type : DAMA15P
 Connector Name : HSFCU_J36

Pin #	Signal Name	EMC Class	Signal Description
1	SCU_P5	1	
2	SCU_P9	1	
3	SCU_N9	1	
4			
5	MCU_OnOff_Cmd	2	
6			
7	PSU_ThSens+	3	
8	PSU_ThSens-	3	
9	SCU_P5 RTN	1	
10	SCU_9 RTN	1	
11			
12	LIAP_OnOff_Cmd	2	
13	LIAS_OnOff_Cmd	2	
14			
15	PSU_ThSens_Shield	3	

Unit : SCU (redundant)
 Sub-unit/Module :
 Connector Identifier : J34
 Connector Type : DAMA15P
 Connector Name : HSFCU_J34

Pin #	Signal Name	EMC Class	Signal Description
1	SCU_P5	1	
2	SCU_P9	1	
3	SCU_N9	1	
4			
5	MCU_OnOff_Cmd	2	
6			
7	PSU_ThSens+	3	
8	PSU_ThSens-	3	

9	SCU_P5_RTN	1	
10	SCU_9_RTN	1	
11			
12	LIAP_OnOff_Cmd	2	
13	LIAS_OnOff_Cmd	2	
14			
15	PSU_ThSens_Shield	3	